Data General Corporation

Technical Manual

Nova 1220

DATA GENERAL TECHNICAL MANUAL

NOVA 1220 COMPUTER

MODELS

8151, 8152, 8153, 8154 8155, 8156, 8157, 8158

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SECTION O

INTRODUCTION

THE NOVA 1220 COMPUTER

The Nova 1220 computer shown in Figure O-1 consists of a power supply-backpanel assembly and a console assembly mounted on a chassis into which plug up to ten 15" by 15" PC boards. The chassis includes a frame, two fans, a filter, a power transformer and a power switch assembly; the power supply-backpanel includes the power supply and ten sets of edge connectors mounted on an

etched PC board. The console includes a frame, front panel and PC board which holds the switches, lights and associated logic. Each basic Nova 1220 includes a Central Processor module, and any one of four types of memory modules; 1K, 2K, 4K or 8K. A table top assembly is also available but not shown.

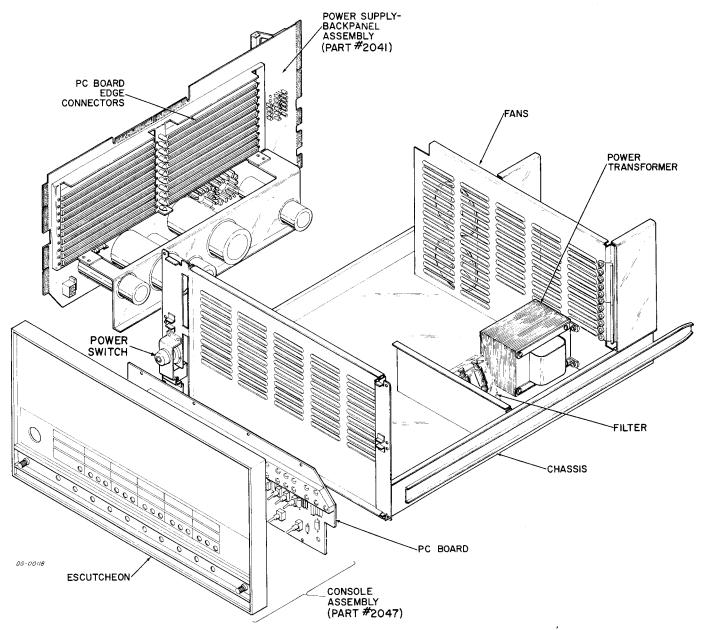


Figure O-1 Exploded View of The Nova 1220 Computer With Central Processor and Memory Cards Removed

The Central Processor, Console, Memories and Controllers communicate with each other along 16 bit buses called MEM, MBO and IN-OUT as shown in Figure O-2. MEM transfers information from Memory or the Console to the MBO or Instruction registers; MBO transfers information from the MBO register to the Console and Memories, and IN-OUT transfers information between the Memory's MB register and peripheral controllers. In the Nova 1220 proper all these data paths and their associated control signals travel along etched tracks on the backpanel to the board's edge connectors and to a plug in the console's PC board.

THIS MANUAL

This manual explains how the basic Nova 1220 works, how it is installed and how it is maintained. It is divided into 8 sections:

Section O introduces the machine and this manual;

Section C explains how the Central Processor works;

Section K explains how the operator's Console works;

Section P explains how the Power Supply works;

Section M explains how the Memories work;

Section I explains how to install the computer;

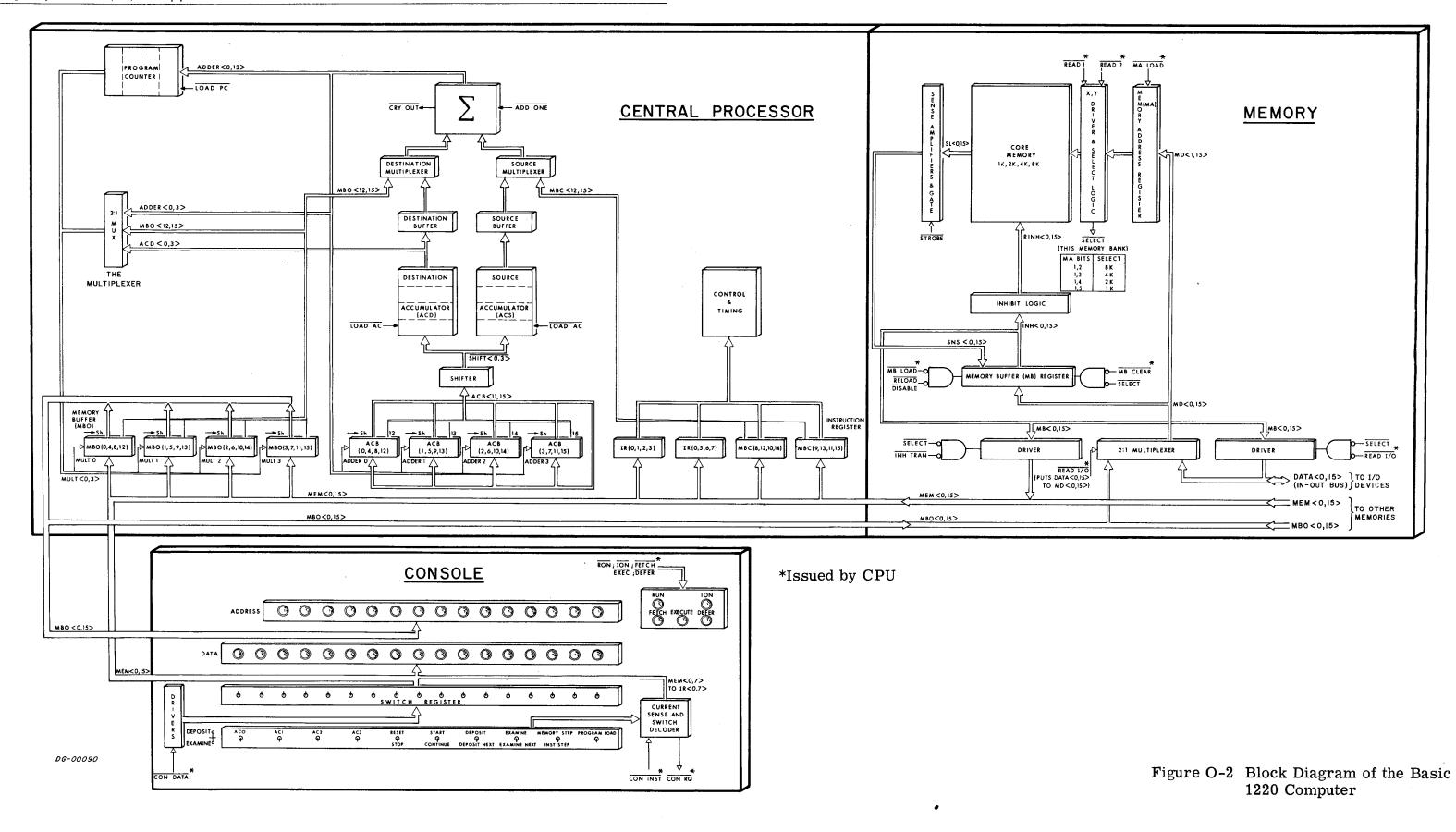
Section N explains how to maintain the computer;

Section T has two reference tables - a signal list and a list of expanded abbreviations. The signal list traces the source and destination of each signal in the Central Processor and the Memory. Source signals are listed alphanumerically by name. Each source signal originates at the output pin (PIN) of an integrated circuit (CHIP) which is called out on a drawing (DWG) at a grid reference (GRID). Each signal is wired to one or more ICs which themselves originate more signals, or (FUNCTIONS), whose names and locations are listed in the DESTINATION column beside their originating signal. Drawing numbers are identified by the last two numbers of the print followed by a hyphen followed by their sheet number(s).

RELATED DOCUMENTS

Figure O-3 lists the engineering prints and manuals which describe the basic computer. The manual "How To Use The Nova Computers" explains how to program the machine. The manual "The I.C. User's Guide" gives logic diagrams and truth tables for the I.C.s used in Data General's machines.

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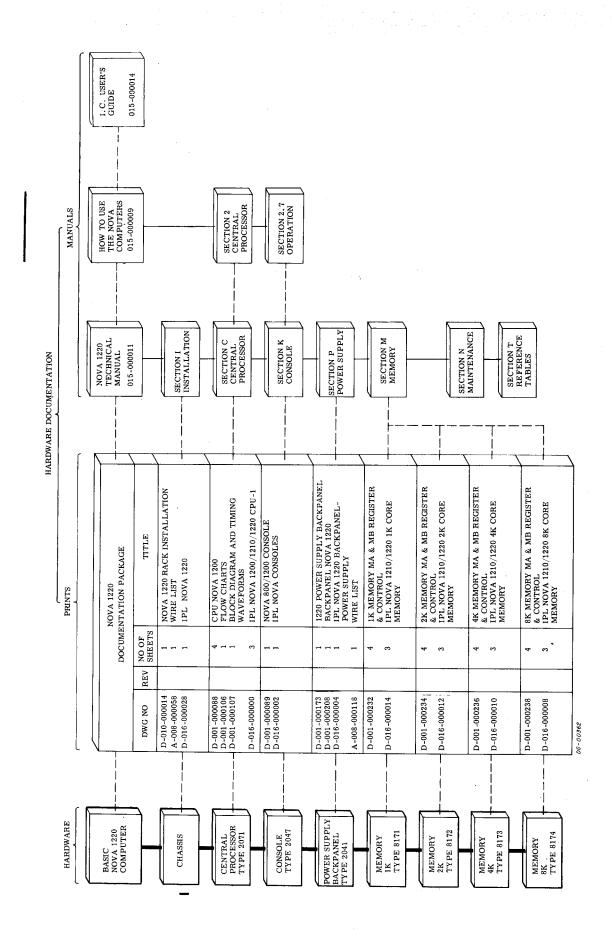


Figure O-3 Nova 1220 Hardware Documentation

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SECTION C

THE CENTRAL PROCESSOR UNIT

INTRODUCTION

The central processor unit (CPU) used in this computer is a binary, 2's complement, fixed word length, parallel/serial, digital, automatic processor. It takes up to 32K words of $1.2\mu \sec$ co-ordinate-addressed core memory of 16 bits per word. It has 7 sixteen bit hardware registers: four accumulators (ACO, AC1, AC2 and AC3); a program-transparent shift buffer (ACB); a program-transparent memory buffer (MBO); and one 15 bit program counter (PC). All internal data paths are four bits (or one "nibble") wide, so each internal transfer takes four steps; all three external data paths or buses, (MEM, MBO and IN-OUT) are 16 bits wide so each external transfer takes one step.

There are three classes of instructions; memory reference (EFA), input-output (I/O) and arithmetic and logic (ALC). There are three modes of addressing; absolute, index (to AC2 or AC3) and relative (to PC).

Peripheral devices can interrupt the processor and transfer data to or from its accumulators via the I/O instruction set, or simply use the processor's high speed data channel directly to memory.

The CPU is contained on a single 15" by 15" PC board which is inserted into the first slot of the computer's chassis. Power is supplied by the chassis' power supply.

THE CONTROL UNIT

The CPU is a synchronous processor for which time is broken up by two clocks into discrete, fixed periods. The two clocks are derived from a 13.333Mhz crystal oscillator which is divided by two. One clock, called MEM CLK is always running; the other, called CPU CLK is gated by three signals RUN, STUTTER and WHOA. RUN is a control flip-flop which stops the processor when it resets; STUTTER inhibits the clock for one cycle and WHOA is used by certain options like the multiply divide to slow the machine down. With these clocks the Control generates eight major states and two levels of minor states called timing state (TS) cycles and timing generator (TG) cycles.

Major States

Major states define what type of memory function is under way. The designated major state of the machine is set at the beginning of each memory cycle and remains set throughout that memory cycle. There are eight major states; Fetch, Defer, Execute, PI,DCH,Key, Keym, and a "dummy" state during which none of the other states are set.

- Fetch occurs when the next word to be read from memory is to be treated as an instruction.
- 2. Defer occurs when the next word from memory is to be treated as the address of an operandor instruction, i.e., during indirect addressing.
- 3. Execute occurs when the next word from memory is to be treated as an operand. Programmed I/O operations also set Execute, but the memory is not allowed to run.
- 4. PI occurs during a program interrupt when:
 - the contents of the PC are stored in location 0
 - the next major state is set to Defer
 - A JMP instruction is forced into the Instruction Register
 - the next address executed is in location 1, which should be set to the starting address of the service routine.
- 5. DCH occurs when the next memory cycle is to be a direct transfer between an I/O device and Memory.
- 6. Key occurs when a manual function is being requested from the Console. During Key, either all or part of the manual function is performed. The memory is not allowed to run during the Key cycle.
- 7. Keym occurs when the manual function requires a memory cycle, such as Examine or Program Load.
- 8. "Dummy" State occurs only when a machine stop is pending and the current instruction requires the skip conditions to be interrogated. During this state the machine increments the PC if the skip is successful in order that the address lights reflect the true next address.

TS Cycles

The TS cycles are four clock pulses long, and may be thought of as the time required to transfer a 16 bit word between two CPU registers at the rate of four bits per clock cycle. Each Major State consists of at least two complementary TS levels, called TS0 and TS3. TS0 occurs during the first half of the Major State, and TS3 occurs during the second half. Certain operations require more time than that provided by the two TS cycles, so a flip-flop called Loop is set to force the TS0 cycle to repeat and give the Major State three TS time intervals. During TS0 of this operation the data is fetched from the memory and loaded into the MBO; then Loop is set, TSO is repeated, and the data in the MBO is shifted through the Adder. Finally, TS3 is set and the data is transferred from the MBO to the Memory and re-written.

Timing Generator Cycles

MEM

CLOCK

OVERALL

OVERALL

DG-00045

FETCH/KEY =0 =1

FETCH/KEY | =0 | =1

There are three timing generators, called the processor timing generator (PTG); the accumulator timing generator (ACTG) and the memory timing generator (MTG). These timing generators effectively designate the clock pulses for specific functions in the processor, accumulator and memory respectively.

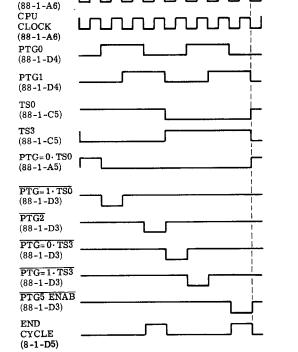
| NEXT MAJOR STATE

900 1050 1200

The Processor Timing Generator. This two bit counter, designated, PTG0 and PTG1, cycles every four clock pulses. PTGO is set during the two middle clock cycles of a TS cycle, and PTG1 is set during the last two cycles of a TS cycle. These two levels are decoded into two others called PTG2 and PTG5. PTG2 is the last clock interval during TSO, and PTG5 is the last clock interval during TS3. PTG5 is used, for example, to enable the major state flip-flops. PTGO "anded" with TS0 to form PTG0 TS0, the first clock interval during TSO, is used to increment the Adder as the least significant four bit nibble is passed through it. Figures C-1 and C-2 show the timing for the PTG during FETCH or KEY major states, and all other states.

The Accumulator Timing Generator. This two bit counter, designated ACTG0 and ACTG1, is always one clock state ahead of the PTG counter. Its two signals are used to drive the accumulator chips. Their timing is given in Figure C-3.

The Memory Timing Generator. This four bit counter, designated MTG0, MTG2, MTG3, is used to form the control signals for memory. Its timing is given in Figure C-4.



TS0

TS0

PTG2

PTG2

PTG PTG

PTG PTG

TS3

TS3

PTG5

PTG5

PTG

Figure C-1 Timing
For The Processor Timing
Generator During All
Major States Except
Fetch or Key

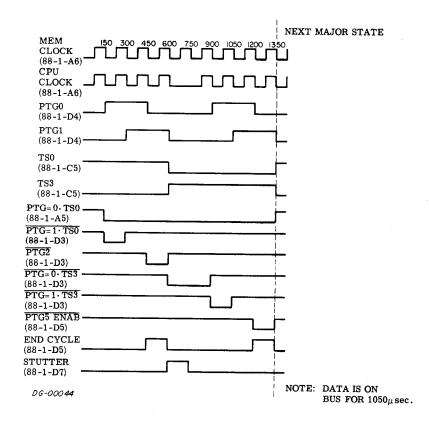


Figure C-2 Timing For The Processor Timing Generator During Fetch or Key

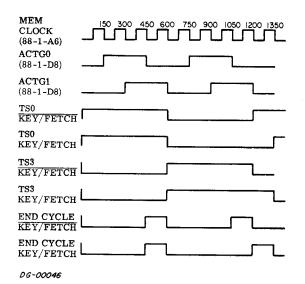


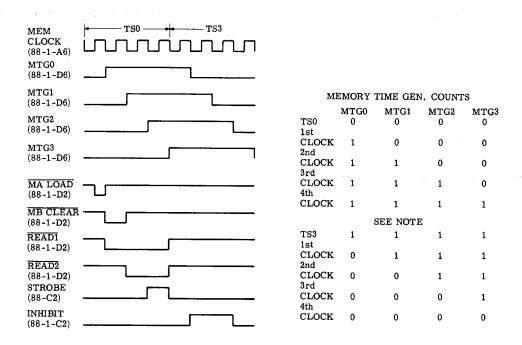
Figure C-3 Timing

Timing Generator

For The Accumulator

ACCUMULATOR TRUTH TABLE (88-4-B6 & B7 U124 & U123)

ACTG0	ACTG1		
0	0	BITS	12-15
1	0	BITS	8-11
1	1	BITS	4-7
0	1	BITS	0 - 3



NOTE - IF LOOPING TS0, CLOCK FREEZES WITH ALL ONES UNTIL FIRST CLOCK IN TS3.

06-00047

Figure C-4 Timing For The Memory Timing Generator

CPU DATA PATHS

Registers

The CPU is organized around eight hardware registers as shown in Figure C-5; a shift buffer (ACB); a program counter (PC); a CPU interface register (MBO); an instruction register (IR and MBC); and four accumulators, (AC0, AC1, AC2, AC3). These eight registers are all 16 bits long except for the PC which is 15 bits. All internal data paths are four bits wide, so it takes four separate operations to perform an add, or a register-to-register transfer.

Program Counter (PC). The 15 bit address of the next instruction to be fetched is held in the PC. During the fetch of an instruction, the PC is incremented by one so that it points to the next sequential instruction. Certain instructions, such as JMP can change the contents of the PC. The PC consists of one 16 bit latch.

Instruction Register (IR and MBC). The Instruction Register stores the instruction currently being executed. The CPU decodes the data held in the Instruction Register in order to perform the instruction. The register is organized into two parts, the IR and MBC. The IR consists of the eight high order bits, and the MBC of the eight low order bits. During an effective address calculation, the MBC contains the displacement and shifts through the source multiplexer into the Adder and the IR bits remain static.

CPU Interface Register (MBO). The MBO is used in every operation the CPU performs. It acts as a parallel-to-serial converter for 16 bit data flowing into the machine from the MEM bus. This data is loaded from the MEM bus into the MBO in parallel. and shifted out four bits at a time into some other part of the machine. Conversely, data is shifted into the MBO from the Adder four bits at a time to be loaded into a Memory from the MBO bus. During effective address calculations, the MBO holds the present address used in relative addressing. During memory modify operations (such as ISZ) data is loaded into the MBO Memory. The MBO then modifies the data by recirculating it through the Adder and back into the MBO. The modified data is then loaded from the MBO back into Memory.

Shift Buffer (ACB). All data to be loaded into the Accumulators are passed through the ACB, where the results of an ALC instruction are assembled before they are loaded back into the Destination Accumulator.

Accumulators (AC0, AC1, AC2, AC3.) There are two identical sets of four - 16bit accumulators all of which can be logically and arithmetically manipulated under program control. Each set of accumulators is contained in a single 64 bit chip: (only one accumulator - nibble per chip can be addressed at any one time). Since it is necessary to be able to access two accumulators simultaneously, two sets are available, called source (S) and destination (D), each set containing the same information as the other. For example, two accumulators can be added together by simultaneously fetching the source data from one chip and the destination data from the other and then adding the two. The accumulators are buffered by four bit registers (source and destination) so that the next nibble can be selected while the current nibble is being processed. It takes 100 ns to access a nibble in the accumulator, and 100 ns to move a nibble through the Adder and Multiplexer, so by overlapping the two, the total time to process a nibble is 100 ns.

During the first nibble, the Adder is idle and a flag called STUTTER inhibits the clock until data is ready.

Data Flow

Nibble Transfers. When transferring data from one register to another, the lower order bits are always transferred first. The first clock interval would transfer bits 12-15, the second 8-11, the third 4-7, and the fourth 0-3. If an operation is to be performed upon a word, two things must be specified; the bit position inside the nibble, and the nibble to be acted upon. For example, to increment a word during FETCH. TSO time when the MBO is incremented, a carry is inserted into the low order bit of the Adder during the first clock interval, PTG=0.TS0, so a "one" is added to that first nibble. If a carry resulted from that first addition, it is stored in a flip-flop for the next clock interval where it is inserted into the Adder as a carry into the low order bit. This continues until all four nibbles have passed through the Adder. During JSR it is necessary to force bit 0 to be zero as it is stored into AC3. A gate in the high order position of the nibble forces the output of the multiplexer/shifter gate high (to load zero) during JSR and the fourth clock interval during the time state in which the PC is being loaded into AC3.

Instruction Overlapping. Certain instructions are carried out at the same time as parts of other instructions. For example, any operation which loads an accumulator is overlapped with the next major state. Such is the case with the ALC instruction when the CPU first operates upon the accumulator(s), loads the result into the ACB register while memory is re-writing the instruction, and then waits until the next state to transfer the result from the ACB back into the accumulator. The next state could be FETCH, PI, DCH or even KEY. Another operation that is overlapped with the next Major State is the interrogation of skip conditions for ALC and ISZ/DSZ instructions. The results of these instructions are loaded into the ACB, which shifts through the multiplexer/shifter during TS0 of the next major state, after which the data may or may not be loaded into the accumulators. The output of the multiplexer/shifter is checked for all zeroes to see if it fulfills the skip conditions. If it does, the SKIP flip-flop is set at the end of TSO. If the next major state was FETCH, the execution of that instruction is inhibited, effectively skipping it, even though it was fetched from memory and loaded into the instruction register. If the next major state is PI, the PC that is loaded into address zero is incremented to reflect the skip before it is stored. If the next state is DCH and the SKIP flip-flop is left in the set state, appropriate action will be taken on the next FETCH or PI cycle. If the machine is about to be stopped from the Console by STOP, ISTP, or MSTP, a "Dummy State" is entered in which the skip conditions are interrogated, and the PC incremented as required to permit the ADDRESS lights on the Console to show the correct next address when the machine is stopped.

Data Buses

Data is transferred between memory and the central processor or an I/O device along three data buses called:

$\overline{ ext{MEM}}$	which transfers data from memory to	
	the Central Processor;	

MBO which transfers data from the Central Processor to Memory;

DATA which transfers data in either direction between memory and I/O devices.

During an output I/O instruction, data moves from the source AC into the MBO and on to the MBO bus. From the bus it is strobed into the memory MB register and on through the IN-OUT bus to the destination device. During an output I/O instruction the destination device outputs to the IN-OUT bus into the memory's MB register, which dumps into the MEM bus. The MEM bus is strobed into the MBO which moves it through the Adder to the ACB and into the destination AC.

THE FLOW AND TIMING DIAGRAMS

The following diagrams illustrate each step in the sequence of functions carried out by the central processor and memory. Each block of a flow diagram describes an operation, its data path and the location of critical logic. For example, this block means that the ACB register was transferred to an AC register via the

shifter (ACB) which is located on print 001-000088, sheet 4, in grid A7. The symbol Σ means Adder, M means Multiplexer, and S means Shifter. Supporting notes near the blocks give the current time state, relevant figures and the status of important signals.

REFERENCES

1.	Nova 1200 CPU	Print D-001-000088-13
2.	Flow Charts	Print D-001-000106-00
3.	Waveforms	Print D-001-000107-00

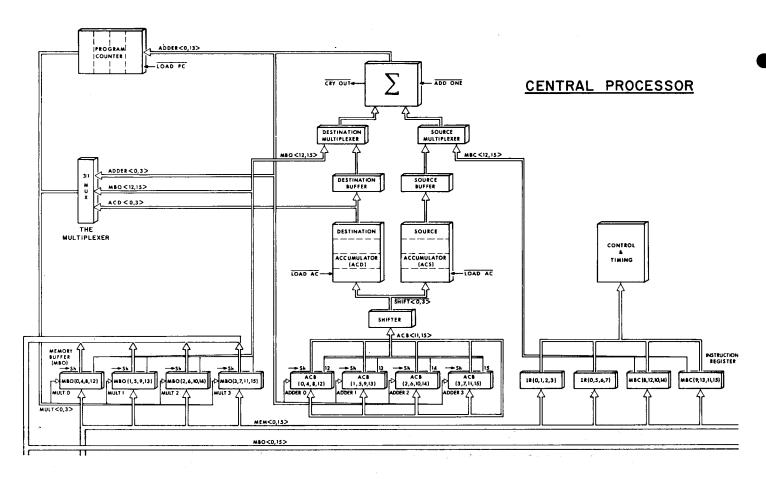
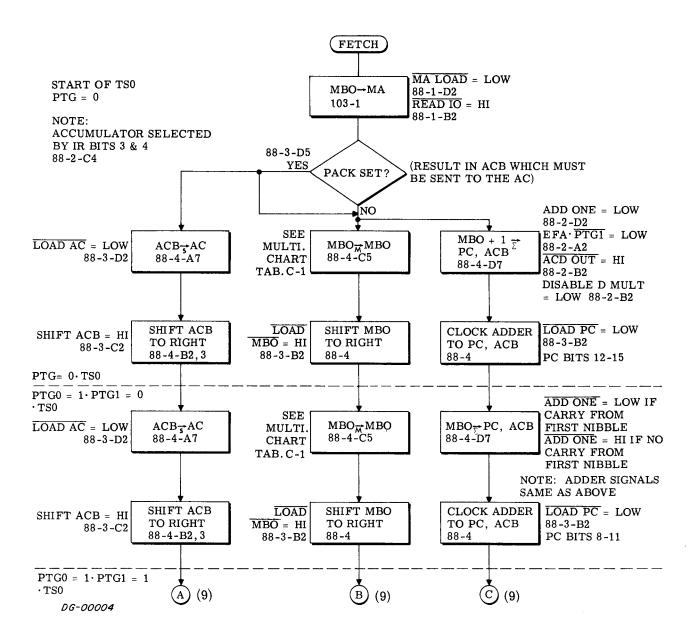
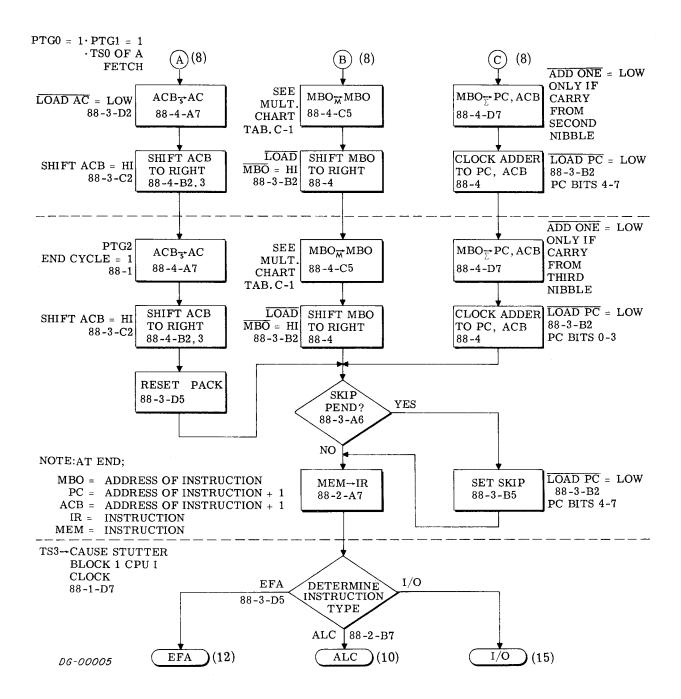
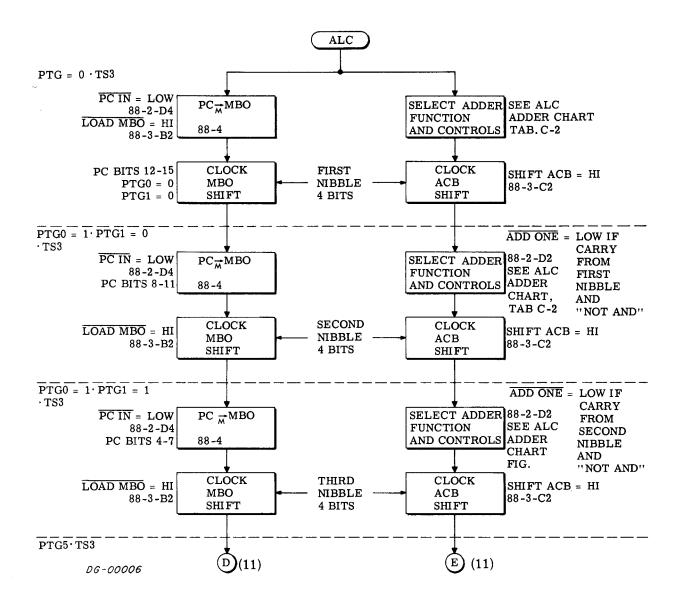
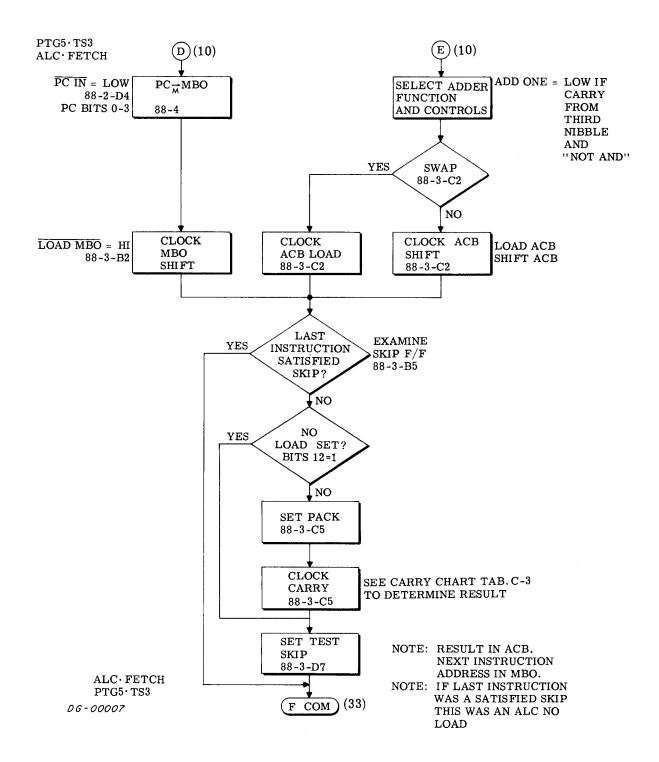


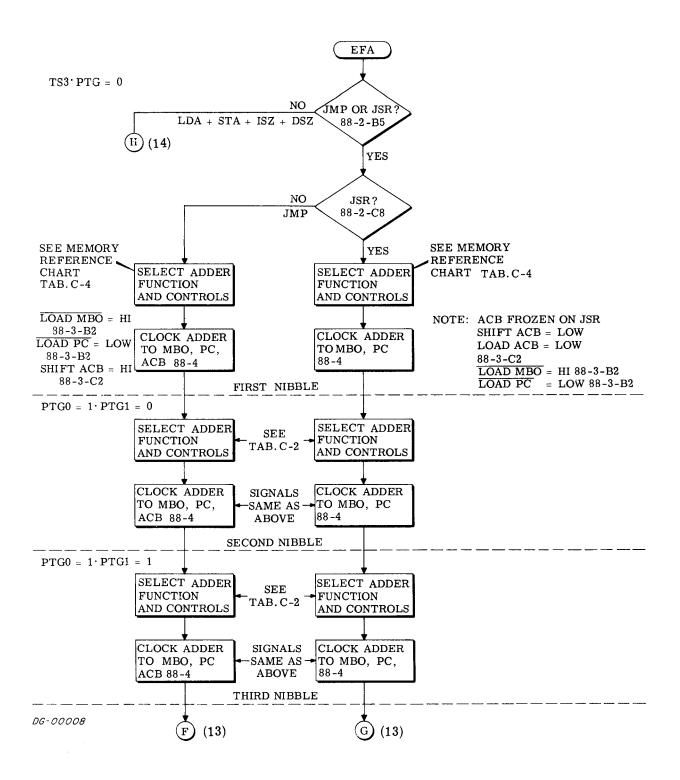
Figure C-5 The Nova 1220 Central Processor

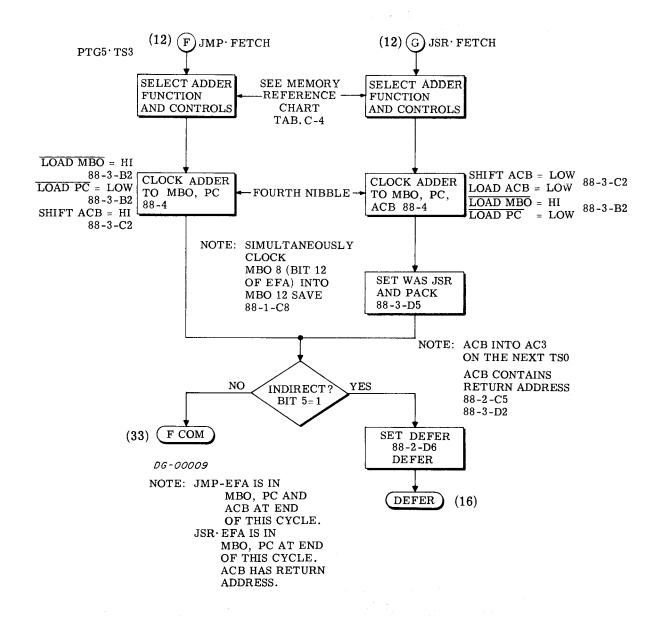


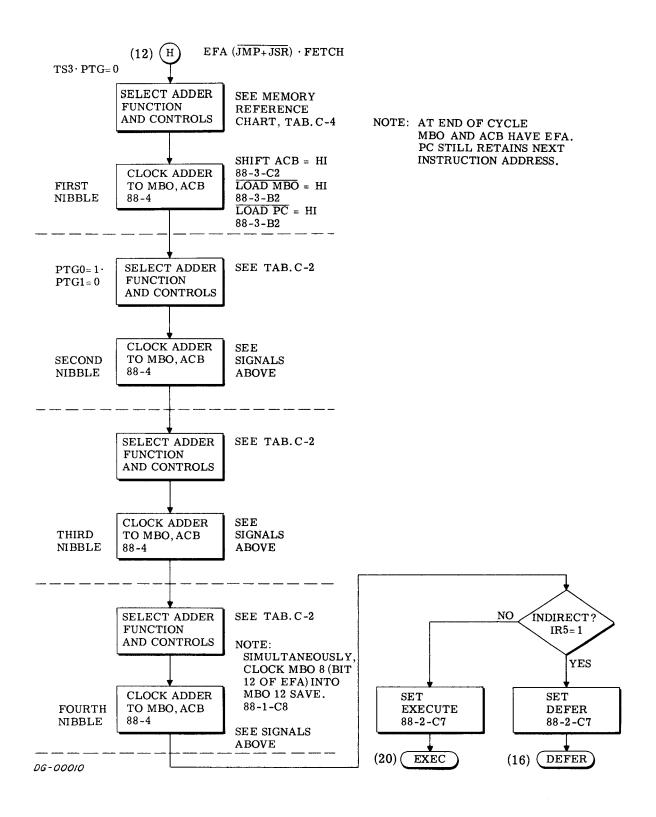


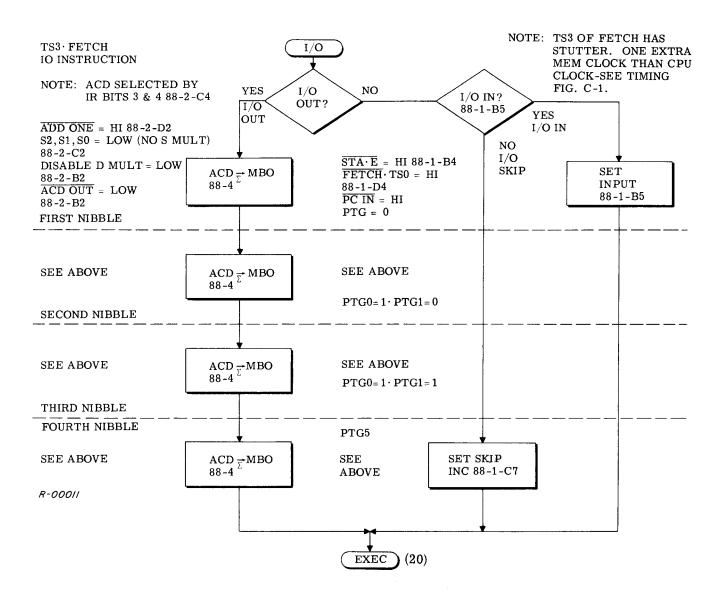


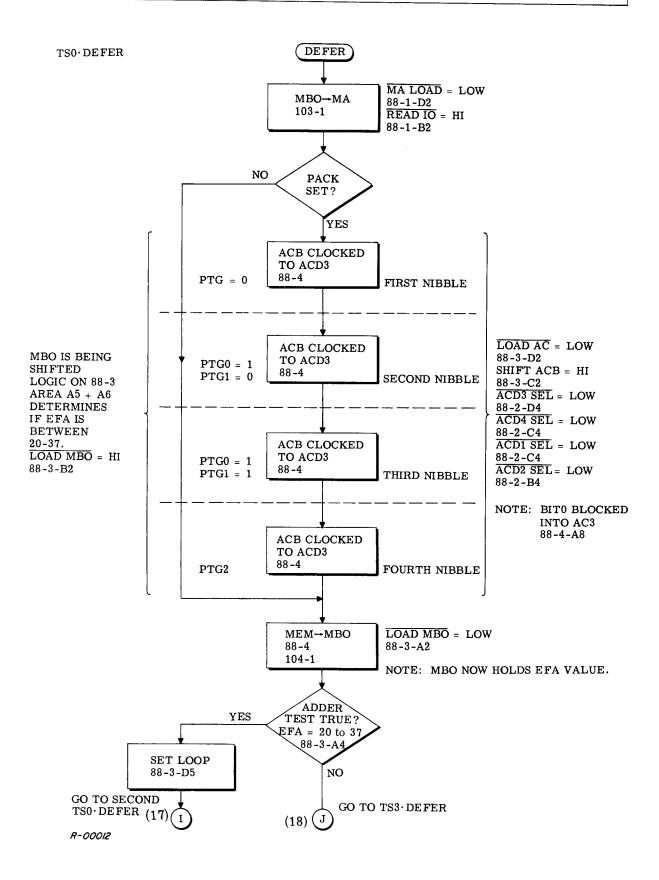


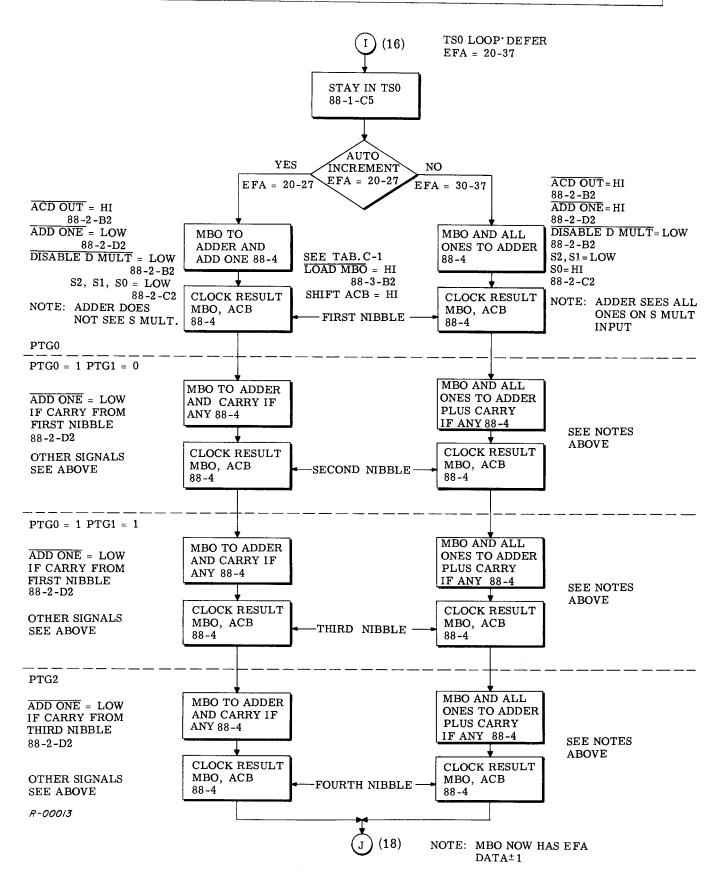


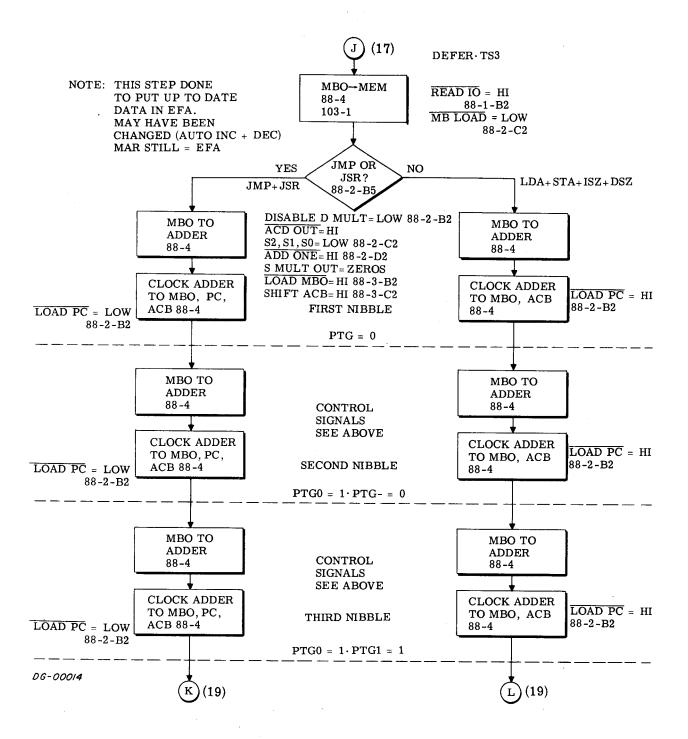


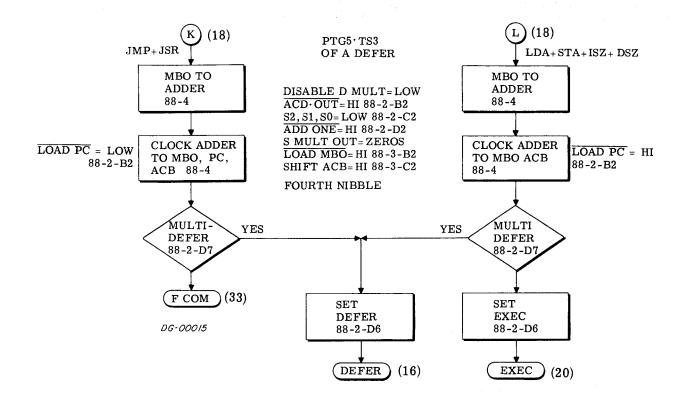


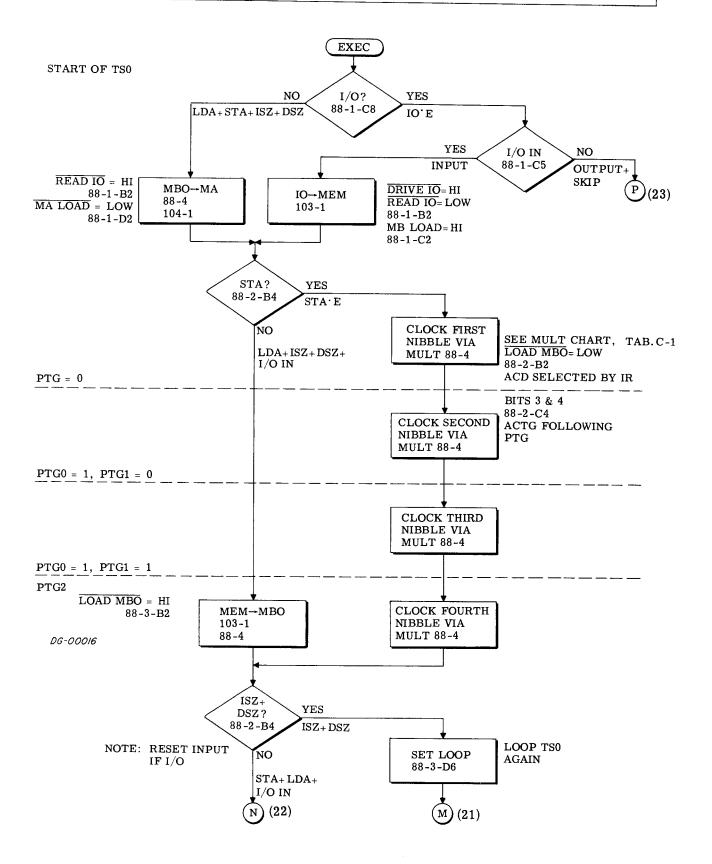


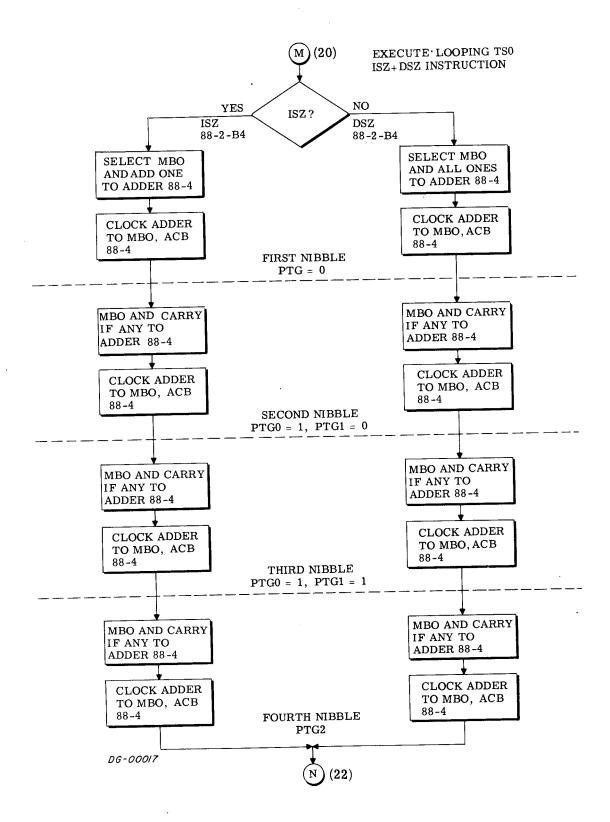


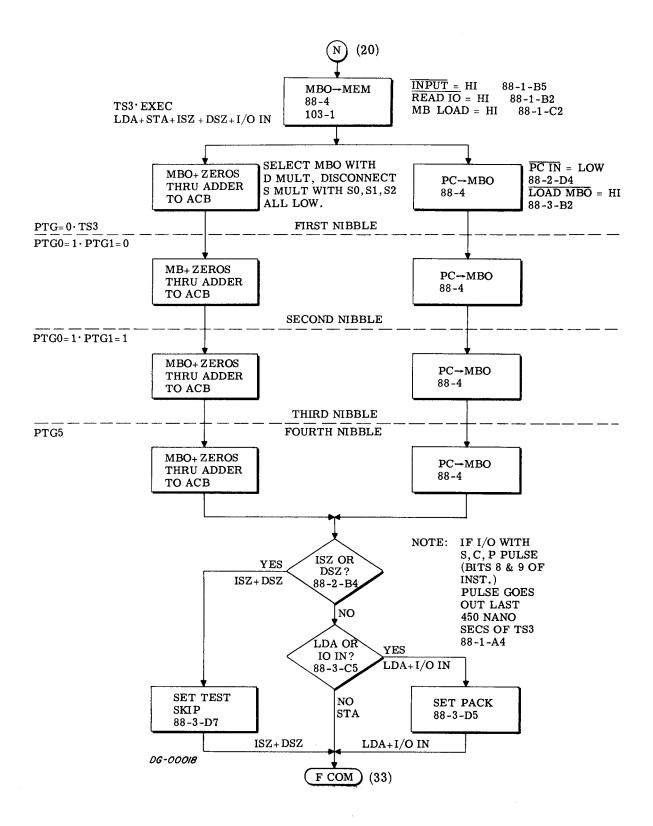


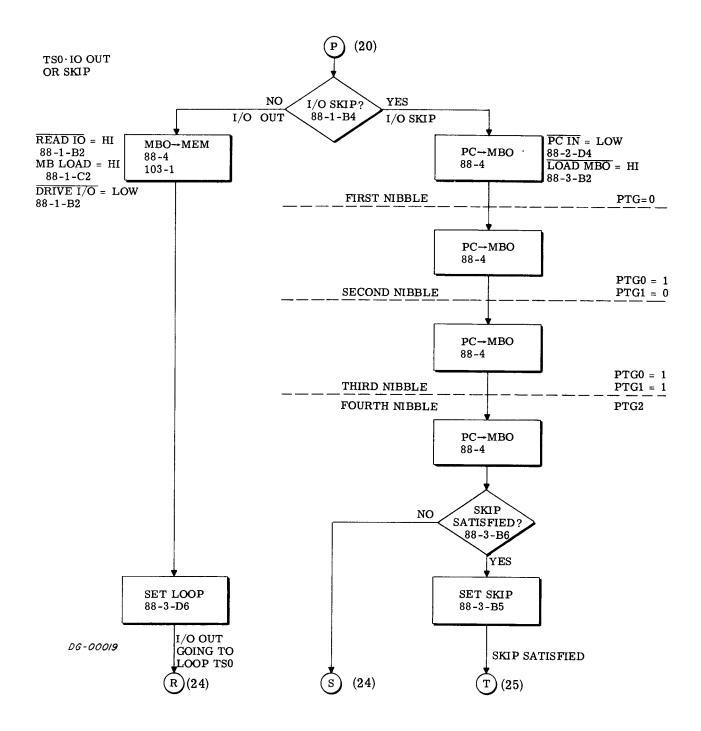


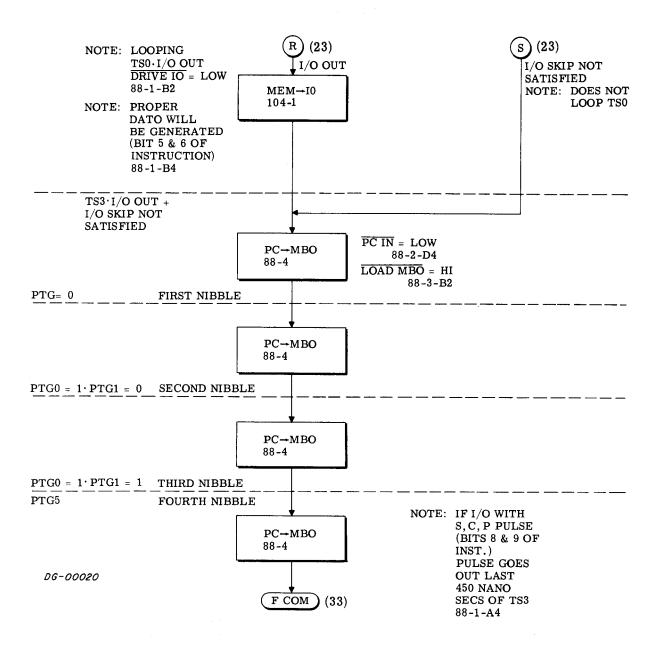


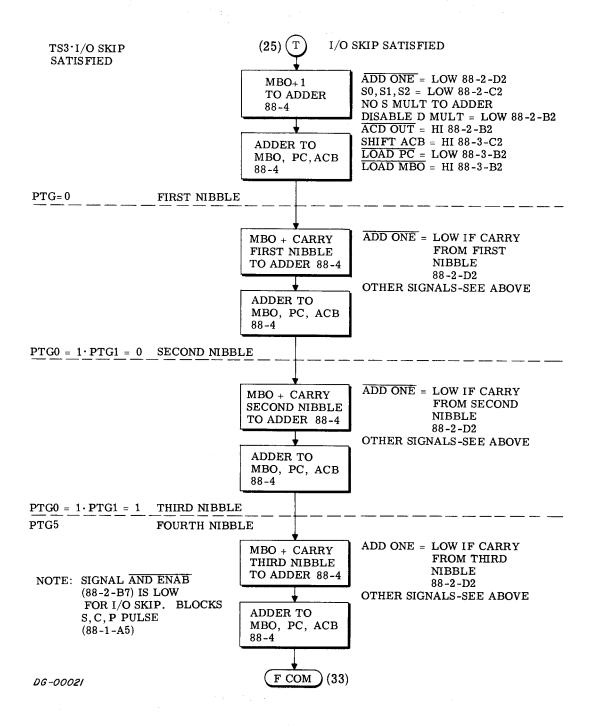


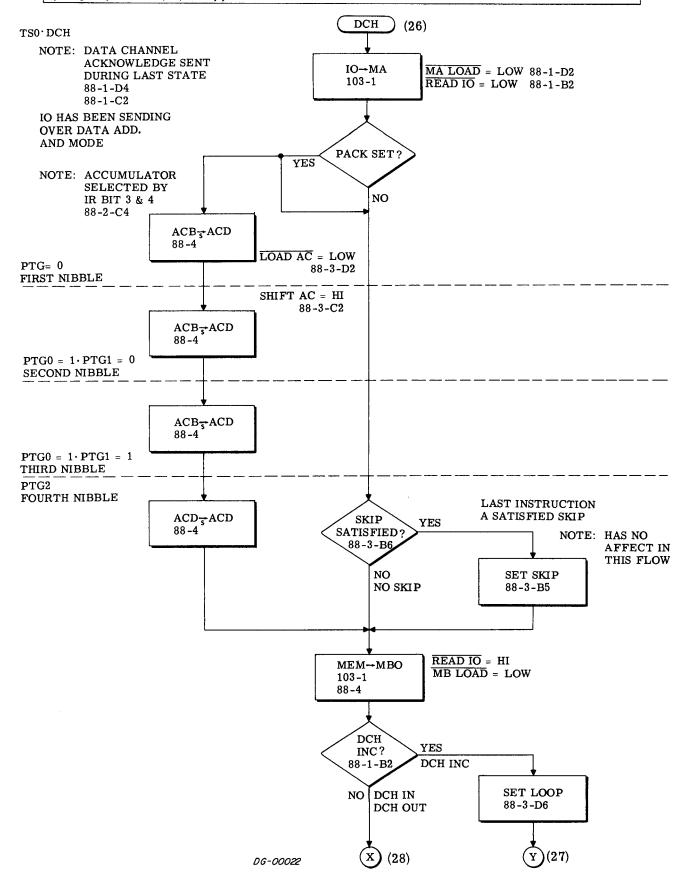


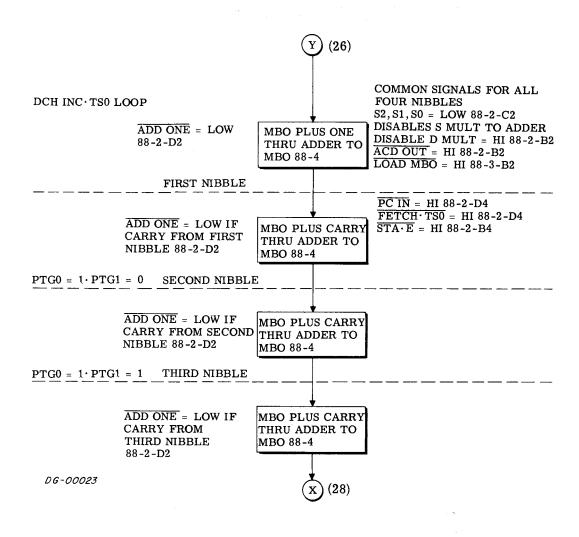


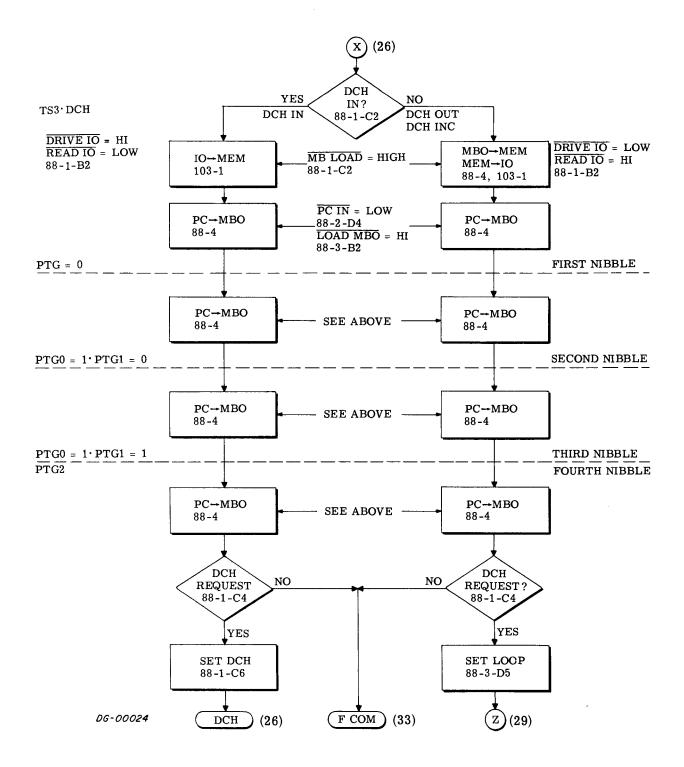


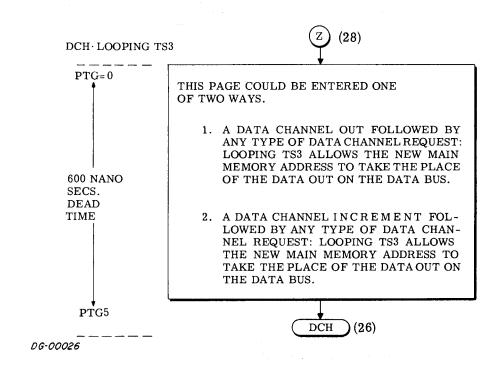




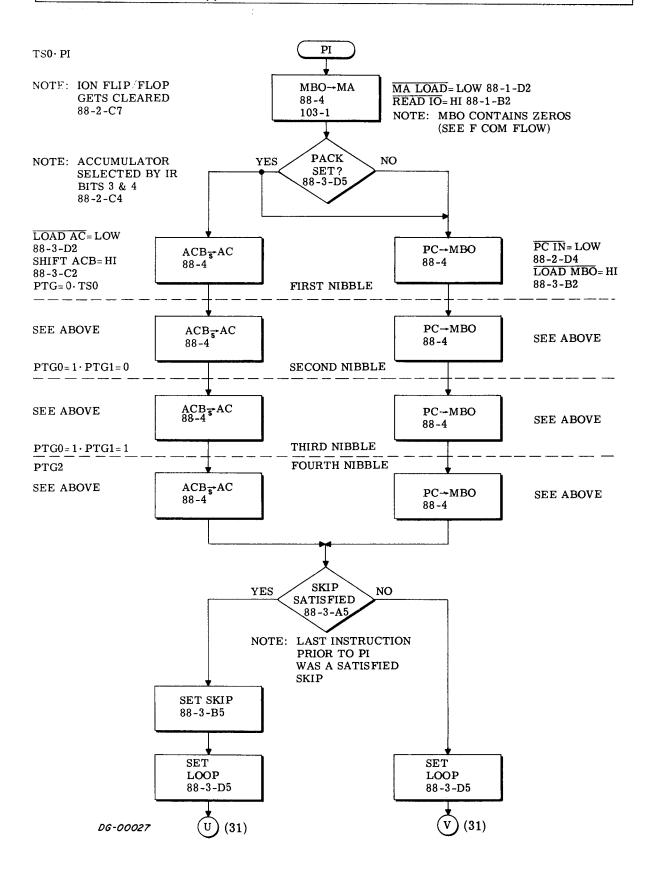


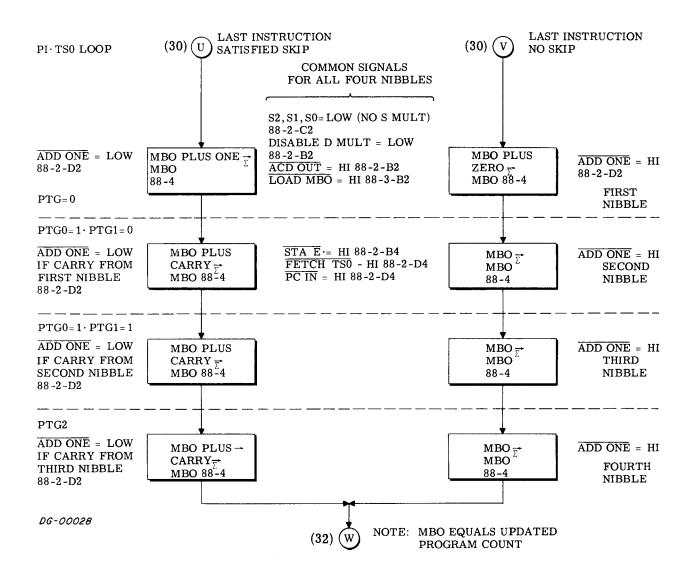


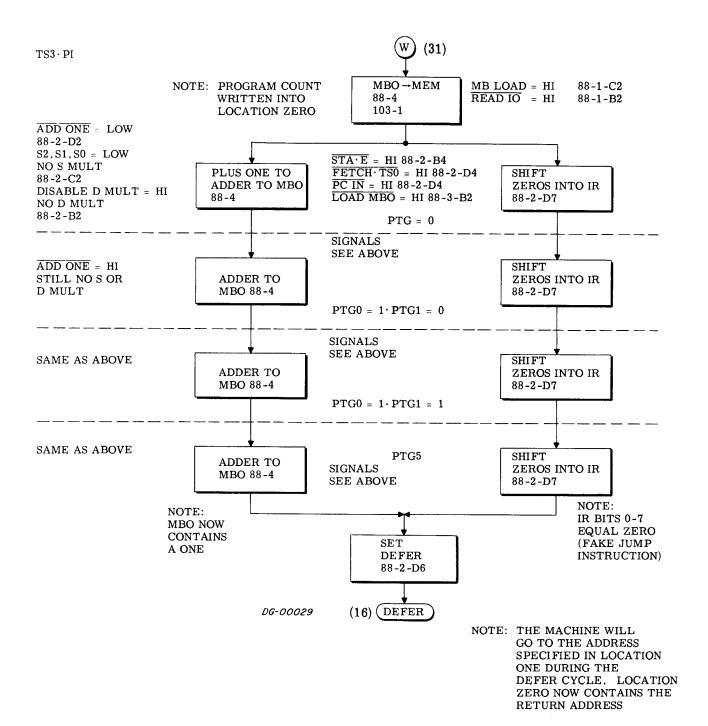




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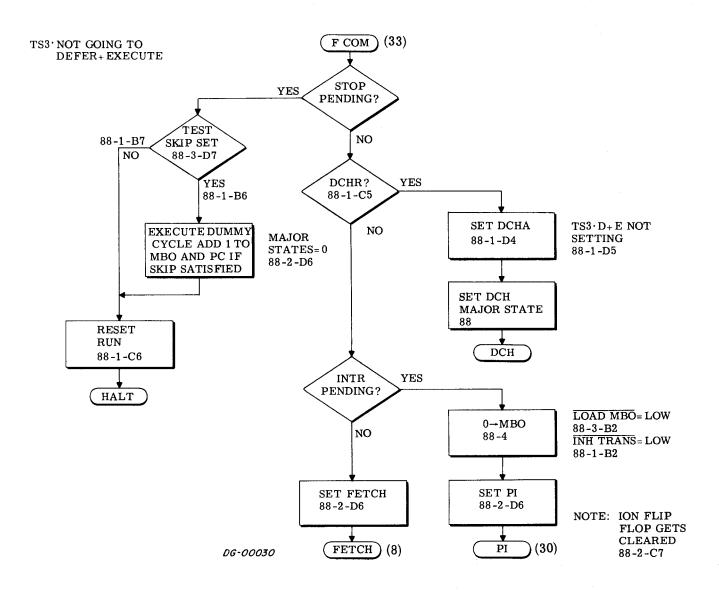


Table C-1

Adder and Multiplexer Control Signals During EFA Instructions

	*				*		
	S0	S1	S2	DISABLE D MULT	EFA· PTG1	ACD OUT	
REL · + (P6)	H/L	L	L	L	H/L	Н	
REL(P6)	н/н	L	L	L	H/L	Н	
(AC2) BASE +(AC3)	H/L	L	L	L	H/L	L	
(AC2) BASE -(AC3)	н/н	L	L	L	H/L	L	
PAGE ZERO	H/L	L	L	Н	H/L	H	DON'T CARE

* H for L for FIRST TWO LAST TWO NIBBLES NIBBLES

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Table C-2
Adder Control Signals During ALC Instructions (TS3)

IR BITS 5 6 7	FUNCTION	IR5(1)=LOW DISABLE D MULT	ACD OUT	EFA · PTG1	IR6(1) = HI S0	S1	IR6(0) = HI S2	IR7(1) = LOW ADD ONE
0 0 0	COMPLEMENT	Н	L	L	L	Н	н	Н
0 0 1	NEGATE	Н	L	L	L	Н	Н	L
0 1 0	MOVE	Н	L	L	Н	L	L	Н
0 1 1	INCREMENT	Н	L	L	Н	L	L	L
1 0 0	ADD COMPLEMENT	L	L	L	L	Н	Н	Н
1 0 1	SUBTRACT	L	L	L	L	Н	Н	L
1 1 0	ADD	L	L	L	Н	L	L	Н
1 1 1	AND	L	L	L	Н	Н	L	L
88-2 A7 & 6		88-2-B2	88-2 B2	88-2 A2	88-2 C2	88-2 C2	88-2 C2	88-2 D2

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Table C-3
Carry Chart For ALC Instruction

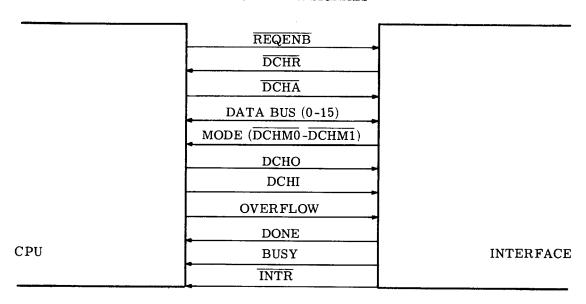
PRIOR TO INSTRUCTION	IR 10	BITS 11	OVERFLOW OCCURRED?	CARRY AT COMPLETION
CARRY RESET	0	0	NO	RESET
CARRY RESET	0	0	YES	SET
CARRY SET	0	0	- NO	SET
CARRY SET	0	0	YES	RESET
CARRY RESET	0	1	NO	RESET
CARRY RESET	0	1	YES	SET
CARRY SET	0	1	NO	RESET
CARRY SET	0	1	YES	SET
CARRY RESET	1	0	NO	SET
CARRY RESET	1	0	YES	RESET
CARRY SET	1	0	NO	SET
CARRY SET	1	0	YES	RESET
CARRY RESET	1	1	NO	SET
CARRY RESET	1	1	YES	RESET
CARRY SET	1	1	NO	RESET
CARRY SET	1	1	YES	SET

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Table C-4
Memory Reference Instruction Decoding Chart

IR ·	(0	1	2	3	4		
	0	0	0	0	0	JMP	SINGLE CYCLE(FETCH)
NO AC	0	0	0	0	1	JSR	EXCEPT DEFER(BIT5=1)
NO AC	0	0	0	1	0	ISZ]
	0	0	0	1	1	DSZ	TWO CYCLE(FETCH & EXEC)
AC <	0	0	1	AC	CD	LDA	EXCEPT DEFER(BIT5=1)
AC \	lo	1	0	AC	CD	STA	J

DATA CHANNEL SIGNALS



SEQUENCE:

- 1. REQENB TO I/O
- 2. DCHR TO CPU
- 3. DCHA TO I/O
- 4. a. MAIN MEMORY ADDRESS ON DATA BUS TO CPU
 - b. MODE BITS TO CPU (SEE TABLE)
- 5. DATA ON DATA BUS DIRECTION DETERMINED BY TYPE OF OPERATION.
- 6. DCHO OR DCHI TO INTERFACE
- A. OVERFLOW LINE APPLIES ON TO INCREMENT MODE
- B. DONE, BUSY AND INTR SAME AS NORMAL I/O

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MODE BIT TABLE

DCHM0	DCHM1	FUNCTION OUT (WRITE)
Н	L	INCREMENT
L_	H	IN (READ)
L	L	NOT USED

Figure C-6 Data Channel Signals

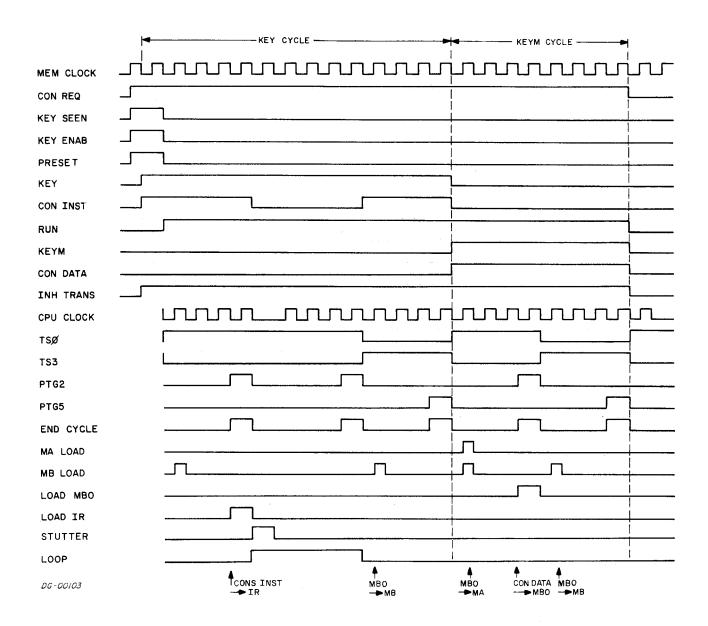


Figure C-7 Deposit Timing Diagram

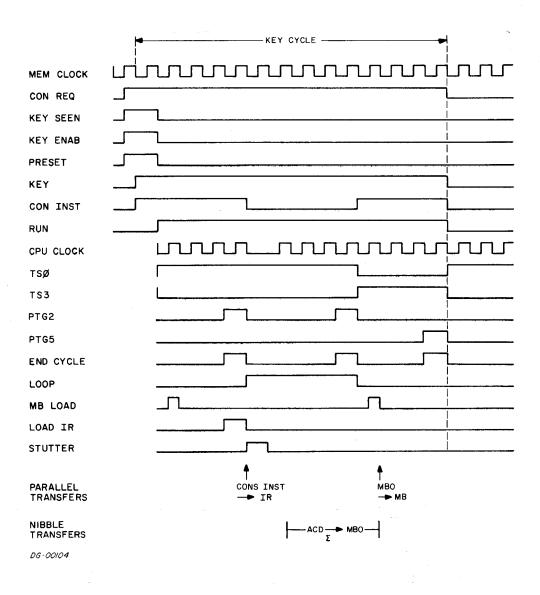


Figure C-8 Examine AC1 Timing Diagram

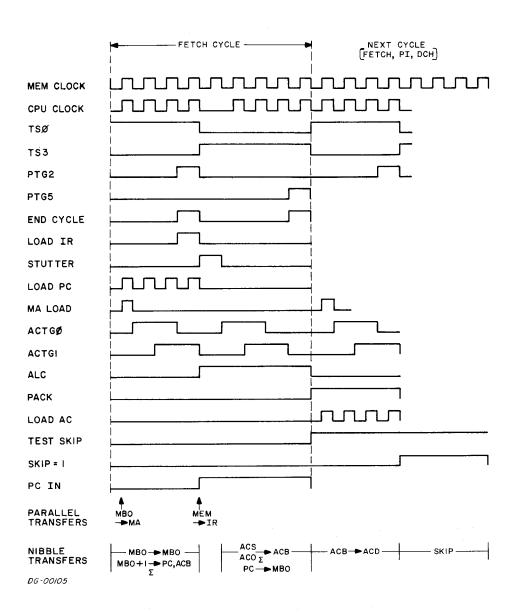


Figure C-9 ADD0, 1, SKP Timing Diagram

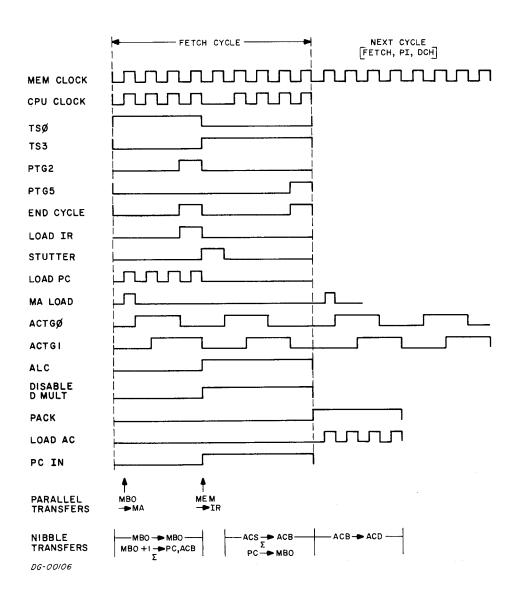


Figure C-10 MOV 0, 0 Timing Diagram

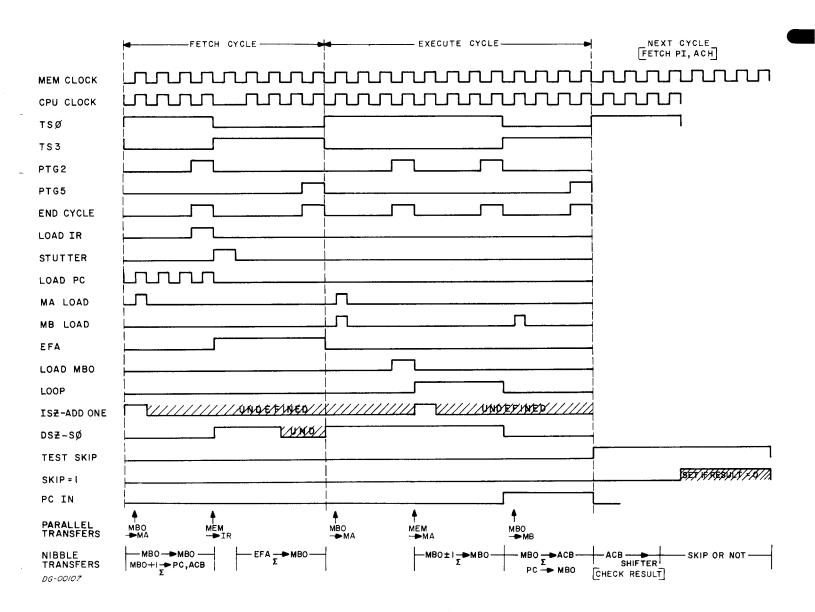


Figure C-11 Timing Diagram For Both The ISZ And DSZ Instructions

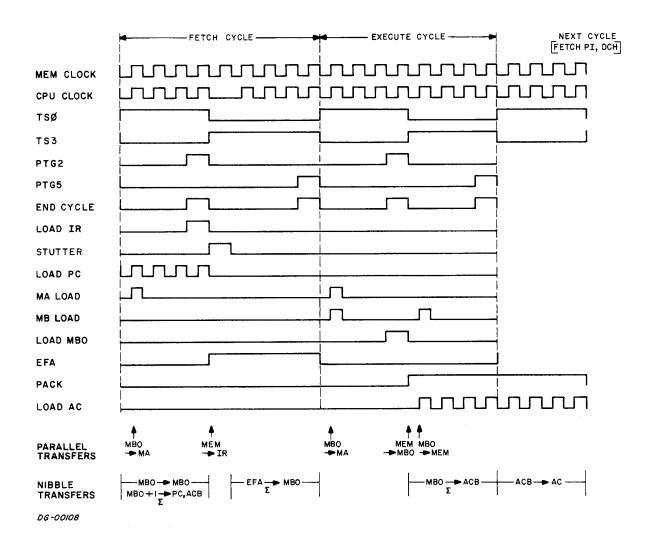


Figure C-12 LDA Timing Diagram

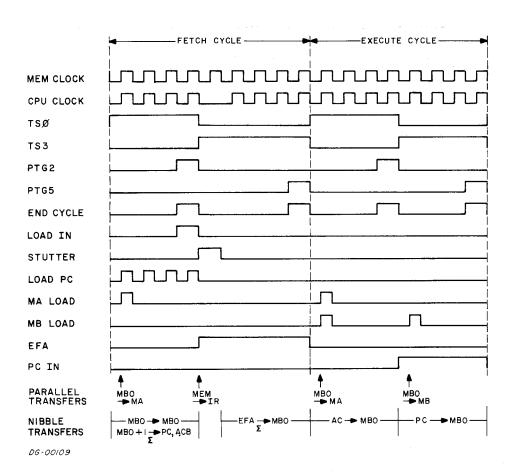


Figure C-13 STA Timing Diagram

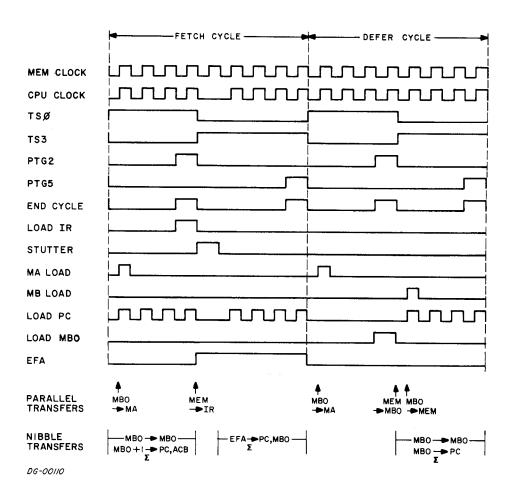


Figure C-14 JMP @ 100 Timing Diagram

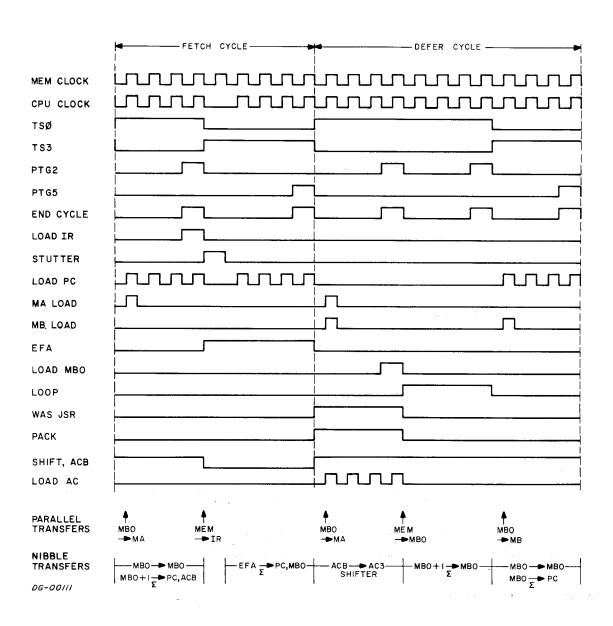


Figure C-15 JSR @ 20 Timing Diagram

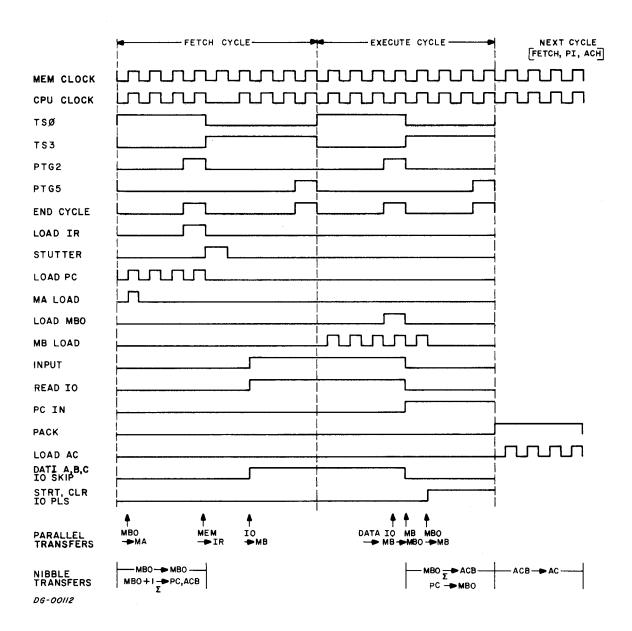


Figure C-16 I/O Input Timing Diagram

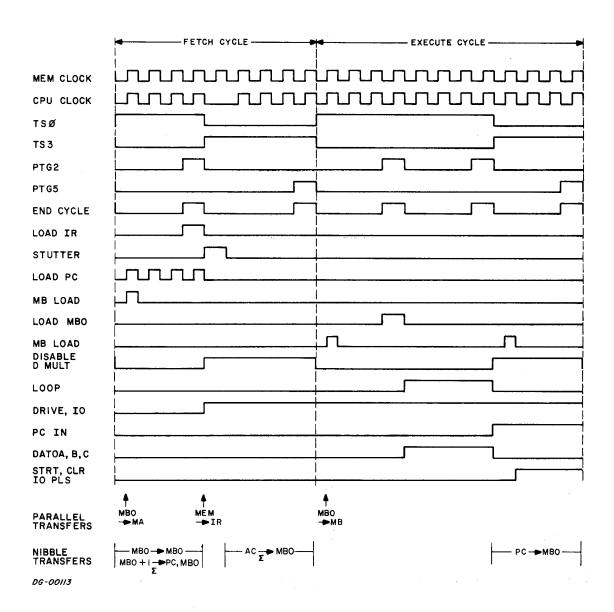


Figure C-17 I/O Output Timing Diagram

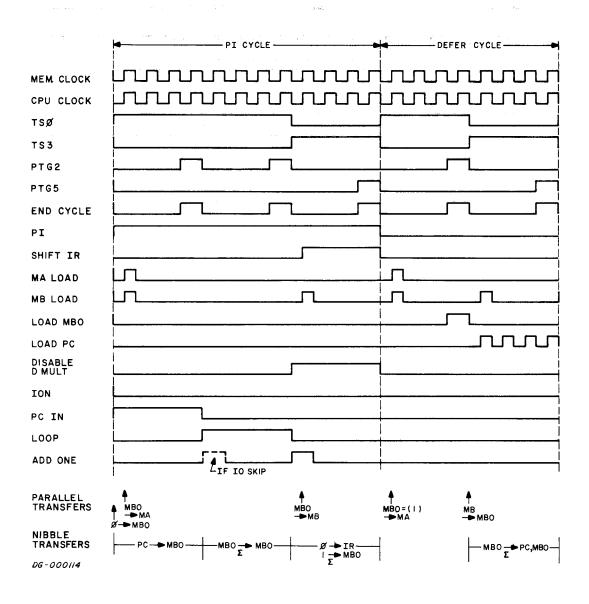


Figure C-18 PI Timing Diagram

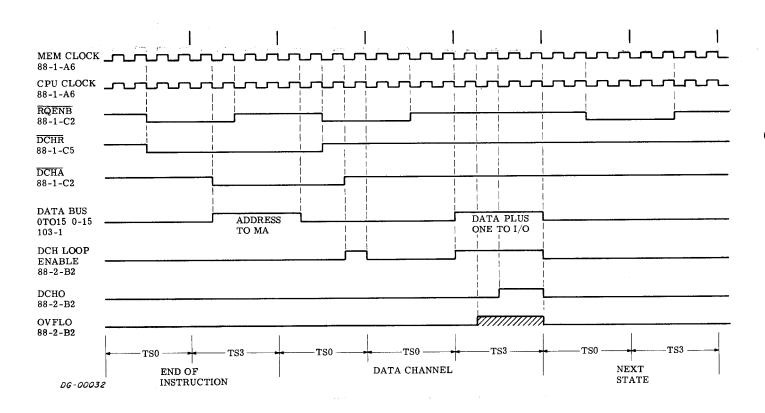


Figure C-19 Data Channel Increment Timing

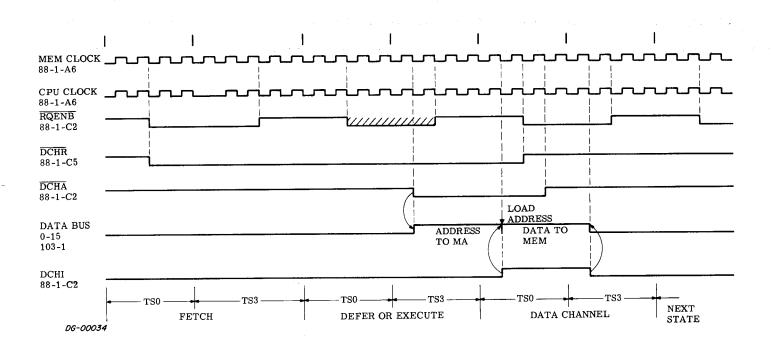


Figure C-20 Data Channel In Timing

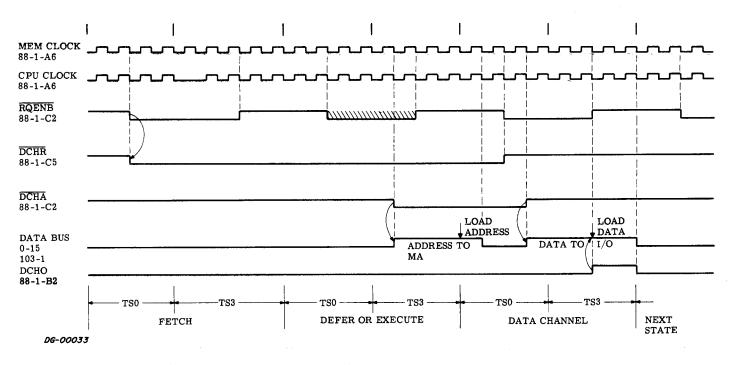


Figure C-21 Data Channel Out Timing

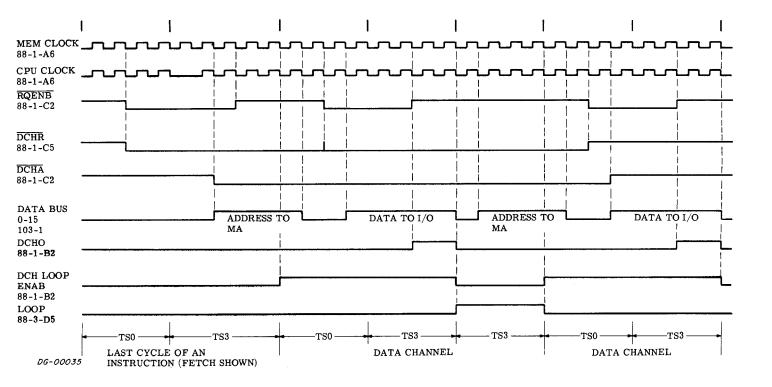


Figure C-22 Data Channel Out Followed By Data Channel In Timing

SECTION K

THE OPERATOR'S CONSOLE

INTRODUCTION

The console illustrated in Figure K-1, has a set of ADDRESS lights which display the contents of the MBO bus; a set of DATA lights which display the contents of the MEM bus; a register of toggle switches which will output to the MEM bus; a row of control switches at the bottom of the panel which instruct the computer on what to display in the lights, what to do with the information in the toggle switches, where to start or stop and how. The console also has a three position keyed rotary switch which turns power on and off and locks some of the operating switches.

CONSOLE LIGHTS AND SWITCHES

All the lights in the console are continually drawing about 10ma each through series resistors, so their filaments are always hot (but not glowing) and large surge currents are avoided when the filaments are driven on.

The Console ADDRESS Lights

These lights are always showing the state of the MBO bus which is driven directly from the MBO register. When the machine is running, the MBO register is continually shifting, so the display is meaningless; when the machine is stopped, the MBO register shows the contents of the PC, i.e., the next address.

The Console DATA Lights

These lights are always showing the state of the MEM bus. When the machine is running this bus carries data from memory to the instruction and MBO registers; when the machine is stopped this bus contains the contents of the memory buffer of the last memory selected.

The Console Operational Indicators

These lights are driven directly from their corresponding flip-flops in the central processor.

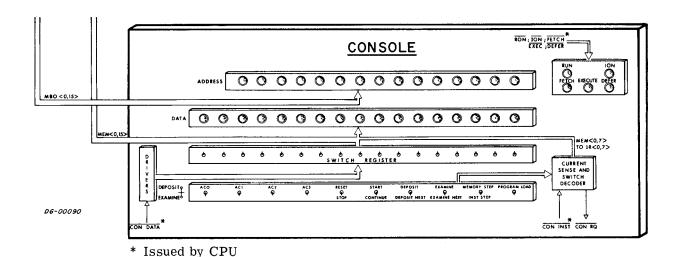


Figure K-1 The Console

The Console Switch Register

These switches connect non-inverting open collector buffers directly to the MEM bus. All Drivers go low when the $\overline{\text{CON DATA}}$ level goes low; $\overline{\text{CON DATA}}$ is issued by the CPU during the READS instruction or during a console operation that requires input from these switches, such as EXAMINE.

The Console Control Switches

All the control switches except STOP and RESET are wired through pull-up resistors to a common circuit which detects when current is flowing through a switch, initiates a delay to suppress contact bounce and then issues the signal $\overline{\text{CON REQ}}$ to the CPU. This signal forces the CPU into the key sequence shown in Figure K-2 which returns the signal $\overline{\text{CON}}$ $\overline{\text{INST}}$ to the console. $\overline{\text{CON INST}}$ connects switches AC0, AC1, AC2, AC3, DEPOSIT, DEPOSIT NEXT, EXAMINE and EXAMINE NEXT through a decoder to the MEM <0, 7> lines, which are input to the Instruction Register and interpreted as shown in Table K-1. The computer then goes into either the KEY or KEYM major state and follows the flows of Figure K-3.

The switches RESET, STOP, MEMORY STEP, IN-STRUCTION STEP and PROGRAM LOAD are wired separately to the CPU. RESET stops the computer at the end of the current cycle, issues the IORST pulse to all I/O devices, clears ION and sets the real time clock to the line frequency. STOP simply stops the computer at the end of the current instruction.

MEMORY STEP takes the processor through the current state and then stops. INST STEP takes the processor through the current state and on to the end of the current instruction. Both signals force a $\overline{\text{CON}}$ $\overline{\text{RQ}}$ to the CPU and output $\overline{\text{MSTP}}$ and $\overline{\text{ISTP}}$ respectively. PROGRAM LOAD deposits the contents of the bootstrap ROM into locations 0-37 and the machine at location 0. It outputs the signal $\overline{\text{PL}}$ to the CPU.

The Console Rotary Switch

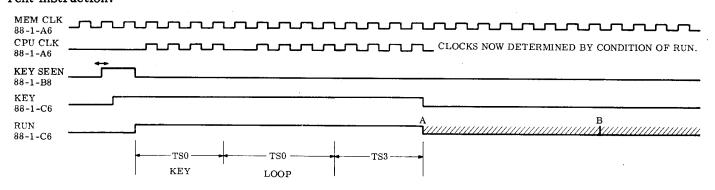
This switch controls the primary power to the power supply. It has three positions:

OFF - the primary power is removed from the power supply
ON - the primary power is applied to the power supply
LOCK - the primary power is applied to the power supply but the STOP

RESET switch is disabled

REFERENCES

- 1. "How To Use The Nova Computers" 015-000009-00.
- 2. Nova 800/1200 Console Print D-001-000089-05.



- A. RUN RESETS IF KEY WAS AC EXAMINE OR AC DEPOSIT.

 NEXT STATE IF RUN DOES NOT RESET;

 KEYM-IF KEY WAS DEPOSIT, DEPOSIT NEXT, EXAMINE, EXAMINE NEXT OR PROGRAM LOAD.

 FETCH-IF KEY WAS START
- B. RUN RESETS IF KEY WAS DEPOSIT, DEPOSIT NEXT, EXAMINE OR EXAMINE NEXT.

NOTE: IF KEY WAS CONTINUE, INSTRUCTION STOP OR MEMORY STOP



DG-00037

Figure K-2 The CPU Key Sequence Timing Diagram

Table K-1
Control Switch Decoding To The Instruction Register

								1		
CONSOLE										
INSTRUCT	ION	IR0	IR1	IR2	IR3	IR4	IR5	IR6	IR7	IR8 TO 15
	AC0	0	0	1	0	0	0	1	1	0
AC	AC1	0	0	1	0	1	0	1	1	0
DEP.	AC2	0	0	1	1	0	0	1	1	0
	AC3	0	0	1	1	1	0	1	1	0
	AC0	0	1	1	0	0	1	1	1	0
AC	AC1	0	1	1	0	1	1	1	1	0
EXAM.	AC2	0	1	1	1	0	1	1	1	0
	AC3	0	1	1	1	1	1	1	1	0
DEPOSIT		1	1	0	1	1	1	0	1	0
DEPOSIT NEX	T	1	1	0	1	1	1	0	0	0
EXAMINE		1	1	1	1	1	0	0	1	0
EXAMINE NEX	ζT	1	1	1	1	1	1	0	0	0
MEMORY STE	P	1	1	1	1	1	1	1	1	0
INSTRUCTION	STEP	1	1	1	1	1	1	1	1	0
PROGRAM LO	AD	1	1	1	1	1	1	0	1	0
START		1	1	1	1	1	0	1	1	0
		1	1	7.7	_	*4	$\overline{\lambda}$	7	$\overline{\lambda}$, A,

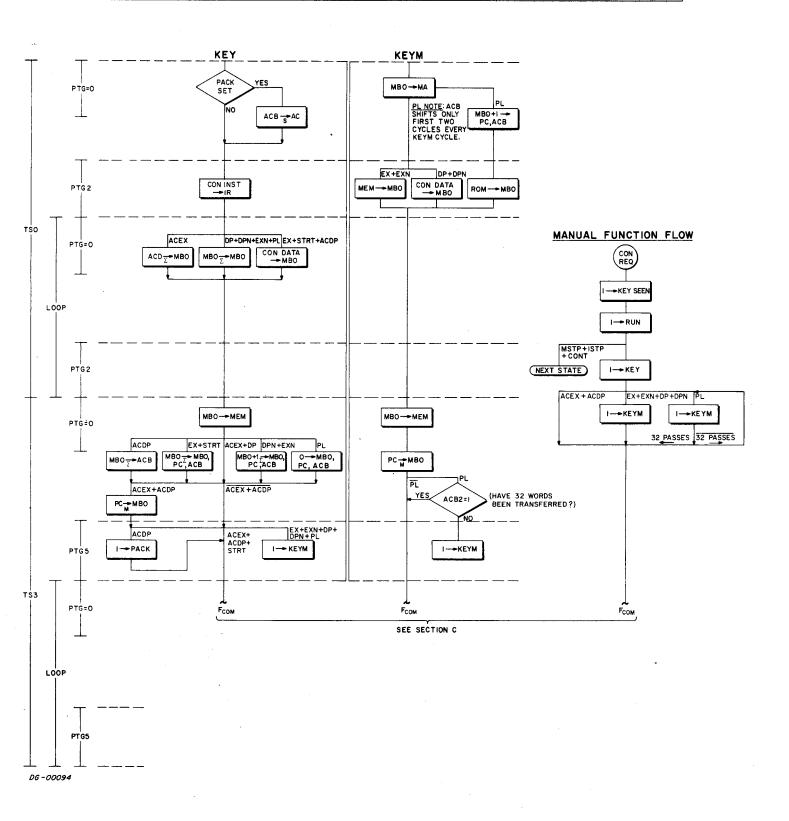


Figure K-3 Key, KEYM and Manual Flow Diagrams

Table K-2
Backpanel Connections To The Console
Through POA

POA		DACKDANET	DO A		DACKDANET
POA	CTCNIAT	BACKPANEL	POA	CICNIAI	BACKPANEL
PIN	SIGNAL	PIN	PIN	SIGNAL	PIN
1 1	GND	B1	27	+5	В4
2	MEM15	B18	28	MBO15	A41
3	MEM14	B76	29	MEM13	A35
4	MBO13	A37	30	MBO12	A39
5	MEM12	A36	31	MEM11	A51
6	MBO11	B5	32	MEM10	A45
7	MEM9	A53	33	+V _{LAMP}	N/A (BUS TO
				LAMP	POWER SUPPLY)
8	$\overline{\text{MBO9}}$	В9	34	MEM8	A55
9	$\overline{\mathrm{MBO7}}$	B14	35	MBO6	B16
10	$\overline{\text{MEM6}}$	B22	36	MEM5	B26
11	$\overline{\mathrm{MBO5}}$	B32	37	MEM4	B28
12	MBO14	A43	38	MBO3	B43
13	MEM2	B47	39	MEMO	B71
14	MBO1	B77	40	LAMP	GND
15	$\overline{\mathrm{MBO2}}$	B44	41	MEM1	B70
16	MBO4	B42	42	MEM7	B24
17	GND	B2	43	MEM3	B68
18	MBO8	B12	44	MBO10	B8
19	RESTART				
1	ENABLE	A32	45	STOP	A31
20	RST	A30	46	CONT DATA	A28
21	CON RQ	A27	47	CONT+ISTP+	
				MSTP	A25
22	CON INST	A22	48	MSTP	A20
23	$\overline{ ext{PL}}$	A19	49	CARRY	A15
24	ISTP	A17	50	FETCH	A13
25	ĪŌN	A16	51	EXEC	A11
26	RUN	A14	52	DEFER	A12

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SECTION P

POWER SUPPLY

INTRODUCTION

The Nova 1220 power supply is mounted on the backpanel below the circuit boards where it converts either 110Vac at 60Hz or 220Vac at 50Hz to regulated, current limited 5Vdc, -5Vdc, +15Vdc for the logic and memories, and to unregulated 6.3Vac for the real time clock. With the power monitor and restart option, the power supply interrupts the computer when it detects a line voltage failure (less than 90% of nominal) stops the computer when the voltage gets too low for reliable operation, and issues a start pulse to the computer when the line voltage recovers.

POWER SUPPLY CIRCUITS

The 30V Unregulated Supply

110Vac or 220Vac are input through the power cord to a switch on the console S1, then on to transformer T1. The two primaries of T1 are wired in parallel for 110Vac, and in series for 220Vac. Note that the cooling fan operates on 110Vac only.

The secondary of the transformer is wired to two full wave bridge rectifiers which output approximately 30V and -15V into RC filters. The 30V is applied to two series pass switching regulators which supply the regulated +5Vdc and +15Vdc. The 15V is applied to a simple linear regulator for the -5Vdc.

The Series Pass Switching Regulators

A series pass switching regulator acts like a multivibrator which sets when it detects a low output voltage and resets when it detects a high output voltage. When the regulator is set, it gates current from the 30V supply into an LC circuit and the load; when the regulator is reset, the load draws all of its power from the LC circuit until the circuit is sufficiently exhausted to be recharged by the regulator. The frequency at which the regulator sets and resets varies from 0 to 25KHz depending on the load.

There are two such regulators in the 1220 power supply, one for the +15Vdc (Figure P-1) and the other for the +5Vdc (Figure P-2). The -5Vdc is controlled by a linear regulator.

Note that the outputs of these circuits are DC levels with about .15V ripple at frequencies which vary with the loads.

The Fuses

The 1220 power supply has two fuses, a 10 amp between the power cord and the switch S1, and a 15 amp just after the bridge rectifier. The 10 amp will blow if there is a short in the cabling to S1, or if the convenience receptacle is overdrawing; the 15 amp will blow if the +15Vdc or +5Vds levels rise high enough to trigger an SCR, which then creates a short between the 30V supply and ground.

The Power Fail Module

This module detects a line voltage failure and outputs the signals shown in Table 2.

REFERENCES:

- 1. Fairchild Semiconductor Integrated Circuit
 Data Catalog Fairchild Semiconductor 1970
- Backpanel Nova 1220 print No. D-001-000208-00
- Backpanel 1220 Power Supply print No. D-001-000173-02.

Table P-1

Nova 1220 Power Supply Specifications

Output Voltage Level Name	Output Voltage	Maximum Current	Used On	Remarks
+ 15 V	14.5-15.1Vdc (.15V ripple)	9A	XY Drivers	Full wave rectified; Short Circuit & Over- voltage Protection Regulated
5 V	-5 7V dc	1A	Sense Amplifiers	Full wave rectified; Current limited by a resistor, regulated
+ 5 V	5.2 5.4Vdc	20A	IC Logic	Full wave rectified; Short Circuit & Over- voltage Protection Regulated
TTY	-57Vdc (.15V ripple)		Teletypewriter	Full wave rectified; Current limited by a resistor, regulated
RINH<0,15>	14.5-15.1Vdc	760mA each	Inhibit Driver	Full wave rectified; Short Circuit & Over- voltage Protection, Regulated
60Hz	6.3Vac	500mAc	Real Time Clock	This signal has the same frequency as the line (input) voltage
A10(VINH)	14.5-15.1Vdc (.15V ripple)	6Adc	Memory In- hibit Logic	Current Limited
B84(VINH)	14.5-15.1Vdc (.15V ripple)		Memory Drivers	Turns off memory drivers at about +12Vdc
+V _{LAMP}	≈14-16Vdc	2Adc	Console Lamps	Unfiltered, Unregu- lated

Table P-2
Output Signals of the Nova 1220 Power Fail Module

SIGNAL NAME	SIGNAL FUNCTION
PWR FAIL	-sets the PWR LOW flag in the processor when the line voltage drops to 90% of nominal voltage.
мем ок	-resets the RUN flag and stops the com- puter when the + Vmem (+15Vdc) voltage goes too low for the memory to function reliably.
+ 5OK	-sets the RUN flag and starts the computer when the $\pm 5 \text{Vdc}$ has risen to 4.4 Vdc.

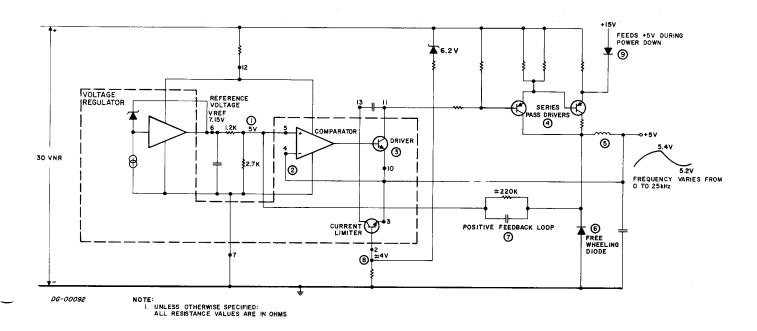


Figure P-1 Simplified Schematic of the +5Vdc Series Switching Regulator. When the comparator senses a difference between the (divided) reference voltage (1) and the output voltage (2) it switches, turning on the driver transistor (3) and consequently the series pass transistors (4). Current is shunted through the series pass transistors to the coil, output capacitor and load (5). The output voltage rises, reducing the error voltage to the comparator, which resets, turning off the driver (3) and consequently the series pass transistors. Now the load is supplied from power stored in the LC circuit. The back emf developed across the coil as a result of this switching is dropped across the free wheeling diode (6). Note that each time the comparator is forced to switch it is driven into saturation by the positive feedback loop which includes the 220K resistors (7).

The current limiter (8) turns on if the output voltage drops below about 4V, turning the driver (3) and subsequently the series pass transistors (4) off. The supply is latched in this state until power is removed and then returned.

The diode (9) feeds current from the 15V supply to +5V during power-down, driving the memory supply off early and the logic supply off later.

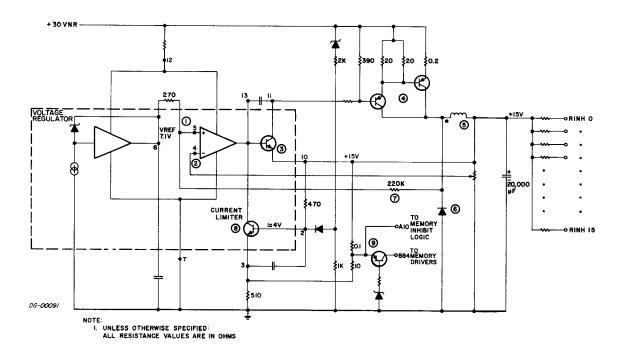


Figure P-2 Simplified Schematic of the +15Vdc Series Switching Regulator. When the comparator senses a difference between the reference voltage (1) and the divided output voltage (2), it switches, turning on the driver transistor (3) and consequently the series pass transistors (4). Current is shunted through the series pass transistors to the coil, output capacitor and load (5). The output voltage rises, reducing the error voltage to the comparator, which resets, turning off the driver (3) and consequently the series pass transistors. Now the load is supplied from power stored in the LC circuit. The back emf developed across the coil as a result of this switching is dropped across the free wheeling diode (6). Note that each time the comparator is forced to switch it is driven into saturation by the positive feedback loop which includes the 220K resistor (7).

The current limiter (8) turns on if the output voltage V MEM drops too low, or if the current at either terminal of (9) (memory inhibit and memory drive) is too high. When on, the current limiter turns off the driver and subsequently the series pass transistors, latching the supply into this mode until power is removed and then returned.

The transistor at (9) will switch off when the +15V drops too low for memory to function properly, thus removing power to the memory drivers.

SECTION M

THE MEMORY

A REVIEW OF CORE MEMORIES

A "bit" of information can be stored in a ferrite core by magnetizing the core in one of two possible directions or "states" and then calling one state a "1" and the other state a "0", similar to a flip-flop. Unlike a flip-flop, however, a core cannot be read simply by examining its output voltages; a core is read by forcing it into the "0" state and then watching for the current pulse which is always generated when a core changes state. If the pulse occurs, then the core must have been in the "1" state before it was excited; if no pulse occurs then the core must already have been in the "0" state because no transition took place.

Reading a core, then, always leaves it in the "0" state and although the information that it contained has probably been transferred to some register which was set by the current pulse, that information is no longer in the core, and it usually has to be restored with what is called a "write cycle". Writing means setting the core to a one or a zero, depending on the state of the memory register that usually contains core bound information.

Reading or writing into a core is a matter of sending current pulses along wires into the core; the direction of current relative to the core determines into which state the core will move.

Data General's core memories contain many thousands of these ferrite cores strung together like beads on wire. Each core has three wires passing through it, and these wires carry the currents to magnetize them and the pulses which occur when they change state. The memories are wired so that the computer can select any group of 16 bits at once, and read or write a complete 16 bit word "in parallel". A group of 16 cores, called an "address" is picked by passing current down two selected wires called X and Y, which are strung into the cores so that they both pass through only one address. The combined effect of current in these two wires is enough to flip the core into the zero state if it is not already there. Each core that flips sends a pulse down its own third wire called the sense wire which is then fed into one flip-flop of a 16 bit Memory Buffer. The flip-flop sets if it sees a pulse, and remains static if it does not. The register which selects the X Y wire or "lines" is called the Address Register.

Restoring the contents of the address involves resetting those core bits that set ones into the Memory Buffer. This is done by sending reverse currents down all the X and Y lines of that address, and inhibit currents to these bits which should remain in the "0" state. The contents of the memory buffer could be changed before this write-cycle so that new information is entered into the address.

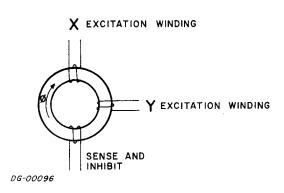


Figure M-1 Simplified Schematic of a Memory Core

A core will remain in the "one" state until currents pass through the X and Y excitation windings and force it into the "zero" state. The transition causes a pulse to travel down the sense winding to the detection logic. The core can be reset to the

"one" state by reversing the currents in the X and Y windings. The transition will still cause a pulse to be generated in the sense and inhibit winding, but the sense logic is disabled at this point.

SECTION N

MAINTAINING THE COMPUTER

INTRODUCTION

The Data General Corporation supports its equipment with a large field service organization, customer training programs and technical documentation. This section summarizes these services and includes tips on preventive maintenance, recommended tools and trouble shooting.

FIELD SERVICE ORGANIZATION

Field Service Programs

Data General's Field Service Organization currently offers its users a choice of three maintenance services. These services are subject to change without notice.

- 1. On Call Service Contract under which DGC will repair equipment at the installation when DGC is notified of a problem by the user. DGC also provides preventive maintenance on a regular schedule under this contract. Parts, labor and travel are included in the monthly payment schedule which is determined by the type and amount of equipment to be serviced and the distance between the installation and the nearest DGC service center.
- 2. Factory Service Contract under which DGC will:
 - (1) repair equipment when it is returned to the DGC factory in Southboro, Mass. The user assumes full responsibility for freight and insurance charges to and from the plant. Parts and labor are included in the monthly payment schedule.
 - (2) repair equipment at the installation when notified of a problem by the user. Parts are included in the monthly maintenance schedule, labor is charged at reduced rates and travel is charged at the prevailing standard rates.
- 3. Hourly Service under which parts, labor and travel are charged as needed at prevailing rates. No contract is signed for this service.

Field Service will also generate on request a complete spare parts list for any installation, and rent or sell replacement and loaner boards.

General Terms and Conditions (Subject to change without notice).

- 1. Equipment which is not under a DGC service contract or normal warranty is subject to an inspection by DGC Field Service before it is eligible for a service contract. All costs for this inspection are borne by the user.
- 2. The user must bear all maintenance costs incurred as a result of unauthorized changes to DGC equipment. These costs will be charged as Hourly Service, regardless of the type of service contract existing between DGC and the user.
- 3. No additional service charge will be added for new (add-on) equipment until the warranty period of that equipment has expired.
- 4. All services are offered between 9 a.m. and 5 p.m. Monday through Friday excluding DGC holidays.
- 5. The minimum contract period is 6 months.
- 6. Field Service price schedules are available on request from Data General Field Service, Southboro, Mass. 01772, Telephone 617-485-9100.

TRAINING ORGANIZATION

Data General's Training Organization currently offers its users four types of training courses. These courses are subject to change without notice.

Mainframe Maintenance Course. This course covers the logical structure of the central processor, memory, operator's console and power supply. Students must have experience with digital logic, integrated circuits and computer principles.

Fundamentals of Mini-Computer Programming.
This course covers number systems, logic, flow charts and computer architecture. Students should have an aptitude for mathematics.

Basic Programming. This course covers Data General's assembly language utility software including loaders, editors, debuggers and assemblers. Students should have experience in programming.

Advanced Programming. This course covers Data General's Operating Systems, DOS, RTOS and SOS. Students must have experience in programming.

Courses are scheduled regularly in the training department at Southboro, Mass., and occasionally in field offices. Special courses can be arranged.

For more information call or write

Training Department
Data General Corporation
Southboro, Mass. 01772

Tel. 617-485-9100

PREVENTIVE MAINTENANCE

Periodically carry out the checks listed in Table, N-1, and remember the following points:

- 1. It is very poor practice to use the equipment as a counter top, particularly for liquids like coffee or soft drinks.
- 2. Always check the line voltage before plugging an expensive piece of equipment into an unknown socket. (see Section I).
- 3. Be careful not to get metal filings into the equipment; for example never let the equipment room be cleaned with steel wool.
- 4. Never clean the equipment with a vacuum cleaner that has a metal (conducting) nozzle.
- 5. Always be aware that too much heat, moisture or contaminants can do much to harm the equipment (see Section I).
- 6. Be very careful how cables are routed; they should never be strained, cramped or crushed (underfoot).

Table N-1

Preventive M	Maintenance Check List
Item	Check
Mechanical Connections	that all screws are tight and that all mechanical assem- blies are secure.
	2. that all crimped lugs are secure and properly inserted onto their mating connectors.
Wiring and Cables	 all wiring and cables for breaks, cuts, frayed leads, or missing lugs.
	2. wire wraps for broken or missing pins.
	3. that no wires or cables are strained or cramped.
	4. that cables do not interfere with doors, and that they do not chafe when doors are opened and closed.
Air Filters	all air filters for cleanliness and for normal air movement through cabinets.
Modules and Components	1. that all modules are properly seated. Look for areas of discoloration on all exposed surfaces.
	2. all exposed capacitors for signs of discoloration, leakage, or corrosion.
	3. power supply capacitors for bulges.
Indicators and Switches	all indicators and switches for tightness; check for cracks, discoloration, or other visual defects.
Fans	for broken fan blades.
Diagnostics	Run all diagnostics periodically

Table N-2

	Recommended Maintenance Tool Kit						
ITEM	QTY	DESCRIPTION	MFG. & PART No.				
1	1	6" combination slip joint pliers	Utica # 5-6				
2	2	5 1/2" needle nose pliers	Utica # 654-5 1/2				
3	1	4" needle nose pliers	Utica # 23-4				
4	1	5" diagonal wire cutters	Utica # 44-5				
5	1	4" diagonal wire cutters	Utica # 347-4 CFJS				
6	1	5" ignition pliers	Utica # 51 7- 5				
7	1	Screwdriver kit including handle, 3/16", 1/4", 5/16" slotted #1, #2 phillips blades, each 4" long	Xcelite # 99 PV-6				
8	1	3/32 slotter screwdriver with 2" blade	Xcelite # R3322				
9	1	1/8" #0 phillips screwdriver	Xcelite # P12S				
10	1	Magnetic pick up tool	Bonney # K26				
11	1	3/32 through 3/8, 10 pc nut driver set	Xcelite # PS120				
12	1	Xacto knife					
13	1	6" adjustable wrench	Utica # 91-6				
14	1	Ignition wrench	Bonney # N24R				
15	Set of 25 feeler gauges with 3" blades		Bonney # K53				
16	1	Set of 15 hex keys	Bonney # N6R				
17	1	Slotter 5" screw starter	Bonney # 5527				
18	1	Phillips 6 1/4" screw starter	Bonney # 556				
19	1	5" adjustable wire strippers	Utica # 110-5				
20	1	Set of 4 cut needle files	Hunter # F228A				
21	1	4 1/2" electrical tweezers	Hunter # B3M3				
22	1	flash light					
23	1	Can Quick Freez (circuit cooler)					

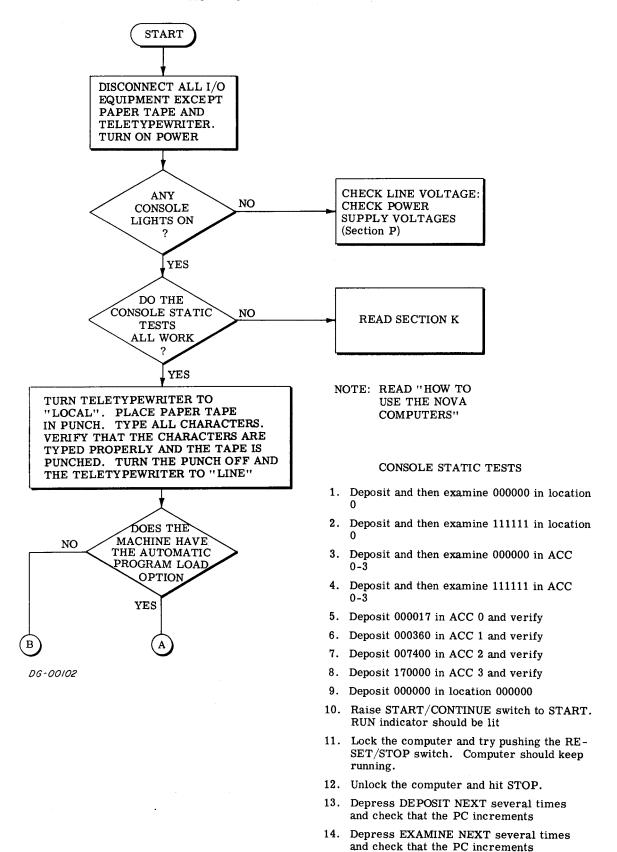
Table N-2 (Continued)

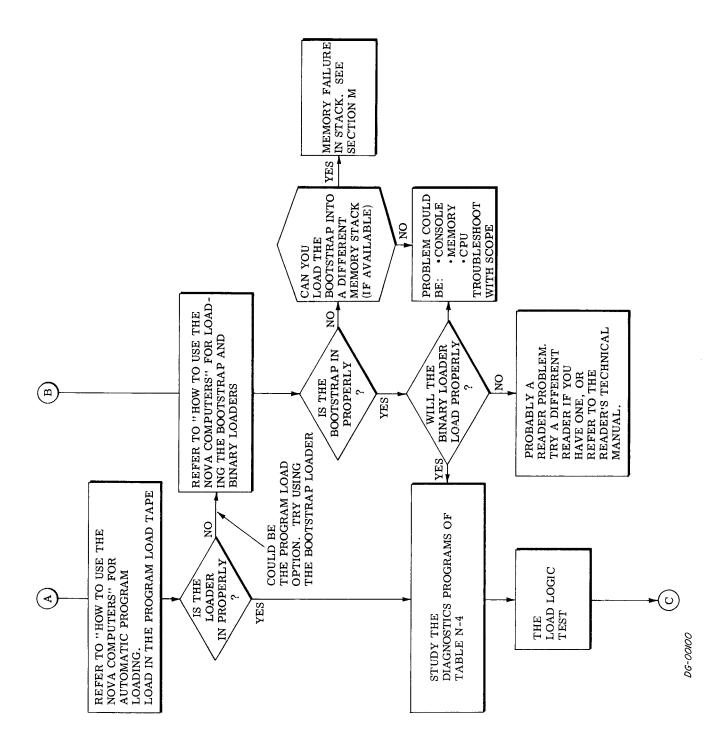
	Recommended Maintenance Tool Kit							
ITEM	QTY	DESCRIPTION	MFG & PART No.					
24	1	Can degreaser (flux remover)						
25	2	16P I/C test clip						
26	1	23 1/2 watt soldering iron with iron plated chisel tip	Ungar					
27	1	47~1/2 watt soldering iron element						
28	1	11b, 60/40 resin core solder	Kester					
29	3	Spools of solder wick						
30	2	Acid brushes						
31	1	Vacuum solder removal tool						
32	1	Multimeter	Simpson # 260					
33	1	Tool carrying case						
34	1	Oscilloscope	Tektronics # 453					
35	1	Current probes	Tektronics # P60-22					

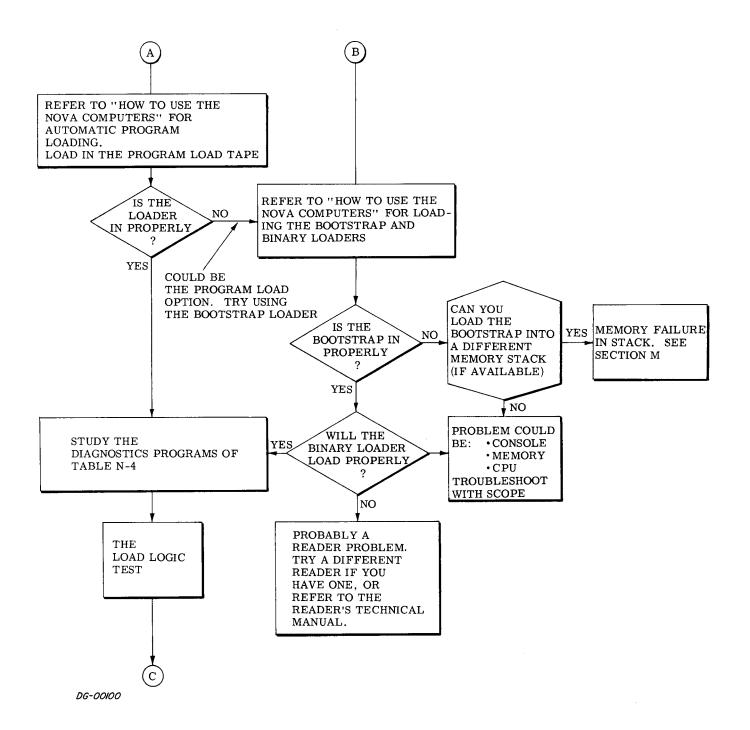
Table N-3

	The Nova 1220 Diagnostics								
Diagnostic	Part No.	Binary Tape No.	Description						
Address Test	097-000007	095-000005	checks memory address selection logic						
Checkerboard III	097-000014	095-000031	tests memory sense amplifiers and inhibit logic						
Nova 1220 Logic Test	097-000017	095-000036	tests CPU logic other than I/O						
Nova 1220 Instruction Timer	097-000019	095-000038	tests CPU clock logic and outputs time-to-complete for each instruction						
Exerciser	097-000004	095-000012	tests CPU logic, teletypewriter, reader, punch and real-time clock;						
Arithmetic Test	097-000018	095-000037	exercises arithmetic and logical instructions in CPU						

HOW TO TEST THE COMPUTER







SECTION M

THE MEMORY

A REVIEW OF CORE MEMORIES

A "bit" of information can be stored in a ferrite core by magnetizing the core in one of two possible directions or "states" and then calling one state a "1" and the other state a "0", similar to a flip-flop. Unlike a flip-flop, however, a core cannot be read simply by examining its output voltages; a core is read by forcing it into the "0" state and then watching for the current pulse which is always generated when a core changes state. If the pulse occurs, then the core must have been in the "1" state before it was excited; if no pulse occurs then the core must already have been in the "0" state because no transition took place.

Reading a core, then, always leaves it in the "0" state and although the information that it contained has probably been transferred to some register which was set by the current pulse, that information is no longer in the core, and it usually has to be restored with what is called a "write cycle". Writing means setting the core to a one or a zero, depending on the state of the memory register that usually contains core bound information.

Reading or writing into a core is a matter of sending current pulses along wires into the core; the direction of current relative to the core determines into which state the core will move.

Data General's core memories contain many thousands of these ferrite cores strung together like beads on wire. Each core has three wires passing through it, and these wires carry the currents to magnetize them and the pulses which occur when they change state. The memories are wired so that the computer can select any group of 16 bits at once, and read or write a complete 16 bit word "in parallel". A group of 16 cores, called an "address" is picked by passing current down two selected wires called X and Y, which are strung into the cores so that they both pass through only one address. The combined effect of current in these two wires is enough to flip the core into the zero state if it is not already there. Each core that flips sends a pulse down its own third wire called the sense wire which is then fed into one flip-flop of a 16 bit Memory Buffer. The flip-flop sets if it sees a pulse, and remains static if it does not. The register which selects the X Y wire or "lines" is called the Address Register.

Restoring the contents of the address involves resetting those core bits that set ones into the Memory Buffer. This is done by sending reverse currents down all the X and Y lines of that address, and inhibit currents to these bits which should remain in the "0" state. The contents of the memory buffer could be changed before this write-cycle so that new information is entered into the address.

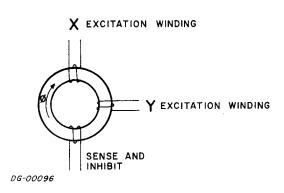


Figure M-1 Simplified Schematic of a Memory Core

A core will remain in the "one" state until currents pass through the X and Y excitation windings and force it into the "zero" state. The transition causes a pulse to travel down the sense winding to the detection logic. The core can be reset to the

"one" state by reversing the currents in the X and Y windings. The transition will still cause a pulse to be generated in the sense and inhibit winding, but the sense logic is disabled at this point.

DATA GENERAL'S CORE MEMORIES

The memories used on the basic computer consist of cores arranged in a three wire 3D scheme in which the sense and inhibit functions share the same wire. The cores are laid out in a single plane in mats, and wired together in the bow tie pattern shown in Figure M-2. There are four core planes available; 1K, 2K, 4K, and 8K. Each plane is assembled on a "daughter" board which is mounted on a 15" by 15" "mother" board, where most of the memory logic sits. Power is supplied by the chassis supply

The memory logic on any board consists of drivers, sense amplifiers, a Memory Address Register, a Memory Buffer Register, Multiplexers, and Memory select logic shown in Figure M-3.

Data is transferred between memory and the central processor or an I/O device along three data buses called:

$\overline{ ext{MEM}}$	which transfers data from memory to
	the Central Processor:

MBO which transfers data from the Central Processor to Memory

DATA which transfers data between memory and I/O devices in either direction.

The Memory Select Logic

When a memory board is plugged into a computer, its select logic must be wired to respond to the correct code in the MA register, since the MA registers of all boards are loaded with the same address at the same time. This wiring is done with a set of jumpers that connect either the 0 or 1 side of the high order MA bits to an "and" gate. The output of this "and" gate will be true only if the code for which it is wired is in the MA register, and only when this output is true can the memory respond. This code must be unique to that memory board.

The jumpers are forced into points on the board. These points are located on the logic side of the board at the lower right hand corner when its fingers are pointing at you. If there is a mixture of boards, i.e., 1K, 2K, 4K or 8K, it is a good policy to wire the largest board for low core, the second largest above it and so on. This way there will not be any gaps in the system's core map.

Figures M-4 and M-5 show how the select logic of the four types of boards are jumpered.

REFERENCES:

8 K	Memory Prints	#001-000238-00
4K	Memory Prints	#001-000236-00
2K	Memory Prints	#001-000234-00
1K	Memory Prints	#001-000232-00

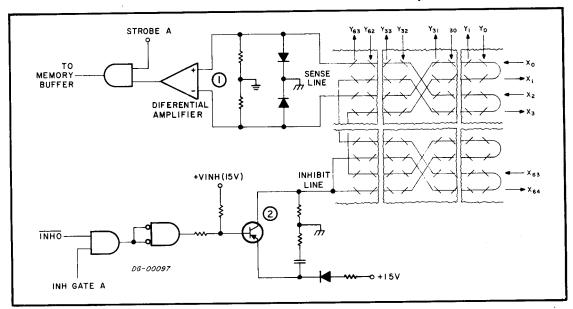


Figure M-2 Simplified Schematic of The Core Memory's Sense and Inhibit Lines

The sense and inhibit functions share the same wire. The sense circuitry, (1), sees both ends of the wire, and detects negative pulses with a differential amplifier. The output of this amplifier is examined at STROBE time.

The inhibit logic, (2), drives +15Vdc level into the middle of the same wire at INHIBIT time. The current is divided and passes through all cores to ground through the diodes at the other end.

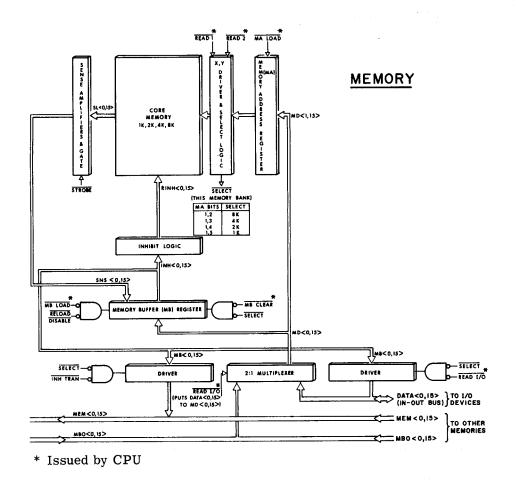


Figure M-3 Core Memory

During a typical FETCH instruction, the CPU outputs the memory address on the MBO <0, 15> data lines and then issues $\overline{\text{MA LOAD}}$. READ I/O is high, so the address is strobed into the Memory Address register and output to the driver select logic. Then, READ 1 and READ 2 are issued, gating the X and Y currents to the selected address. A little later, STROBE is output by the CPU and it gates all core pulses into their corresponding Memory Buffer bits. The Memory Buffer is then re-read back into core by reversing all the driver currents and gating the INHIBIT signal issued by the CPU to those bits which are not to be reset. If the contents of the address are to change, the Memory Buffer is loaded with the new word before the address is re-written.

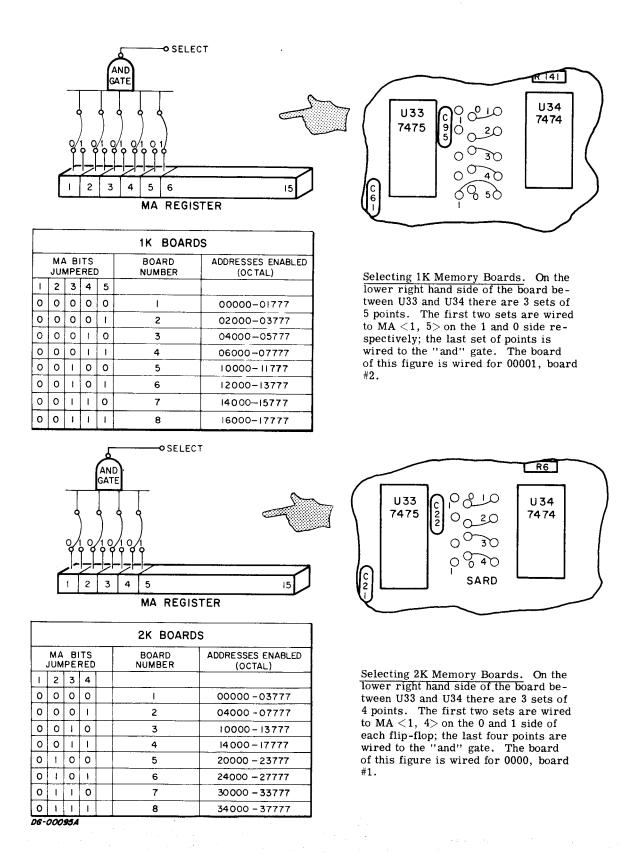
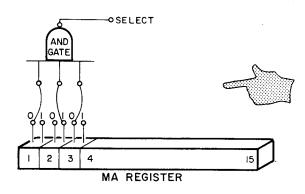


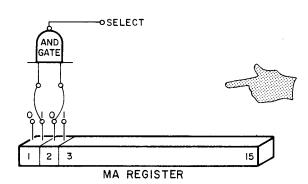
Figure M-4 Wiring Up The Select Logic of 1K and 2K Boards



			R6	
Con-	U33 7475	0 10 20 20 30 0 40 sard	U34 7474	
V				

	4K BOARDS							
	MA BITS JUMPERED)	BOARD NUMBER	ADDRESSES ENABLED (OCTAL)		
1	2	3						
0	0	0			1	00000-07777		
0	0	1			2	10000-17777		
0	1	0			3	20000-27777		
0	1	ı			4	30000 37777		
.1	0	0			5	40000 - 47777		
1	0	ı			6	50000-57777		
1	Ī	0			7	60000-67777		
I	ı	ı			8	70000-77777		

Selecting 4K Memory Boards. On the lower right hand side of the board between U33 and U34 there are 3 sets of 4 points. The first two sets are wired to MA <1, 3> on the 1 and 0 sides respectively, the last set is wired to the "and" gate. The board of this figure is wired for 010, board #3. Sard 4 should NOT be jumpered.



	U30 7475	00 0 R U3	9 9
		0 U 01 ² O 01 ³ O	
T.		C88 6 C	ر ا

8K BOARDS						
		BITS PERED	BOARD NUMBER	ADDRESSES ENABLED (OCTAL)		
Ì	2					
0 0			ı	00000 - 17777		
0 1			2	20000 - 37777		
10			3	40000 - 57777		
ı	1		4	60000 -77777		
06-	000	95B	<u> </u>			

Selecting 8K Memory Boards. On the lower right hand side of the board between U30 and U31 there are 2 sets of 6 points. The first set is wired to MA <1,3> on the 1 and 0 sides; the second set is wired to the "and" gate. The board of this figure is wired for 10, board #3. Position 3 should NOT be jumpered.

Table M-1

External Memory Signals

SIGNAL NAME	FUNCTION
DATA < 0, 15>	16 bidirectional lines which carry information to and from devices on the IN-OUT bus.
DRIVE I/O	Issued by CPU-1 to strobe the MB register onto DATA <0, 15> lines.
INH TRAN	Issued by CPU-1 to prevent the MB register from outputting to the MEM <0, 15> bus during a data transfer from the console.
INHIBIT SELECT	Issued by CPU-1 to prevent the memory from being selected.
MA LOAD	Issued by CPU-1 to load the MA register.
MEM <0, 15>	16 lines which carry information from the memory to CPU-1.
MB CLEAR	Issued by CPU-1 to clear the MB register.
MB LOAD	Issued by CPU-1 to load the MB register.
READ 1	Issued by CPU-1 to select the memory drivers.
READ 2	Issued by CPU-1 to select memory drivers.
READ I/O	Issued by CPU-1 to enable the DATA <0 , 15> lines into the MD <1 -15> lines.
RELOAD DISABLE	Issued by CPU-1 to inhibit MB Load.
STROBE	Issued by CPU-1 to strobe core pulses into the Memory Buffer.
$\overline{\text{MBO}} < 0, 15 >$	16 lines which carry information from CPU-1 to memory.

SECTION I

NOVA 1220 INSTALLATION

INTRODUCTION

This section explains how to unpack, assemble and cable the computer.

PLACING THE COMPUTER

The computer room must be large enough to accommodate the equipment, operating personnel, tables and chairs, storage space (for tapes, manuals and listings), service clearances and possible future expansion. The room should be well lit and clean, with adequate primary power. The temperature and humidity must fall within acceptable tolerances of the most sensitive peripheral.

Overhead sprinklers should be "dry pipe" systems that remove primary power from the room and turn on a battery operated light source before opening the master valve. If power connections are made under the floor, use waterproof receptacles and connections. Any carpeting should be of the type that minimizes static electricity, and metal flooring should be well grounded.

UNPACKING THE COMPUTER

The computer is shipped in the kit shown in Figure I-1.

- 1. Open the top of the outer carton; remove all cables, manuals, packing filler, etc.
- 2. Remove the styrofoam container (it and contents weigh about 50 pounds) and place it on a flat surface right side up.
- 3. Unstrap the container and remove the cover and styrofoam spacers.
- 4. Carefully remove the styrofoam block from the back of the computer.
- 5. Remove the computer, placing your hands under the chassis front and back.
- 6. The computer is sometimes shipped with cardboard spacers in spare slots to keep the boards from vibrating during shipment. Remove these.

Table I-1

The Nova 1220 Electrical, Mechanical and Environmental Specifications

Voltage (AC)	Current (A) NOMINAL @ 115V	Power Dissipation (W)	Heat Dissipation (Btu/hr)	Operating Temperature (min-max F)	1 '	Humidity (Rel) (min-max)	Maximum Wet Bulb	Maximum Cable Length	Dimensions (inches)	Service Clearance (inches)	Weight (Ibs)
110	9	1000	3400	32-130	-30-+160	20% 90%	78°F	IN-OUT 50FT	HEIGHT 10 ½" WIDTH 17 ½" LENGTH 22 1/4"	BACK 3" FRONT 36"	PACKED 65 UN- PACKED 45

The Nova 1220 operates from a single-phase source at 115V 60Hz or ± 50 Hz all $\pm 20\%$. This device has a separate 4.5 foot power cord terminating in a standard 3 wire single-phase male connector. An earth ground connection must be supplied through the power cord.

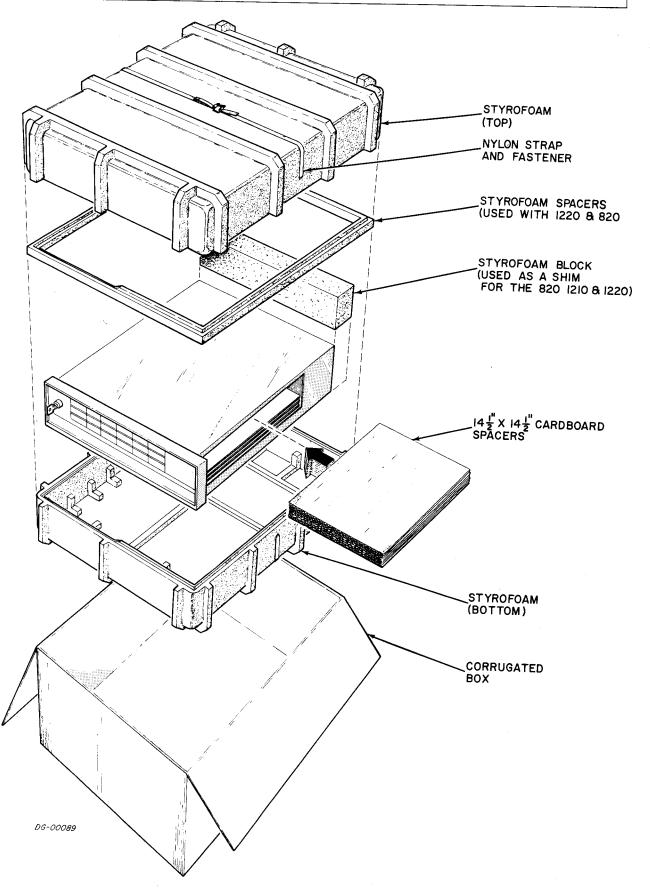


Figure I-1 The Nova 1220 Shipping Kit

PACKING THE COMPUTER

- Locate the original shipping container and packing material. If it is not available, order a shipping kit from Data General Corporation.
 DO NOT SHIP THE COMPUTER IN ANY OTHER CONTAINER.
- 2. Fill any large spaces inside the chassis with just enough cardboard spacers so the boards cannot vibrate.
- 3. Place the computer in the bottom half of styrofoam container "front justified" with the back
 end on top of the extra rib. Pack the power
 cord into the hollow area at the back. Fill in
 the space at the back with the styrofoam block
 to prevent the computer from moving during
 shipment.
- 4. Add the styrofoam spacers as needed.
- 5. Put on the cover of the styrofoam container and strap the pieces together.
- 6. Put the styrofoam container into the cardboard box. Place any odds and ends on top of the container, and fill in any empty spaces with cardboard or pieces of styrofoam.
- 7. Close and seal the cardboard box.
- 8. Call your local Field Service representative for the correct address if the equipment is to be shipped to Data General Corporation.

ASSEMBLING THE COMPUTER

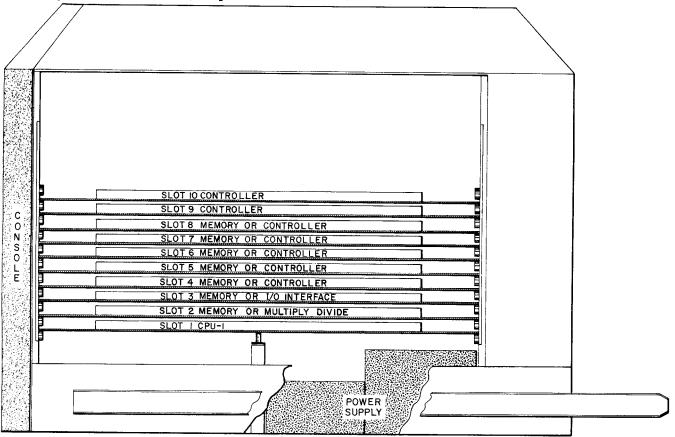
Assembling the computer outside the factory involves installing memory or controller boards or mounting the chassis into a 19" rack.

Installing or Removing Boards

The Nova 1220 computer has slots for ten 15 X 15 inch circuit boards which plug into ten sets of 100 pin connectors on the PC backpanel. The slots are numbered from the bottom up and assigned as follows:

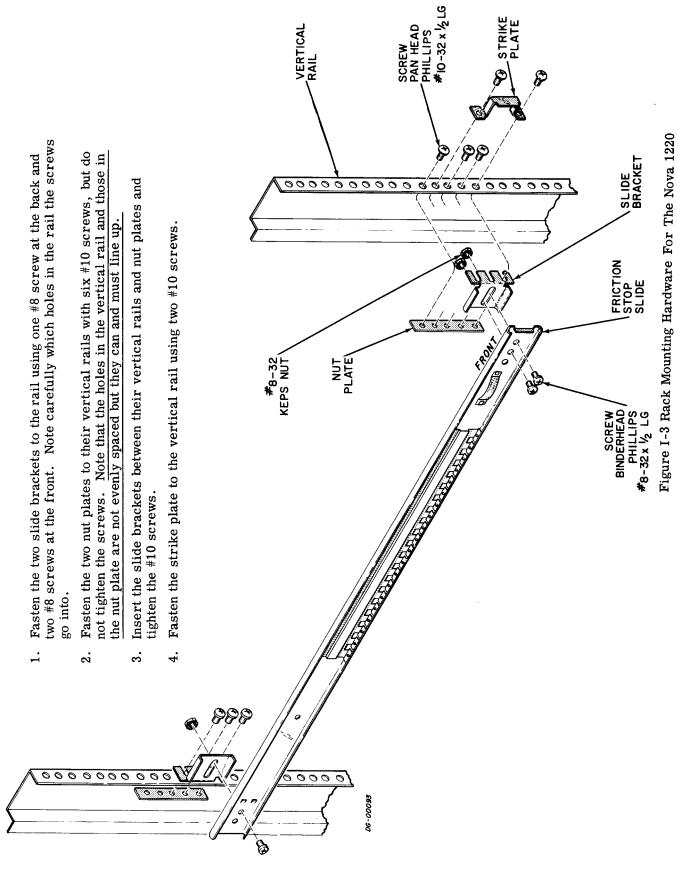
Slot Number	Boards Accepted
1	CPU-1 Only
2	Any 1220 Memory or the Multiply Divide option (8107)
3	Any 1220 Memory or the I/O Interface Assembly (4007)
4-8	Any 1220 Memory or Controller
9,10	Any 1220 Controller

Note that slot 3 has special wiring for the 4007.



DG-0009**9**

Figure I-2 Nova 1220 Board Slots



Note that if the Multiply Divide option 8107 is used, it must go into slot 2, and if the I/O Interface Assembly is used it must go into slot 3. If a new memory board is installed, check that the select logic jumpers are correct (See Section M).

If boards are installed or removed from the computer chassis, it is important that the integrity of the Program Interrupt and Data Channel priority systems be preserved. The Priority systems of the Program Interrupt and Data Channel facilities each use a scheme in which a wire is chained through every controller, one after the other, in such a way that only when there is an enabling level on that wire can a controller effectively request service of the facility. The enabling level on the wire will appear at any given controller only if all controllers closer to the computer on the chain are not requesting service themselves; i.e., whenever a controller requests service it removes the enabling level from all devices below it on the chain. There are two chains, one for the Program Interrupt and the other for the Data Chan-

The program interrupt chain enters a board slot at pin A96 and leaves at pin A95; the data channel chain enters at pin A94 and leaves at pin A93. (See "How to Use the Nova Computers" for more details.)

Here are the rules:

- 1. Memories take Data Channel and Program Interrupt signals and pass them through their slots.
- 2. All controllers that use the interrupt system must be included in the interrupt chain; all controllers that use the data channel must be included in the data channel chain.
- 3. The Data Channel and Program Interrupt chains are completely independent and must not cross. Each chain must run through the controllers in series, NEVER in parallel.
- 4. Controllers that use the Program Interrupt system but do not use the Data Channel system do not need a jumper for the unused line. The only jumpering required is on unused slots or the user's manufactured boards.

Rack Mounting The Computer

The Nova 1220 can be mounted in a standard 19 inch rack, so each unit is shipped with rack slides attached and all of the necessary mounting hardware included. Figure I-3 shows how the right side of the rack slide is assembled in a cabinet; the other side uses identical hardware.

Leave at least two inches open at the back for cables and about 36" open at the front for servicing.

The console protrudes 1 3/4 inches out of the front of the rack.

CABLING ASSEMBLIES TOGETHER

Types of Cables

There are five types of cables used on a typical installation; I/O cables, device cables, internal cables, interdevice cables, and adapter cables. The correct cables are supplied with the equipment unless otherwise specified in the price list.

I/O Cables which connect peripheral controllers mounted outside the computer chassis, to the computer IN-OUT bus. The cables form a daisy chain, from controller to controller and finally to the computer chassis, where the first cable must terminate in a female connector compatible with the 100 finger male called P3 shown in Figure I-4. Controllers mounted inside the chassis are connected to the IN-OUT bus through backpanel etching, and therefore do not need an I/O cable.

Device Cables which connect each peripheral controller to the device it is controlling. When such a controller is inserted into the Nova 1220 chassis, an internal cable is run from the appropriate backpanel pins to a male connector, such as P3 of Figure I-4. The device cable must then run between the male paddle board on the 1220 chassis and the device.

Internal Cables are added when the controller is added, whether in the factory or in the field, so each shipment includes a wire list for the internal cable, and the internal cable itself. Figure I-4 shows how the paddle boards are mounted on the chassis.

Interdevice Cables interconnect peripheral devices. Some controllers will drive more than one device of the same kind, such as industry compatible tape controllers. In this case the device cables are daisy chained from device to device in the same way that the I/O cables are chained between controllers. The cables which interconnect the devices are not always the same as the device cable that runs from the controller to the first device, however, so these cables are called "interdevice cables".

Adapter Cables reconcile different cabling schemes. The Nova, Supernova, Nova 1200 and Nova 800 series computers use Cannon connectors instead of paddle boards for their device and I/O cables, and Data General supplies adapters so that peripherals used on these machines can also be used on the new models, or the other way around.

Figure I-4 Sketch of the Nova 1220 Cabling Schemes

① ②

(3)

(5) (6)

Signals from the backpanel pins are connected to edge connectors called P3-P12, which are mounted parallel to the backpanel. The fingers of P3 are permanently connected to the IN-OUT Bus signals according to Table I-2 via etched tracks on the backpanel PC board. The fingers of P4 are permanently connected to pins of slot 9 according to Table I-3. P5, P6 and P7 are all part of a three plug 60 finger paddle board which is permanently connected, but used only when the paper tape reader, the paper tape punch or the EAI options are installed in slot 3. P8-P12, 100 finger paddle boards which accept 48 signal wires and two ground wires, can be mounted on standoffs next to P4 or P5, P6, P7 and wire wrapped to backpanel pins as they are needed. The Teletypewriter cable is run from its backpanel pins (marked TTY) of slot 3, through a cable clamp to the teletypewriter. AIR INLET TELETYPEWRITER CABLE (SLOT 3) CABLE ITEM DESCRIPTION TIE P4 BACKPANEL SLOT 9 2 P5 PAPER TAPE READER OPTION 4011B P6 EIA OPTION 4023 STRAIN RELIEF 4 P7 PAPER TAPE PUNCH OPTION 4012A 5 P8 CLAMP 6 P9 (8) 7 PIO (9) 8 PII 9 PI2 DG-00002 10 P3 IN-OUT BUS POB CUSTOMER CONSOLE 11 12 POA CONSOLE 13 P2 TELETYPEWRITER INTERFACE CONNECTOR

14 TELETYPEWRITER CABLE CLAMP

15 1030B CABLE

Table I-2
P3 Interconnections for Nova 1220

Р3	P3	
LETTER SIDE	NUMBER SIDE	SIGNAL NAME
		GND PWR ON (+5V) MSKO INTA DATIB DATIA DS3 DATOC CLR STRT CLR STRT DATO B DATO A DCHA DS4 DS5 DS2 DS1 IORST DS0 DCHP OUT INTP OUT INTP OUT INTP OUT INTR DCHO DCHMI INTR DCHO DCHR COV FLO RQENB DATA1
y z AA AB — — — — — — — — — — — — — — — — — — —		DATA13 DATA1 DATA15 DATA3 DATA10 DATA2 DATA6 GND

Table I-3
P4 Interconnections for Nova 1220

	BACKPANEL					
NUMBER SIDE	LETTER SIDE	SLOT-SIDE-PIN No.				
	A THRU AF GND					
1		——— GND				
2		9 A 92				
3		9 A 91				
4		9 A 78				
5 — — —		——— 9 A 77				
6		9 A 76				
7		9 A 75				
8		9 A 73				
9		9 A 71				
10 — — —		——— 9 A 69				
11		9 A 67				
12		9 A 65				
13		9 A 63				
14		9 A 61				
15 — — —		9 A 59				
16		9 A 57 9 A 47				
17		9 A 47 9 A 49				
18 19		1				
20 — — —		9 A 79 				
20 — — — 21		9 A 84				
22		9 A 83				
23		9 A 86				
24		9 A 85				
25 — — —		——— 9 A 88				
26		9 A 87				
27		9 A 89				
28		9 A 90				
29		9 B 6				
30	L — — — — — — —	——— 9 B 11				
31		9 B 13				
32		9 B 15				
33		9 B 19				
34		9 B 23				
35 — — —		9 B 25 9 B 27				
36 37		9 B 27 9 B 31				
38		9 B 34				
39		9 B 36				
40		+9 B 38				
41		9 B 40				
42		9 B 48				
43		9 B 49				
44		9 B 51				
45	 	├─── 9 B 52				
46		9 B 53				
47		9 B 54				
48		9 B 67				
49	1	9 B 69				
50 —— —	 	— RESERVED				

Data General Corporation (DGC) has prepared this manual for use by DGC personnel and customers as a guide to the proper installation, operation, and maintenance of DGC equipment and software. The drawings and specifications contained herein are the property of DGC and shall neither be reproduced in whole or in part without DGC's prior written approval nor be implied to grant any license to make, use, or sell equipment manufactured in accordance herewith.

Cabling The System

Turn all systems off, do not plug in any power cords, then:

- 1. install all internal cables not factory installed, following the instructions in the appropriate controller's manual.
- 2. install all device cables, remembering not to exceed the maximum length in each case. Be careful to protect each cable from wear and tear.
- 3. install the teletypewriter cable as shown in Figure I-4.

- 4. measure the line voltage of each service outlet, and check that it is correct for the computer.
- 5. measure the voltage between the ac return line and the frame ground at each outlet.

 THIS MUST BE ZERO
- 6. plug the power cord of each device into its service outlet.

REFERENCES:

Nova 1220 Rack Installation Print D-010-000014-01.

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SECTION N

MAINTAINING THE COMPUTER

INTRODUCTION

The Data General Corporation supports its equipment with a large field service organization, customer training programs and technical documentation. This section summarizes these services and includes tips on preventive maintenance, recommended tools and trouble shooting.

FIELD SERVICE ORGANIZATION

Field Service Programs

Data General's Field Service Organization currently offers its users a choice of three maintenance services. These services are subject to change without notice.

- 1. On Call Service Contract under which DGC will repair equipment at the installation when DGC is notified of a problem by the user. DGC also provides preventive maintenance on a regular schedule under this contract. Parts, labor and travel are included in the monthly payment schedule which is determined by the type and amount of equipment to be serviced and the distance between the installation and the nearest DGC service center.
- 2. Factory Service Contract under which DGC will:
 - (1) repair equipment when it is returned to the DGC factory in Southboro, Mass. The user assumes full responsibility for freight and insurance charges to and from the plant. Parts and labor are included in the monthly payment schedule.
 - (2) repair equipment at the installation when notified of a problem by the user. Parts are included in the monthly maintenance schedule, labor is charged at reduced rates and travel is charged at the prevailing standard rates.
- 3. Hourly Service under which parts, labor and travel are charged as needed at prevailing rates. No contract is signed for this service.

Field Service will also generate on request a complete spare parts list for any installation, and rent or sell replacement and loaner boards.

General Terms and Conditions (Subject to change without notice).

- 1. Equipment which is not under a DGC service contract or normal warranty is subject to an inspection by DGC Field Service before it is eligible for a service contract. All costs for this inspection are borne by the user.
- 2. The user must bear all maintenance costs incurred as a result of unauthorized changes to DGC equipment. These costs will be charged as Hourly Service, regardless of the type of service contract existing between DGC and the user.
- 3. No additional service charge will be added for new (add-on) equipment until the warranty period of that equipment has expired.
- 4. All services are offered between 9 a.m. and 5 p.m. Monday through Friday excluding DGC holidays.
- 5. The minimum contract period is 6 months.
- 6. Field Service price schedules are available on request from Data General Field Service, Southboro, Mass. 01772, Telephone 617-485-9100.

TRAINING ORGANIZATION

Data General's Training Organization currently offers its users four types of training courses. These courses are subject to change without notice.

Mainframe Maintenance Course. This course covers the logical structure of the central processor, memory, operator's console and power supply. Students must have experience with digital logic, integrated circuits and computer principles.

Fundamentals of Mini-Computer Programming.
This course covers number systems, logic, flow charts and computer architecture. Students should have an aptitude for mathematics.

Basic Programming. This course covers Data General's assembly language utility software including loaders, editors, debuggers and assemblers. Students should have experience in programming.

Advanced Programming. This course covers Data General's Operating Systems, DOS, RTOS and SOS. Students must have experience in programming.

Courses are scheduled regularly in the training department at Southboro, Mass., and occasionally in field offices. Special courses can be arranged.

For more information call or write

Training Department
Data General Corporation
Southboro, Mass. 01772

Tel. 617-485-9100

PREVENTIVE MAINTENANCE

Periodically carry out the checks listed in Table, N-1, and remember the following points:

- 1. It is very poor practice to use the equipment as a counter top, particularly for liquids like coffee or soft drinks.
- 2. Always check the line voltage before plugging an expensive piece of equipment into an unknown socket. (see Section I).
- 3. Be careful not to get metal filings into the equipment; for example never let the equipment room be cleaned with steel wool.
- 4. Never clean the equipment with a vacuum cleaner that has a metal (conducting) nozzle.
- 5. Always be aware that too much heat, moisture or contaminants can do much to harm the equipment (see Section I).
- 6. Be very careful how cables are routed; they should never be strained, cramped or crushed (underfoot).

Table N-1

Preventive Maintenance Check List						
Item	Check					
Mechanical Connections	that all screws are tight and that all mechanical assem- blies are secure.					
	2. that all crimped lugs are secure and properly inserted onto their mating connectors.					
Wiring and Cables	 all wiring and cables for breaks, cuts, frayed leads, or missing lugs. 					
	2. wire wraps for broken or missing pins.					
	3. that no wires or cables are strained or cramped.					
	4. that cables do not interfere with doors, and that they do not chafe when doors are opened and closed.					
Air Filters	all air filters for cleanliness and for normal air movement through cabinets.					
Modules and Components	1. that all modules are properly seated. Look for areas of discoloration on all exposed surfaces.					
	2. all exposed capacitors for signs of discoloration, leakage, or corrosion.					
	3. power supply capacitors for bulges.					
Indicators and Switches	all indicators and switches for tightness; check for cracks, discoloration, or other visual defects.					
Fans	for broken fan blades.					
Diagnostics	Run all diagnostics periodically					

Table N-2

Recommended Maintenance Tool Kit							
ITEM	QTY	DESCRIPTION	MFG. & PART No.				
1	1	6" combination slip joint pliers	Utica # 5-6				
2	2	5 1/2" needle nose pliers	Utica # 654-5 1/2				
3	1	4" needle nose pliers	Utica # 23-4				
4	1	5" diagonal wire cutters	Utica # 44-5				
5	1	4" diagonal wire cutters	Utica # 347-4 CFJS				
6	1	5" ignition pliers	Utica # 51 7- 5				
7	1	Screwdriver kit including handle, 3/16", 1/4", 5/16" slotted #1, #2 phillips blades, each 4" long	Xcelite # 99 PV-6				
8	1	3/32 slotter screwdriver with 2" blade	Xcelite # R3322				
9	1	1/8" #0 phillips screwdriver	Xcelite # P12S				
10	1	Magnetic pick up tool	Bonney # K26				
11	1	3/32 through 3/8, 10 pc nut driver set	Xcelite # PS120				
12	1	Xacto knife					
13	1	6" adjustable wrench	Utica # 91-6				
14	1	Ignition wrench	Bonney # N24R				
15	1	Set of 25 feeler gauges with 3" blades	Bonney # K53				
16	1	Set of 15 hex keys	Bonney # N6R				
17	1	Slotter 5" screw starter	Bonney # 5527				
18	1	Phillips 6 1/4" screw starter	Bonney # 556				
19	1	5" adjustable wire strippers	Utica # 110-5				
20	1	Set of 4 cut needle files	Hunter # F228A				
21	1	4 1/2" electrical tweezers	Hunter # B3M3				
22	1	flash light					
23	1	Can Quick Freez (circuit cooler)					

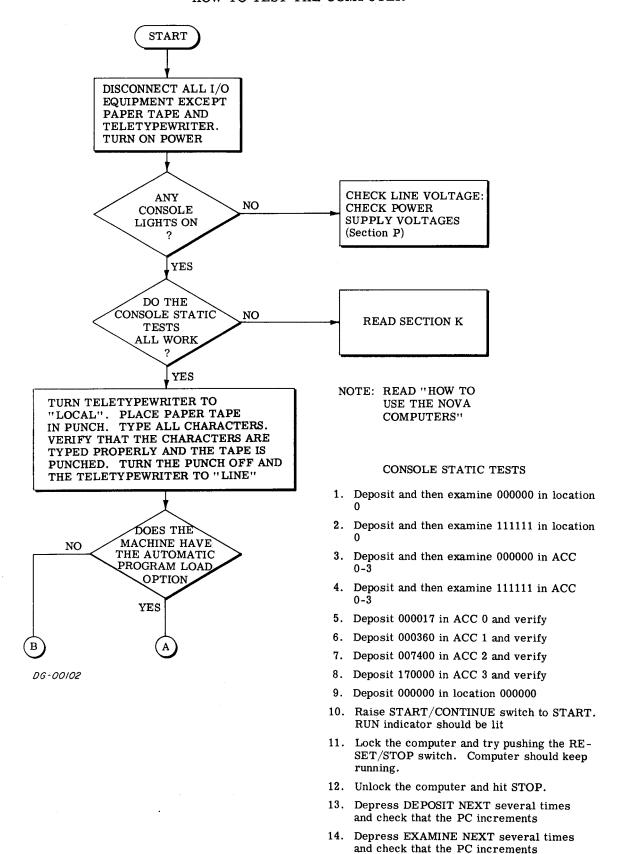
Table N-2 (Continued)

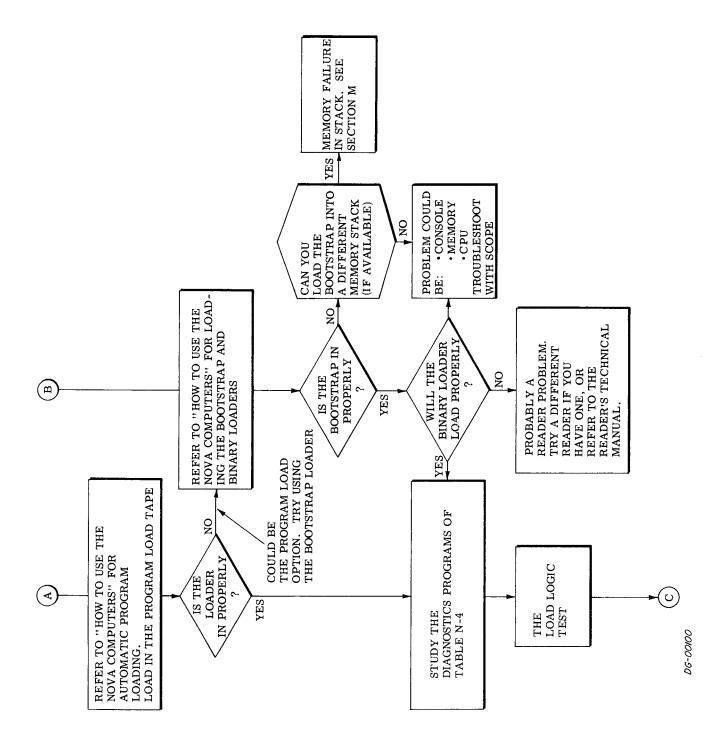
Recommended Maintenance Tool Kit								
ITEM	QTY	DESCRIPTION	MFG & PART No.					
24	1	Can degreaser (flux remover)						
25	2	16P I/C test clip						
26	1	23 1/2 watt soldering iron with iron plated chisel tip	Ungar					
27	1	47~1/2 watt soldering iron element						
28	1	11b, 60/40 resin core solder	Kester					
29	3	Spools of solder wick						
30	2	Acid brushes	Acid brushes					
31	1	Vacuum solder removal tool						
32	1	Multimeter	Simpson # 260					
33	1	Tool carrying case						
34	1	Oscilloscope	Tektronics # 453					
35	1	Current probes	Tektronics # P60-22					

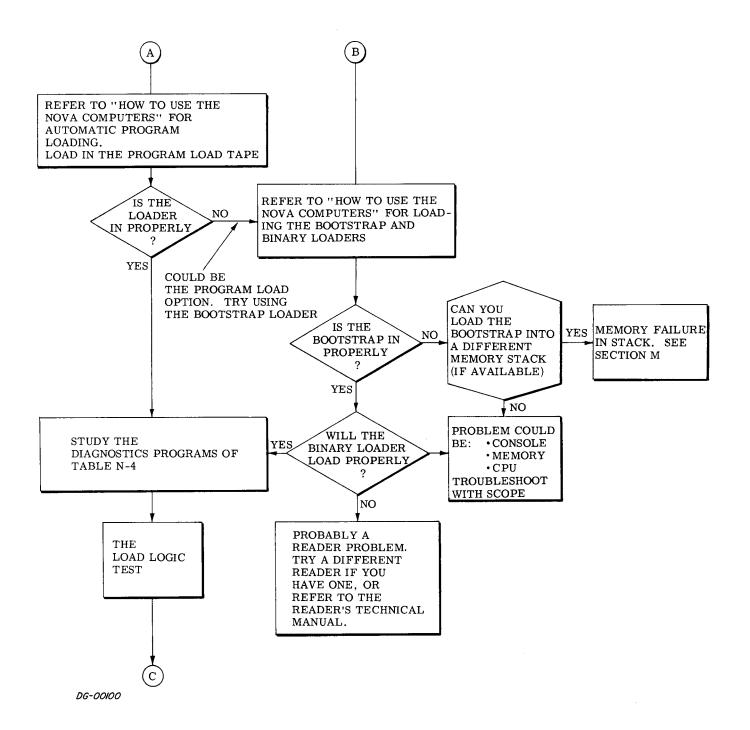
Table N-3

	The Nova 1220 Diagnostics							
Diagnostic	Part No.	Binary Tape No.	Description					
Address Test	097-000007	095-000005	checks memory address selection logic					
Checkerboard III	097-000014	095-000031	tests memory sense amplifiers and inhibit logic					
Nova 1220 Logic Test	097-000017	095-000036	tests CPU logic other than I/O					
Nova 1220 Instruction Timer	097-000019	095-000038	tests CPU clock logic and outputs time-to-complete for each instruction					
Exerciser	097-000004	095-000012	tests CPU logic, teletypewriter, reader, punch and real-time clock;					
Arithmetic Test	097-000018	095-000037	exercises arithmetic and logical instructions in CPU					

HOW TO TEST THE COMPUTER







SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN					DESTINATION				
	СНІР	PIN	DWG	GRID	FUNCTION			DWG	GRID
		5	88-4	B4	ACB12	105	14	88-4	ВЗ
ACB0	105 106	5 5	11	B3	ACB12 ACB13	106	14	11	B2
ACB1	106	5 5	,,	A4	ACB14	107	14	,,	A4
ACB2	107	9		A4	LOAD MBO*	98	6	88-3	A3
1					KEYM SET*	101	9	88-1	B7
ACB3	108	5	,,	A3	ACB15	108	14	88-4	A2
ACB4	105	7	,,	B4	ACB0	105	3	''	B4
ACB4 ACB5	103	7	**	B3	ACB1	106	3	**	B3
ACB5 ACB6	107	7	٠,,	A4	ACB1	107	3	**	A4
ACB0 ACB7	101	7	**	A3	ACB2 ACB3	108	3	,,	A3
ACB7 ACB8	105	9	**	В4	ACB4	105	$\frac{3}{2}$	**	B4
ACB6 ACB9	103	9	,,	B3	ACB5	106	2	,,	B3
ACB10	107	9	**	A4	ACB6	107	$\frac{2}{2}$,,	A4
ACB10 ACB11	108	9	,,	A3	CRY SET	81	13	88-3	C6
ACDII	100			A.O	ACB7	108	$\tilde{2}$	88-4	A3
					SHIFTER	100	_	00 1	1.0
					Logic	114	10	11	A8
ACB12	105	11	11	В4	ACB12 SAVE	69	3	88-1	D5
110012	100	1		-	SHIFTER				
					Logic	109	9	88-4	A8
ACB12*	105	12	17	В3	SHIFTER	125	19	11	A7
ACB13	106	11	11	B2	5111.1.2.1				
ACB13*	106	12	11		SHIFTER	125	2	,,	A7
nobis	100				SHIFTER	125	20	,,	A7
ACB14	107	11	11	A4	· ·-			i I	
ACB14*	107	12	11	A3	SHIFTER	125	1	11	A7
					SHIFTER	125	5	11	A6
	1				SHIFTER	125	18	11	A7
ACB15	108	11	11	A2					
ACB15*	108	12	,,	A2	SHIFTER	125	3	11	A7
ACB12	1			ľ					
SAVE	69	5	88-1	D4	SHIFTER				
					Logic	90	1	88-4	A7
AC CLR	20	9	**	A6	IR(SH)	83	5	88-2	B8
]	Į				SHIFTER	125	7	88-4	A 8
1	I				LOAD AC*	111	3	88-3	D3
ACD0	123	5	88-4	B8	MULT	120	5	88-4	D5
	l				D BUFFR	122	3	''	C8
ACD1	123	7	11	B8	MULT	120	2	''	D5
*Indicates ''Not''	I								

SIGNAL LIST
Table 1 - Nova 1210/1220

	DICIN				DESTINATION					
<u> </u>	RIGIN	T		_		T	1		1	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
	ł				D BUFFER	122	2	88-4	C8	
ACD2	123	9	88-4	B8	${f MULT}$	120	22	71	C5	
	i				D BUFFER	122	15	''	C7	
ACD3	123	11	**	B8	MULT	120	19	''	C5	
4 CD 0 CTT .!!			00.0	i _ , i	D BUFFER	122	14	''	C7	
ACD3 SEL*	50	6	88-2	D4	ACD	123	1	''	B8	
ACD4 SEL*	44	8	**	C4	ACD	123	15	"	B8	
ACD OUT*	45 124	6 5		B3	D MULT(SEL)	121	1	**	C8	
[ACS0]	$124 \\ 124$	7	88-4	B7	S BUFFER	115	3	,,	C7	
[ACS1]	124	9	**	B7	**	115	2	11	C7	
[ACS2]	124	11	**	B6 B6	• •	115 115	15	17	C6	
ACS1 SEL*	49	6,8	88-2	C4	ACS	124	14 1	,,	C6	
ACS2 SEL*	49	[3, 11]	11	B4	ACS	124	15	,,	B7 B7	
ACTG0	54	5	88-1	D8	ACTG1	73	9	88-1	C8	
l nordo	01		00-1	D0	IR(SH) LOGIC	111	2	88-2	B8	
					ACD	123	14	88-4	B8	
					ACS	124	14	11	B7	
ACTG1	54	7	88-1	D8	ACTG0	53	9	88-1	D8	
		Í			IR(SH) LOGIC	111	9	88-2	A8	
					ACD	123		88-4	B8	
	J				ACS	124	13	11	B7	
ADDER0	117	13	88-4	D7	CRY SET*	81	3	88-3	C6	
					ACB (DS)	105	4	88-4	В4	
					ACB8	105	15	11	В4	
					PC LOGIC	118	5,4	11	В6	
	İ				MULT	120	4	11	D5	
ADDER1	117	11	88-4	D7	ACB(DS)	106	4	"	В3	
		i			ACB9	106	15	**	В3	
	j	ļ	1		PC LOGIC		1,2	11	B6	
					MULT	120	1	''	D5	
ADDER2	117	10	88 -4	D7	ACB(DS)	107	4	",	A4	
Ì	Į		I	ŀ	ACB10	107	15	''	B2	
ľ	ļ			Ì	PC LOGIC	118	12,			
	ĺ			ı		100	13	"	A6	
V D D ED 3	117	9	00 4	Dr.	MULT	120	23	".	C5	
ADDER3	117	9	88-4	D7	ACB(DS)	108	4	<u>''</u> [A3	
Indicates ''Not''					ACB11	108	15	''	A2	

SIGNAL LIST
Table 1 - Nova 1210/1220

						jå 114, 1₹,		Lyn Di 190 - 250 -	
OI OI	RIGIN	,	· · · · · · · · · · · · · · · · · · ·		DES	STINA	ΓΙΟΝ		
SIGNAL	СНІР	ΡΙΝ	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
ADD ONE*	88	8	88-2	D2	PC LOGIC MULT ADDER	118 120 117	9, 10 20 7	88 -4 ''	A6 C5 D6
ADDER TEST ALC	58 94	3 6	88-3 88-2	A4 B7	LOOP SET* DISABLE D	104	5	88-3	
ALC*	50	8	88-2	В7	MULT S0 TEST SKIP SET ADD ONE* AND E SET S2	46 47 86 44 65 74 91	10 1 5 2 5 1	88 -2 " 88 -3 88 -2 "	C3 D8 D3 B7 C7 C3
ALC·SKIP AND AND ENAB*	83 65 64	10 6	88 -3 88 -2 88 -2	D8 B7 B7	ALC S BUFFER (SH) LOAD CRY* CRY ENAP S1 ADDER IO DCDR AND PACK	94 115 97 91 91 117 62 65 89	5 13 13 2 5 8 13 4 2	88-3 88-2 88-4 88-1 88-2 88-3	C6 C3
CARRY (F/F) CARRY* (F/F)	76 76	8	88-3	C5	CRY ENAB CON IND (A15, P49) CRY ENAB	77 6 77	5 3	88-3 89-1 88-3	C8 C7
CLK FLOP *Indicates ''Not''	20	5	88-1	A6	MA LOAD* CPU CLK MEM CLK LOAD AC*	56 72 73 93	10 2, 12 3 5	88-1 '' '' 88-3	D3 A7 A7 D3

0	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР		DWG	GRII
CLK FLOP* [CLR*] CLR CLR ION* CLR SKIP*	20 63 7 63 99	6 5 2 11 8	88-1 88-3	A7 A4 A4 B4 B3	CLK FLOP CLR (IO CLR PLS) ION SKIP LOAD MBO*	20 7 (A50) 84 79 98	1 4	88-1 90-1 88-2 88-3	A7 A4 C7 B5 B3
[CON0*](S11) [CON1*](S12)	6 6	4 2	89-1 89-1	C8 C7	MEM0* (CON IND) MEM1*	(B71) 7 (B70)	(391) 9 [P41]	89-1	C8 C8 C7
[CON2*](S13) [CON3*](S14)	6 6	8 12	89-1 89-1	C7 C7	(CON IND) MEM2* (CON IND)	7 (B47) 7	13 (P13 3	†† †† ††	C7 C7 C7
[CON4*](S14)	3	8	89-1	C6	MEM3* (CON IND) MEM4* (CON IND)	(B68) 7 (B28) 8	(P43) 1 (P37) 13	11	C7 C7 C6 C6
[CON5*](S16) [CON6*](S17)	3 3	10 6	89-1 89-1	C6 C6	MEM5* (CON IND) MEM6*	(B26) 8 (B22)	(P36) 3 (P10	11 11	C6 C6 C6
[CON7*](S18)	3	4 2	89-1 89-1	C5 C5	(CON IND) MEM7* (CON IND)	8 (B24) 9	1 (P42) 13	11 11	C6 C5 C5
[CON9*](S20)	3	12	89-1	C5	(CON IND)	(A55) 9 (A53) 9	3	** ** **	C5 C5 C5 C5
[CON10*](S21) [CON11*](S22)		8 10	89-1 89-1	C4 C4	MEM10* (CON IND)	(A45) 10 (A51)	P32) 13	†† ††	C4 C4 C4
[CON12*](S23)	4	12	89-1	C3	(CON IND) MEM12* (CON IND)	10 (A36) (10	3 P5) 1	'' ''	C4 C3 C3
[CON13*](S24) *Indicates '' Not''	4	6	89-1	C3	. , .	(A35) 11	~	**	C3 C3

SIGNAL LIST
Table 1 - Nova 1210/1220

OI.	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
[CON14*](S25)	4	4	89-1	C3	MEM14*	(B76)	(P3)	89-1	C3
[CON15*](S26)	4	2	89-1	C2	(CON IND) MEM15*	11 (B18)	' 1	**	C3 C2
CON DATA*	4	8	88-1	A2	(CON IND)	12 (A28)	13 (P46	77	C2
CON INST* [CON INST]	36 5	8 8	88 -1 89 -1		[CON0*](S11) [CON1*](S12) [CON2*](S13) [CON2*](S14) [CON3*](S14) [CON5*](S16) [CON5*](S16) [CON6*](S17) [CON7*](S18) [CON9*](S20) [CON10*] (S21) [CON11*] (S22) [CON12*] (S23) [CON13*] (S24) [CON14*] (S25) [CON15*] (S26) [CON INST] MEM0* MEM1* MEM2* MEM3* MEM4* MEM5* MEM6*	6 6 6 6 3 3 3 3 3 4 4 4 4 4 (A22) 5 1 1 2 2 2	3 1 9 13 9 11 5 3 1 13 5 3 1 12 9 2 4 10 12 12 2	** ** ** ** ** ** ** ** ** ** ** ** **	C8 C7 C7 C6 C6 C6 C5 C5 C4 C4 C3 C3 C2 A8 C8 C7 C7 C7 C6
'*Indicates ''Not''					MEM7*	2	4	**	C5

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN	_			DES	STINA	LION	l	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
CON RQ*	5	6	89-1	C8					
	A27)	(P21)		KEY SEEN	3	4	88-1	B8
CONT+ISTP+ MSTP*	(4 20)		89-1	D2	KEY ENAB*	3	2	88-1	В8
CPU CLK	(A20) 72	6,8	88-1		MB LOAD	14	4	11 00 – T	C2
Crochk	'~	, ,	00 1	1.0	IR4-IR7	28	6	88 -2	A6
	1			1	MBC	32	6	11	A4
					MBC	33	6	11	A5
					MBO	37	6	88-4	C4
					MBO	38	6	**	C3
					MBO	39 40	6 6	11	D3 D4
					MBO	40	6	88-1	C8
	Ī				LOAD PC*	57	10	88-3	B3
					MA LOAD*	60	10	88-1	D2
					INPUT	66	13	**	C 5
					PTG	69	6	11	D4
					SKIP	78	13	88-3	В5
					MAJOR	0.5		00 0	ا ہم ا
					STATES	95	6	88-2	D6
					$\begin{array}{c} \text{CARRY } \mathbf{F}/\mathbf{F} \\ \text{Logic} \end{array}$	97	9	88-3	C5
					nogic	102	6	11	D8
	l				LOOP/PACK		ľ		١٠٠
					/EFA [']	103	6	11	D5
					ACB	105	6	88-4	B4
					ACB	106	6	11	B3
					ACB	107	6	11	A4
					ACB END CYCLE	108	6	''	A3
	i i				F/F	113	13	88 - 1	D5
CPU INST	6	11	88 -2	В7	INTA	6	5	"	B5
0_01.01	Ĭ				IORST	6	10	**	A4
		l			(SKIP Logic)	11	2	88-3	В7
					''	11	12	''	B7
					CON DATA*			00.4	
		1			(Reads)	24	4	88-1	A3
*Indicates ''Not''									

SIGNAL LIST

Table 1 - Nova 1210/1220

OF	RIGIN	·			DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
CPU INST*	10	6	88-2	В7	(IO OCDR) HALT* PACK Logic MSKO* CPU INST	64 71 87 4 6	2 2 4 13 12,	88-1 88-2 88-3 88-1	B5 C8 C6 A4	
CRY ENAB	80	11	88-3	C6	CRY SET* CRY ENAB SAVE	81 102	13 4 15	88-2 88-3	B7 C6 D7	
CRY ENAB SAVE	102	9	88-3		SHIFT Logic	90 114	10 13	88-4	A7 A8	
CRY OUT*	117	16	88-4		SERIAL CRY CRY ENAB	54 91	14 1	88-1 88-3	D7 C6	
CRY SET*	81	8	88-3	C5	CRY SET SAVE CARRY F/F	42 76	15 12	88 -1 88 -3	C7 C5	
CRY SET SAVE	42	9	88-1	C7	(SKIP Logic)	77	9	11	B7	
DATA0*	16 17 (B62)	11 1	103-1	С	Termin a tor			88-3	C8	
DATA1*	16 17	8 3	103-1 ''	С	Terminator			88 - 3	C8	
DATA2*	(B65) 14 15	11 1	103-1	С	Terminator			88 - 3	C8	
DATA3*	(B82) 14 15	8	103-1	С	Terminator		:	88 - 3	C8	
DATA4*	(B73) 12 13 (B61)	11 1	103-1	С	Terminator			88 - 3	C8	
*Indicates '' Not''										

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
DATA5*	12	8	103-1	С	Terminator			88-3	C8	
DATA6*	13 (B57) 10 11	3 11 1	103-1	С	Terminator			88-3	C8	
DATA7*	(B95) 10 11 (B55)	8 3	11	С	Terminator			88-3	C8	
DATA8*	(B55) 8 9	11 1	103-1	С	Terminator			88-3	C8	
DATA9*	(B60) 8 9	8 3	103-1	С	Terminator			88-3	В8	
DATA10*	(B63) 6 7	11 1	103-1	С	Terminator			88-3	В8	
DATA11*	(B75) 6 7	8	103-1	C	Terminator			88-3	В8	
DATA12*	(B58) 4 5	11 1	103-1	С	Terminator			88 - 3	В8	
DATA13*	(B59) 4 5	8 3	103-1	С	Terminator			88-3	В8	
DATA14*	(B64) 2 3	11 1	103-1	С	Terminator			88-3	В8	
DATA15*	(B56) 2 3	8	103-1	С	Terminator			88-3	В8	
[DATOA*] DATOA DATOB*	(B66) 25 7 25	6 8 5	88-1 ''	B4 B4	DATOA DATOB MSKO*	7 (A58) 7 4	9 13 12	88-1 90-1 88-1	B4 B4 B4	
DATOB *Indicates ''Not''	7	12	88-1	B4		(A56)		90-1		

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DES	TINAT	ΓΙΟΝ	<u> </u>	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
[DATOC*] DATOC	25 26	4 6	88-1	B4 B4	DATOC	26 (A48)		88-1 90-1	В4
[DATIA*] DATIA	25 5	9 12	11	B4 B4	DATIA CON DATA*	5 24	13 5	88-1	B4 A3
[DATIB*] DATIB	25 5	10 10	**	B4 B4	DATIB INTA	(A44) 5 6	11 4	88-1	B4 A4
[DATIC*] DATIC	25 7	11 6	11	B4 B4	DATIC IORST	(A42) 7 6	5 9	88-1	B4 A4
[D BUFFR0] [D BUFF1] [D BUFFR2]	122 122 122 122	5 7 9	88-4	C8 C8 C8 C8	[D MULT0] [D MULT1] [D MULT2]	(A54) 121 121 121 121	2 5 14 11	88-4	C8 C8 C8 C8
[D BUFFR3]	23	9	88-1	C8	[D MULT3] DCHI DCH LOOP	14	9	88-1	C8 C2
DCHA	69	7	88-1	D4	ENAB ADD ONE* DCHA* DRIVE IO* DCH	15 41 7 13 23	2 2 11 5 15	88-1 88-2 88-1	B3 D4 C2 B3 C6
DCHA* DCHA SET*	7 71	10 8	88-2 88-1	_	[DCHA SET] FETCH	(A60) 67 97	3	90-1 88-1 88-2	C4 D7
[DCHA SET] DCHI	67 14	4 8	88-1 ''	C4 C2	DCHA	69 (B37)	2	88-1 90-1	C4
DCH LOOP ENAB	15	6	88-1	B2	DRIVE IO* OVFLO	13 15	9	88-1 88-1	B3 B2
					DCHO ACTG(LD)	18 75	12, 13 10	88-1	B2 D8
					LOOP SET*	104	10, 13	88-3	C6
*Indicates ''Not''									

					<u> </u>		**		
O	RIGIN				DES	TINA	ΓΙΟΝ	Ι	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
DCHM0*	(B17)		88-1	B3	DCH LOOP				
İ					ENAB		4, 5	88-1	В3
[DOMA0]	1.0		00.1	- DO	[DCHM0]	16	1	• • • • • • • • • • • • • • • • • • • •	B3
[DCHM0] DCHM1*	16 (B21)	2	88-1	B3 B3	DCHI	14	10	"	B2
DCHMI	(D21)		''	ъ	[DCHM1]	14 16	12 3	**	B2 B3
İ					LOOP SET*	34	12	88-3	C6
[DCHM1]	16	4	88-1	В3	OVFLO	15	10	88-1	B2
DCHO	18	8	","	B2	0,120	(B33)	10	90-1	22
DCHR*	(B35)		**	C5	DCHR PEND	13	2	88-1	C5
DCHR PEND	13	3	**	C5	DCHA SET*	71	10	**	C5
	i				LOOP SET*	104	9	88-3	D6
DEFER	95	7	88 -2	D6	DEFER				
					AGAIN	76	4	88-2	C7
					ADD ONE*	90	4	"	D4
					DEFER* LOOP SET*	94 104	11 6	88-3	D6
DEFER*	94	10	88-2	D6	(CON IND)	(A12)		88-3 89-1	D6 C2
DELER	51	10	00-2	Do	S0	48	1	88-2	C2 C4
					ADDER	10	*	00-2	
					TEST	58	12	88-3	A6
					ADDER				
					TEST	59	10	11	A6
					FETCH +				1
	[_			DEFER	75	2	88-2	C7
DEFER AGAIN*	76	5	88-2	C7	D SET	74	9	**	C7
(D ₊ E SET) + TS3	36	11	,,	D5	DOID DEVE	,		00 1	<u></u>
120	36	11	''	פע	DCHR PEND (RUN LOGIC)	13 24	$\begin{vmatrix} 1 \\ 13 \end{vmatrix}$	88-1	C5 B7
]			,		PC IN*	24 35	13	88-2	D5
D+E SET*	96	11	88-2	D7	(D ₊ E SET) ₊	00	1	00-2	100
	- 1		I	-	$\frac{(S+L)SL1)^{+}}{TS3}$	36	13	88-2	D5
		j			(RUN LOGIC)	43	13	88-1	B7
	j	- 1			FETCH				
	j				LOGIC	97	5	88-2	C7
1	- 1	ı							
*Indicates ''Not''	- 1	j							
mulcates Not	I	ı							
<u> </u>	L	1							

SIGNAL LIST
Table 1 - Nova 1210/1220

		•							
OI	RIGIN					TINAT			_
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION			DWG	GRID
Disable D Mult DIV* [D MULT0] [D MULT1] [D MULT2] [D MULT3]	53 (A91) 121 121 121 121	3 4 7 12 9	88-4 ''	B2 C5 C7 C7 C7	D Mult (Enab) Carry F/F ADDER " " "	121 76 117 117 117 117	15 10 19 21 23 2	88-4 88-3 88-4	C8 C5 D7 D7 D7 D7
DRIVE IO*	12	8	88-1	В2	READ IO* [DRIVE IO]	(B88) 12 18	4,5 1	90-1 88-1 103-1	B2 C8
[DRIVE IO]	18	2	103-1	C8	[Drive IO· Select]	26	9, 10, 12	103-1	C8
[DRIVE IO· Select]	26	8	103-1	C8	DATA0* DATA1* DATA2* DATA3* DATA4* DATA5* DATA6* DATA7* DATA8* DATA9* DATA10* DATA11* DATA12* DATA13* DATA13* DATA15*	16 16 14 14 12 12 10 10 8 8 6 6 4 4 2 2	12 10 12 10 12 10 12 10 12 10 12 10 12 10 12 10 12 10 12 10 10 10 10 10 10 10 10 10 10 10 10 10	11 11 11 11 11 11 11 11 11 11 11 11 11	000000000000000
*Indicates ''Not''									

SIGNAL LIST

Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
DS0* DS1* DS2* DS3* DS4* DS5*	8 8 8 22 8	8 10 12 8 4 2	88-1	C4 C4 C4 C4 C4 C4		(A72) (A68) (A66) (A46) (A62) (A64)		90-1		
D SET DSZ·E·TS0*	74 52	8	88-2 88-2	C6 B4	DEFER E SET D+E SET* S0	95 96 96 92	2 2 13 1	88-2	C6 C6 D7 C3	
EFA	103	11	88-3	D5	MBC(SH) MBC(SH) ACD4 SEL* ACD OUT* Disable D Mult S0 S0 D SET JSR• EFA	32 33 44 45 46 47 47 74 93	13 13 9 10 4 3 4 4	88-2	A5 A4 C5 B3 B3 C3 B3 C7 C8	
EFA*	103	12	88-3	D5	EFA·PTG1 ACD4 SEL* ACD3 SEL*	34 44 50	5 1 3	** **	A3 C5 C5	
EFA·PTG1	34	6	88-2	A2	MBC (DS) S Mult (SEL)	32 116	4 1	'' 88-4	A4 C7	
End Cycle (F/F)	113	1	88-1	D5	ACTG End Cycle(F/F) LOAD CRY* (LD) Test Skip (LD) Loop/ Pack Shifter Logic """	53 113 97 102 103 109 114	10, 12 2 12 10 10 13 1	88-1 88-3 88-4	C8 C5 C5 D8 D5 A8 A8	
*Indicates ''Not''										

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	T		DWG	GRID
End Cycle*(F/F)	113	6	88-1	C5	Shifter Logic PTG0·TS0	114	9	88-4 88-1	A8
E SET	96	3	88-2	C6	Logic EXEC D+ E SET*	112 95 96	15 12	88-2	A6 D6 D7
EXEC	95	9	88-2	D6	EXEC* (INST DCDR)	73 92	11 9	",	D6 B5
EXEC*	73	10	11	D6	(CON IND) (INST DCDR)			89-1 88-2	C1 B5
EXT LOAD*	(A47) (B49)			A3 A8	LOAD AC* Shifter (Enab)	111 125	4	88-3 88-4	D3 A8
EXT Select*	(B80)				SELECT	35	9,	103-1	
FETCH*	95 94	5 12	88 -2 88 -2	D6	MB LOAD LOAD IR LOAD PC* FETCH·TSO* ALC* ION FETCH* CLR SKIP* (CON IND)	13 34 61 64 50 85 94 100 (A13)	13 9 10 9 1 13 4	88-1 88-2 88-3 88-2 "" "" 88-3	C3 A7 B4 D5 B8 C6 D6 B4 C2
FEICH"	94	12	00-2	Do	FETCH+ DEFER ADD ONE*	45 75 89	1, 13 1 1	88-2	B4 C7 D3
Fetch+Defer	75	3	88-2	C7	IR0+SKP E SET	50 74	1 13	"	B6 C7
FETCH·TS0*	64	8	88-2	D4	EFA Mult (SEL)	85 120	12 16	,, 88-4	C5 C5
Force Load IR*	(A85)		88 -2	A8	IR(LD)	12	4	88-2	A8
*Indicates ''Not''									

SIGNAL LIST

Table 1 - Nova 1210/1220

OF	RIGIN				DES	TINAT	TION		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
HALT*	71	6	88-2	C7	MB LOAD (RUN LOGIC) DCHA	14 62 71	2 3 9	88-1	C2 B7 C5
INH0	34	9	103-1	В	MEM0* DATA0*	16 16	1 13	103-1	C C
INH0* INH1	34 34	8 5	103-1	B B	(INHB0) (Q15) MEM1* DATA1*	68 16 16	12 5 9	103-2 103-1	7 C C
INH1* INH2	34 32	6 5	103-1	B B	(INHB1) (Q16) MEM2* DATA2*	68 14 14	2 1 13	103-2 103-1 ''	7 C C
INH2* INH3	32 32	6 9	103-1	B B	(INHB2) (Q13) MEM3* DATA3*	64 14 14	2 5 9	103-2 103-1 ''	7 C C
INH3* INH4	32 31	8 9	103-1	B B	INHB3) (Q14) MEM4* DATA4*	64 12 12	12 1 13	103-2 103-1 ''	7 C C
INH4* INH5	31 31	8 5	** **	B B	(INHB4) (Q11) MEM5* DATA5*	58 12 12	12 5 9	103-2 103-1	7 C C
INH5* INH6	31 28	6 5	103-1	B B	(INHB5) (Q12) MEM6* DATA6*	58 10 10	2 1 13	103-2 103-1	7 C C
INH6* INH7	28 28	6 9	103-1	B B	(INHB6) (Q9) MEM7* DATA7*	55 10 10	2 5 9	103-2 103-1	7 C C
INH7* INH8	28 27	8 9	103-1	B B	(INHB7) (Q10) MEM8* DATA8*	55 8 8	12 1 13	103-2 103-1	7 C C
INH8* INH9	27 27	8 5	103-1	B B	(INHB8) (Q7) MEM9* DATA9*	48 8 8	12 5 9	103-2 103-1	4 C C
INH9* INH10	27 24	6 5	103-1	B B	(INHB9) (Q8) MEM10* DATA10*	48 6 6	2 1 13	103-2 103-1	4 C C
INH10*	24	6	103-1	В	(INHB10)(Q5)	45	2	103-2	4
*Indicates ''Not''				L				1	

SIGNAL LIST
Table 1 - Nova 1210/1220

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OF OF	RIGIN	_			DES	STINA	LION	Į	,
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
INH GATE B	26	6	103-1	D2	(INHB8) (Q7)	48	13	103-2	4
					(INHB9) (Q8)	48	1	''	4
				l I	(INHB10) (Q5)	45	1	''	4
					(INHB11) (Q6)	45 39	13	''	4
					(INHB12) (Q3) (INHB13) (Q4)	39	13 1	, '' 3 11	4
					(INHB13) (Q4) (INHB14) (Q1)	37	<u>, .</u> 1 1	,,	4
					(INHB14) (Q1) (INHB15) (Q2)	37	13	**	4
INHIBIT	13	8	88-1	C2	(11(11210) (Q2)	(B30)	10	103-1	$\overline{D3}$
					INH GATE A, B	,	9	103-1	D3
				•	WRITE MEM	41	2	77	D3
INHIBIT									i i
SELECT*	(B85)		103-1	D8	SELECT	35	5	103-1	D8
INPUT*(F/F)	66	8	88-1	B5	DRIVE IO*	12	10	88-1	В3
					(IO INST	م ا		11	
]					DCDR)	25	15	11	B4 C3
[INTA*]	6	6	88-1	A4	MB LOAD INTA	112 5	$\frac{1,9}{9}$	71	A4
INTA	5	8	11	A4	INIA	(A40)		90-1	Ач
	(B29)	Ĭ			PI SET	75	12	88-2	C7
INH TRANS*	` 56	6	88-1	B2		(B45)		90-1	
		ı			INH TRANS.	Ì			1
1	ŀ	ı			SEL]	36	2,5,		
							4	103-1	C8
INH TRANS.	2.0		100.4	G0					
SEL]	36	6	103-1	C8	MEM0*	16	2	103-1	C
	- 1				MEM1* MEM2*	16 14	4 2	,,	CC
	ı	ł		ı	MEM3*	14	4	,,	Č
ļ	I				MEM4*	12	2	**	č
l i	ł	ı	1	ı	MEM5*	12	4	11	Č
į į	- 1	ı	1		MEM6*	10	2	11	С
			I	- 1	MEM7*	10	4	11	С
	- 1			ļ	MEM8*	8	2	11	C
	į	ı	l	l	MEM9*	8	4	**	C
]	i		l		MEM10*	6	2	11	C
	j	ļ		1	MEM11* MEM12*	6 4	$\frac{4}{2}$	77	C C
*Indicates ''Not''					W1 62 W1 1 7	4	4		Š

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	T		DWG	GRID	
IO·E	42	5	88-1	C8	MEM13* MEM14* MEM15* IO·E* (IO Inst DCDR) (IO DCDR) HALT*	62 71	4 2 4 3 4 2 1	103-1 '' 88-1 '' 88-2	C C C7 D5 A5 C8	
IO· E* [IO(F+D*] IO(F+D)	94 51 27	4 12 6	88-1 88-2	C7 B6 B5	LOOP SET* (Pack Logic) MA LOAD* IO(F+D) INPUT F/F Logic IO·E	86 89 60 27 9	9 4 13 5 12 3	88 - 3 88 - 3 88 - 1 88 - 2 88 - 1 88 - 1	C7 C5 D2 B6 C5 C8	
ION	82	6	"	C7	(SKIP Logic)	11	13	88-3	В7	
ION*	84	6	88-2	C7	ION* (CON IND) ION (ION LOGIC)	84 (A16) 82 85	5 (P26 5 5	88-2) 89-1 88-2	C7 D2 C7	
[IO PLS*] IO PLS IORST IO SKIP* IO SKIP	63 26 10 25 26 28	4 4 8 12 2 5	88-1 "' "' 88-1 88-2	A7 A4 A4 B4 B4 A6	IO PLS IO SKIP SKIP INC* (Skip Logic) (RUN LOGIC)	26 (A74) (A70) 26 87 59 43	3 1 1 5	88-1 90-1 90-1 88-1 '' 88-3 88-1	C7 A4 B4 B8 B6 B7	
IR5·IR6 IR0+SKIP	65 50	3 12	88 -2 88 -2	B8 B6	ACD OUT* SH/SWP DCDR " PC ENAB* (Pack Logic) AND ENAB* HALT* ALC* (SH/SWP DCDR)	45 50 51 53 92 64 71 50	3 13 1 4,5 4 12 4 11	88-2 88-2 88-3 88-3 88-2 	B3 B6 B6 B4 C6 B8 D8 B8	
*Indicates ''Not''										

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Table 1 - Nova 1210/1220

OF	RIGIN	·			DESTINATION					
SIGNAL	CHI P	PIN	DWG	GRID	FUNCTION			DWG	GRID	
ISTP* (ISZ+DSZ)E	(A17) 84	(P24 8	89-1 88-3	B8 D6	(RUN LOGIC) CRY SET*	24 81	9 9, 10	88 - 1 88 - 3	В7 С6	
(ISZ+DSZ)E*	52	9	88-2	В4	LOOP SET* (INST DCDR) (ISZ+DSZ)E Test Skip Set	104 52 84 86	2 1 13	88-2 88-3	D6 B5 D6 D8	
ISZ·E·TS0*	52	5	88-2	В4	ADD ONE*	89	9	88-2	D3	
(JMP+JSE) (F+D)	48	11	**	B5	PC ENAB* JSR·EFA*	61 93	3 2	88-3 88-2	B4 C7	
JSR.EFA	92	11	88 -3	C3	SHIFT ACB WAS JSR	100 103	1 3	88-3	C3 D5	
$\mathtt{JSR} \cdot \mathtt{EFA}^*$	93	12	88-2	C7	JSR·EFA (Pack Logic)	92 99	$\frac{1}{2}$	• • •	C3 C5	
KEY	23	5	88-1	C6	KEY* LOAD IR	6 34	1 10	88 -1 88 -2	C7 A7	
KEY*	6	3	88-1	C6	CON INST* (RUN LOGIC) KEYM SET* Disable D Mult LOAD PC* KEY·LOOP (DS) ADD ONE* INH TRANS* MA LOAD* (Pack Logic) LOOP SET* CLR SKIP*	36 43 55 46 61 4 23 44 56 56 70 84 99	9 9 5 1 5 2 4 5 4 9 13 10	88-1 88-2 88-3 88-1 88-2 88-1 88-3	A2 B7 B6 B3 B4 C6 C6 D3 B2 D3 C6 C6 B3	
KEY ENAB*	3	3	88-1	В8	PRESET*	3 6	$\frac{12}{2}$	88 - 1	B7 C7	
KEY·LOOP	4	3	88-1	C6	CON DATA* ACD OUT* LOAD MBO*	4 45 98	10 2 13	88-2 88-3	A2 A3 B3	
*Indicates ''Not''										

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Table 1 - Nova 1210/1220

OF	RIGIN				DESTINATION				
SIGNAL	CHI P	₽IN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
KEYM	23	11 12	88 -1 88 -1	C6	CON DATA* (RUN LOGIC) ADD ONE*	24 43 41	3 2 1	88-1 88-2	A3 B7 D4
KEYM* KEYM∙PL	23 41	8	88-1	C5	KEYM SET* KEYM·PL·TSO* JSR·EFA LOAD MBO*	55 57 93 98	3 2 9 5	88-1 88-3 ''	B6 C4 C4 A3
KEYM·PL· TS0*	57	3	88-3	C3	INH TRANS* LOAD PC*	56 57	5 4	88-1 88-3	B2 B3
KEYM SET*	55	6	88-1	В6	[KEY M SET] FETCH	22 97	1 2	88-1 88-2	B6 D7
[KEYM SET] KEY SEEN*	22	2	88-1	B6	KEYM	23	14	88-1	A6
(F / F)	2	6	**	В8	(RUN LOGIC) (MR) (MR)	21 54 102	1 1 1	'' '' 88 –3	B6 D8 D8
KEY SEEN (F/F)	2	5	88-1	В8	KEY ENAB* (SH)	3 23	1 13	88-1	D8 C6
LDA·E* LOAD AC*	52 93	10 6	88 -2 88 -3	B4 D2	(Pack Logic)	99 (A77)	1	88-3 90-1	D5
	100	11	88-3	C3	ACD ACS SHIFT ACB	123 124 100	3 3 2	88 -4 '' 88 -3	B8 B7 C3
LOAD ACB	100	11	88-3	Co	ACB(LD) ACB(LD) ACB(LD)	105 107 108	10 10 10	88-4	B4 B4 B4
LOAD CRY*	97	8	88 -3	C5	CARRY (Pack Logic)	76 99	11 5	88-3	C5 C5
LOAD IR	34	3	88-2	A6	IR(LD) IR(LD) Logic MBC(LD) MBC(LD) [STUTTER]	(A73) 28 8 32 33 54	10 5 10 10	90 -1 88 -2 '' '' 88 -1	A6 A8 A4 A5 D7
*Indicates ''Not''		l					Ĺ		

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
LOAD MBO*	98	8	88-3	A2	MBO(SH)	37	13	88-4	C4	
				li	MBO(SH)	38	13	**	C4	
		i			MBO(SH)	39	13	**	C4	
TOAD DOX	E 17	0	88-3	4.9	MBO(SH)	40	13 12	11	C4 A6	
LOAD PC* LOOP	57 103	8	88-3	A2 D5	PC MB LOAD	119 13	12	88-1	C3	
LOOP	103	' '		DJ	LOOP*	$\frac{13}{22}$	5	88-3	D5	
					S0	47	9	88-2	C3	
					(IO Inst DCDR)	64	5	88-1	B5	
				l	$PTG2 \cdot \overline{LOOP}$	70	4	''	D5	
LOOP*	22	6	88-3	D5	PC IN*	35	5	88-2	D5	
					CON INST*	36	10	88-1	A2	
					MA LOAD*	56	13	••	D3	
LOOP SET	83	2	88-3	D5	(TS3/TS0)	65	9	11	C5	
					PTG-5	70	10	11	D5	
		ľ			LOOP	103	2	88-3	D5	
LOOP SET*	104	8	88-3	D5	DCHA SET*	71	12	88-1	C5	
					LOOP SET	83	1	88-3	D5	
MA1	33	15	103-1	C7	[SARD1](Jumper)	35	4	103-1	D8	
MA1*	33	14	11	C7	[SARD1] ''	35	4	''	D8	
MA2	33	10	**	C7	SARD2	35	1	,,	D8	
MA2*	33	11	**	C7	SARD2 ''	35	1	11	D8	
MA3	33	9	11	C7	SARD2 1 ''	35	2	"	D8	
MA3*	33	8	**	C7	SARD3 ''	35	2	11	D8	
MA4	29	16	11	C7	MA4B*	67	3	103-4	D8	
MA4*	29	1	**	C7						
MA4B*	67	4	103-4	D8	MA4B	67	11	''	D8	
					Y ADDR DCDR	52	5, 4	''	7	
					**	66	5, 4	,, ,,	7	
MA4B	67	10	103-4	D8	**	54	5, 4	,,	7	
2545		1 =	102 1	GC	. 17	62	5, 4	''	[[
MA5	29 29	15 14	103-1	C6	MA5B	67	5	103-4	C8	
MA5* MA5B	67.	6	103-4	C6 C8	MA5B*	67	9	103-4	C8	
MAGD	01	υ	100-4	Co	MAD	O i	J			
*Indicates ''Not''										
murcares not							<u> </u>	L	L	

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN			_	DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRII	
					Y ADDR DCDR	54		103-4	7	
					**	62	7	11	7	
					11	52	7	7.7	7	
				G0	"	66	7	11	7	
MA5B*	67	8	103-4	C8	Y ADDR DCDR	54	1	103-4	7	
					**	62 52	1 1	**	7	
			ŀ		••	66	1	**	7	
MA6	29	10	103-1	C5	MA6B*	67	1	11	В8	
MA6*	29	11	100-1	C5	WHOD		_			
MA6B*	67	$\hat{2}^{1}$	103-4	B8	MA6B	67	13	103-4	B8	
VIAUD	"	-	100 1		Y ADDR DCDR	62	6	**	7	
					11	66	6	11	7	
MA6B	67	12	103-4	B8	7.7	54	6	"	7	
					17	52	6	**	7	
MA7	29	9	103-1	C5	MA7B*	44	11	**	A8	
MA7*	29	8	**	C5				Į.		
MA7B*	44	10	103-4	A8	MA7B	44	3	103-4	A8	
					Y ADDR DCDR		5,4		A	
					11	50	5,4		A A	
MA7B	44	4	103-4	A 8	11	57	5, 4		A	
				C4	11	47	5, 4	103-4	A8	
MA8	25	16	103-1	C4 C4	MA8B*	44	9	103-4	Ao	
MA8*	25 44	1 8	103-4	A8	MA8B	44	5	103-4	A8	
MA8B*	44	Ö	103-4	Ao	Y ADDR DCDR		7	100-1	A	
				ł	1 ADDIT DCDIT	50	7	,,	A	
					11	57	7	**	Α	
			ŀ		11	47	7	",	Α	
MA8B	44	6	103-4	A8	11	60	1	11	Α	
WAOD	11		1.00 2		11	50	1	"	Α	
			l		11	57	1	11	Α	
				•	**	47	1	"	Α	
MA9	25	15	103-1	C4	MA9B*	44	13	''	A8	
MA9*	25	14	11	C4					i	
*Indicates ''Not''										

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
MA9B*	44	12	103-4	A8	MA9B Y ADDR DCDR	44 60 57	1 6 6	103-4	A8 A A	
мА9В	44	2	103-4	A8	11 11	50 47	6 6	†† ††	A A	
MA10 MA10*	25 25	10 11	103-1	C4 C4	MA10B*	71	3	11	D8	
MA10B*	71	4	103-3	D8	MA10B X ADDR DCDR	71 73 77	$ \begin{array}{c} 11 \\ 5, 4 \\ 5, 4 \end{array} $		D8 7 7	
MA10B	71	10	103-3	D8	11	72 76	5, 4 $5, 4$		7 7	
MA11 MA11* MA11B	25 25 71	9 8 6	103-1 '' 103-3	C4 C4 C8	MA11B MA11B* X ADDR DCDR	71 71 72 76	5 9 7 7	103-3	C8 C8 7	
MA11B*	71	8	103-3	C8	** ** ** **	73 77 72 76 73	7 7 1 1	*† *** *** ***	7 7 7 7	
MA12 MA12* MA12B*	22 22 71	16 1 2	103-1 '' 103-3	C3 C3 B8	MA12B* MA12B	77 71 71	1 1 13	103-3 103-3	7 B8 B8	
MA12B	71	12	,,	B8	X ADDR DCDR	76 77 72 73	6 6 6	11 11 11	7 7 7	
MA13 MA13* MA13B*	22 22 80	15 14 10	103-1	C3 C3 A8	MA13B* MA13B X ADDR DCDR	80 80 79	11 3 5,4		A8 A8 A	
MA13B	80	4	103-3	A 8	Y ADDR DCDR	74 78 75	5, 4 5, 4 5, 4	11	A A A	
*Indicates ''Not''						, ,				

SIGNAL LIST

Table 1 - Nova 1210/1220

0)	RIGIN	·			DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
MA14 MA14*	22 22	10 11	103-1	C2 C2	MA14B*	80	9	103-3	A8
MA14B*	80	8	103-3	A8	MA14B X ADDR DCDR	80 79	5 7	103-3	A8 A
					11 11	74 78	7 7	11 11	A A
MA14B	80	6	103-3	A8	11	75 79	7 1	11	A A
					11	74 78	1 1	"	A A
MA15	22	9	103-1	C2	'' MA15B*	75 84	1 13	11	A A8
MA15* MA15B*	22 80	8 12	'' 103-3	C2 A8	MA15B	80	1	103-3	A8
					X ADDR DCDR	79 78	6 6	''	A A
MA15B	80	2	103-3	A8	11	74 75	6 6	"	A A
MA LOAD*	60	8	88-1	D2	MTG(SH)	(B7) 35	11	90-1 88-1	C7
					[MA LOAD]	30 30	11 9,10 12,	103-1	C8
						30	13	''	C8
[MA LOAD]	30	8	103-1		MA1-3	33 33	13 4	103-1	
					MA4-7	29 29	13 4	"	
					MA8-11	25 25	13 4	11 11	
MBC8*	33	5	88-2	A5	MA12-15 (SKIP LOGIC)	22 ·11	13 9	" 88-3	В7
					MBC8 MBC(DS)	27 33	1 4	88 -2 ''	A5 A5
	j				(SH/SWP DCDR) (IO DCDR)	51 63	3 3	88-1	B6 A4
*Indicates '' Not''					11	63	13	''	A4

SIGNAL LIST
Table 1 - Nova 1210/1220

O:	RIGIN				DESTINATION					
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
MBC8	27	2	88-2	A4	(SKIP LOGIC)	11	5	88 - 3	В7	
MBC9*	32	5	88-2	A4	S0 (SH/SWP DCDR)	47	5 2	88-2	C3	
MBCJ	32	J	00-2	A4	(IO DCDR)	51 63	$\frac{2}{2}$	88-1	B6 A4	
					(IO DODIC)	63	14	"	A4	
				•	MBC9	79	9,			
15000					,		10	88-2	A4	
MBC9	79	8	88 -2	A3	(SKIP LOGIC)	80	1	88-3	В6	
MBC10*	33	9	88-2	A5	MBC10	27	9	88-2	A4	
MBC10	27	8	88-2		CRY ENAB	77	2	88-3	C7	
MBC10	41	0	00-2	A4	CPU INST* DS0*	9	5 9	88-2	B8	
MBC11*	32	9	**	A4	MBC11	8 27	13	88-1 88-2	C4 A3	
MBC11	27	12	11	A3	DS1*	8	11	88-1	C4	
				110	CPU INST*	9	4	88-2	B8	
					CRY ENAB	77	5	88-3	C7	
MBC12*	33	7	88 -2	A5	MBC12	27	11	88-2	A4	
MBC12	27	10	88 -2	A4	DS2*	8	13	88-1	C4	
					CPU INST*	9	2	88-2	D8	
					LOAD CRY*	101	1	88-3	C6	
					S MULT	116	3	88-4	C7	
MBC13*	32	7	88-2	A4	MBC13	27	3	88-2	A3	
MBC13	27	4	**	A3	DS3*	22	9	88-1	C4	
	1				CPU INST*	9	1	88-2	B8	
					(SKIP LOGIC) S MULT	77 116	1 6	88-3 88-4	B7	
MBC14*	33	11	88-2		SWILLI	110	0	00-4	C7	
(NOT USED)	00		00-2							
MBC14	33	12	88-2	A5	DS4*	8	3	88-1	C4	
					CPU INST*	10	1	88-2	B8	
	ı				(SKIP LOGIC)	77	10	88-3	B7	
	1	1			S MULT	116	13	88-4	C6	
MBC15*	32	11	88-2	A4	(SKIP LOGIC)	80	4	88 -3	B6	
MBC15	32	12	**	A3	DS5*	8	1	88-1	C4	
	İ	1			CPU INST*	10	2	88-2	B8	
]	- 1	ŀ			S MULT	116	10	88-4	C6	
*Indicates ''Not''										
mulcates "Not"										

OF	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	T		DWG	GRID
MB CLR* [MB CLEAR]	19 18	6 8	88-1 103-1	D2 B8		(B86) 30	2,4 , 5	103-1 103-1	B8 B8
[MB CLEAR· SEL]	30	6	**	В8	INHO F/F INH1 F/F INH2 F/F INH3 F/F INH4 F/F INH5 F/F INH6 F/F INH7 F/F INH8 F/F INH9 F/F INH10 F/F INH11 F/F INH12 F/F INH13 F/F INH14 F/F INH15 F/F	34 34 32 32 31 31 28 28 27 27 24 24 23 23 21 21	13 1 13 13 13 1 13 13 13 13 13 13 13 13	103-1	B B B B B B B B B B B B B B B B B B B
MB LOAD	14	6	88-1	C2		(B74) 36	9	90-1 103-1	В8
[MB LOAD· SEL]	36	8	103-1	В8	INHO F/F INH1 F/F INH2 F/F INH3 F/F INH4 F/F INH5 F/F INH6 F/F INH7 F/F INH8 F/F INH9 F/F INH10 F/F INH11 F/F INH12 F/F INH13 F/F INH14 F/F	34 34 32 32 31 31 28 27 27 24 24 23 23	11 3 3 11 11 3 3 11 11 3 3 11 11 3	103-1	8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8
*Indicates ''Not''					211111 1 1 / 1				

O	RIGIN	. ,			DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION			DWG	GRID
MDO0*	40	5	88-4	D4	INH15 F/F	21 (B79)	11	103-1	В
MBO0*					[MD0]	17	9	103-1	A7
MBO1*	39	5	88-4	D3	MB1	(B 77) 17	5	103-1	A7
MBO2*	37	5	88-4	C4	(CON IND) (P14)	7 (B44)	11	89-1	D7
					MD2 (CON IND) (P15)	15 7	9 5	103-1 89-1	A7 D7
MBO3*	38	5	88-4	C3	MD3	(B43) 15	5	103-1	A6
					(CON IND) (P38)	8	9	89-1	D7
MBO4*	40	7	88-4	D4	MD4	(B42) 13	9	103-1	A6
MBO5*	39	7	88-4	D3	(CON IND) (P16)	8 (B32)	11	89-1	D6
200		Ì	2		MD5 (CON IND) (P11)	13 [°] 8	5 5	103-1 89-1	A6 D6
MBO6*	37	7	88-4	C4		(B16)		103-1	A5
					MD6 (CON IND) (P35)	11	9	89-1	D6
MBO7*	38	7	88-4	C3	MD7	(B14) 11	5	103-1	A5
MBO8*	40	9	88-4	D4	(CON IND) (P9)	9 (B12)	11	89-1	D5
					MBO12 SAVE* MD8	42 9	2 9	88 <i>-</i> 1 103 <i>-</i> 1	C8 A5
MTDO0*	39	9	88-4	D3	(CON IND) (P18)	9 (B9)	5	89-1	D5
MBO9*	39	9	88-4	ДЗ	MD9	` g	5	103-1	C4
MBO10*	37	9	88-4	C4	(CON IND) (P8)	10	9	89-1	D5
					MD10 (CON IND) (P44)	7 10	9 11	103-1 89-1	C4 D4
MBO11*	38	9	88-4	C3	MD11	(B5) 7	5	103-1	C4
					(CON IND) (P6)	10	5	89-1	D4
*Indicates '' Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN		. "		DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
MBO12*	40	11	88-4	D4		(A39)		100.1		
					MD12	5 11	9	103-1 89-1	A3 D4	
147010	40	12	88-4	D3	(CON IND) (P30) D MULT	121	3	88-4	C8	
MBO12	40	12	00-4	Do	MULT	120	6	11	D6	
					ADDER TEST	57	12	88-3	A4	
MBO13*	39	11	88-4	D2		(A37)		00.9	A 4	
					ADDER TEST	60 5	5 5	88 -3 103 -1	A4 A3	
					MD13 (CON IND) (P4)	11	11		D3	
мво13	39	12	88-4	D2	D MULT	121	6	88-4	C8	
MIDOIS	0.0	12	0,0 1	מע	MULT	120	3	* * * * * * * * * * * * * * * * * * * *	D6	
MBO14*	37	11	88-4	Ç4		(A43)		00.0		
					ADDER TEST	60 3	4 9	88-3 103-1	A4 A3	
				1	MD14 (CON IND) (P12)	11	5	89-1	D3	
MBO14	37	12	88-4	C3	D MULT	121	13		C7	
MBO14	31	12	00-4	Co	MULT	120	21	,,	C6	
MBO15*	38	11	88-4	C2		(A41)	_			
				1	MD15	3	5 1	103-1 89-1	A2 D3	
		10	00.4		(CON IND) (P28) ADDER TEST	11 84	9	88-3	A4	
MBO15	38	12	88-4	C2	D MULT	120	10		C7	
			l .		MULT	121	18		C6	
MBO12 SAVE*	42	7	88-1	C7	S0	48	2	88 -2	C4	
				ł	ADD ONE*	90	5	100.1	D4	
[MD0]	17		103-1		INH0	34 34		103-1 103-1	B7 B7	
MD1	17	6	103-1	В7	INH1 MA1	33	3	103-1	C7	
MD2	15	8	103-1	В7	INH2	32	_	11	В7	
MIDZ	10	ľ	100 1		MA2	33		''	C7	
MD3	15	6	103-1	B6	INH3	32		''	B7	
		_			MA3	33 31		1	C7 B7	
MD4	13	8	103-1	В6	INH4 MA4	29		1 ,,	C7	
					MIVA		ĺ			
*Indicates ''Not''										

SIGNAL LIST
Table 1 - Nova 1210/1220

O)	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRIL	
MD5	13	6	103-1	В6	INH5	31	2	103-1	В6	
				_	MA5	39	3	**	C6	
MD6	11	8	103-1	В5	INH6	28	2	11	B5	
				70.5	MA6	29	6	11	C5 B5	
MD7	11	6	103-1	B5	INH7	28 29	$\frac{12}{7}$	77	C5	
		_	100 1	В5	MA7	29 27	12	**	B5	
MD8	9	8	103-1	БО	INH8 MA8	25	2	**	C5	
14D0	9	6	103-1	В4	INH9	$\frac{23}{27}$	$\frac{2}{2}$	**	B4	
MD9	l ⁹	О	103-1	Dī	MA9	25	3	,,	C4	
MD10	7	8	103-1	В4	INH10	$\frac{24}{24}$	$\frac{\circ}{2}$	**	B4	
MDIU	' ·	0	100-1		MA10	25	6	11	C4	
MD11	7	6	103-1	В4	INH11	24	12	11	В4	
WIDII	'	J	100 1		MA11	25	7	**	C4	
MD12	5	8	103-1	В3	INH12	23	12	11	В3	
MIDIE		Ů			MA12	22	2	11	C3	
MD13	5	6	103-1	В3	INH13	23	2	11	В3	
1122					MA13	22	3	11	C3	
MD14	3	8	103-1	B3	INH14	21	2	**	В3	
					MA14	22	6	11	C3	
MD15	3	6	103-1	B2	INH15	21	12	"	B2	
					MA15	22	7	103-1	C2	
${ t MULTIPLY}/$				1						
DIVIDE	SEL			~ 5		40	ا م	00.0	C	
MD SEL1*	(A87)	_	88-2	•	ACS1 SEL*		6,8	88-2		
MEM0*	16	3	103-1		(CON IND) (D20)	(B71) 7	9	89-1	C	
(ACEX+ACDP)	1	3	89-1	ΑĐ	(CON IND) (P39)	28	3	88-2	A	
		İ			IR0* MBO0*	40	3	88-4	D	
			İ	l	Defer Again	76	2	88-2	C	
					(EFA LOGIC)	55	10,	00 2	~	
	l				(EFA LOGIC)	"	13	88-3	C	
MEM1*	16	6	103-1	В7		(B70)	٦	~~ ~		
(ACDP)	10	6	89-1		(CON IND) (P41)	7	13	89-1	C	
(ACDF)		J	00-1		IR1*	29	2	88-2	A	
					MBO1*	39	3	88-4	D	
					(EFA LOGIC)	55	9	88-3	C	
*Indicates ''Not''	i				[`		1			
	1 1								L	

	OTCINI			1	DESTINATION				
	RIGIN		a	anv-					6DID
SIGNAL	CHI P	PIN		GRID	FUNCTION		PIN	DWG	GRID
MEM2* (DP+DPN)	14 2	3 8	103 -1 89-1	B7 A4	(CON IND) (P13) IR2* MBO2* (EFA LOGIC)	(B47) 7 29 37 55	3 15 3 1	89-1 88-2 88-4 88-3	C7 A7 C4 C6
MEM3* (ACEX+ACDP)	14 1	6 11	103-1 89-1	A7	(CON IND) (P43) IR3* MBO3*	(B68) 7 29 38	1 14 3	89-1 88-2 88-4	C7 A7 C3
MEM4* (ACEX+ACDP)	12	3 8	103-1 89-1	A6	(CON IND) (P37) IR4* MBO4*	(B28) 8 29 40	13 3 2	89-1 88-2 88-4	C6 A7 D4
MEM5* (EX+STRT+ ACDP)	12 2	6 11	103-1 89-1		(CON IND) (P36) IR5*	(B26) 8 28 39	3 2 2	89-1 88-2 88-4	C6 A6 D3
MEM6* (EX+EXN+DP+ DPN)	10 2	3	103-1 89-1		MBO5* (CON IND) (P10)	(B22) 8	1	89-1	C6
MEM7*	10	6	103-1		IR6* MBO6*	28 37 (B24)	15 2	88-2 88-4	A6 C4
(EXN+DPN)	2	6	89-1		(CON IND) (P42) IR7* MBO7*	9 28 38	13 14 2	89-1 88-2 88-4	C5 A6 C3
MEM8*	8	3	103-1	В5	(CON IND) (P34) MBC8* MBO8*	(A55) 9 33 40	3 3 15	89-1 88-2 88-4	C5 A5 D4
MEM9*	8	6	103-1	В4	(CON IND) (P7) MBC9* MBO9*	(A53) 9 32 39	1 3 15	89-1 88-2 88-4	C5 A4 C3
*Indicates ''Not''									

O	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
MEM10*	6	3	103-1	В4	(CON IND) (P32) MBC10* MBO10*	(A45) 10 33 37	13 15 15	89-1 88-2 88-4	C4 A5 C4
MEM11*	6	6	103-1	В4	(CON IND) (P31) MBC11* MBO11*	(A51) 10 32 38	3 15 15	89-1 88-2 88-4	C4 A4 C3
MEM12*	4	3	103-1	В3	(CON IND) (P5) MBC12* MBO12*	(A36) 10 33 40	1 2 14	89-1 88-2 88-4	C4 A5 D4
MEM13*	4	6	103-1	В3	(CON IND) (P29) MBC13* MBO13*	(A35) 11 32 39	13 2 14	89-1 88-2 88-4	C3 A4 D2
MEM14*	2	3	103-1	B2	(CON IND) (P3) MBC14* MBO14*	(B76) 11 33 37	3 14 14		C3 A5 C4
MEM15*	2	6	103-1	B2	(CON IND) (P2) MBC15* MBO15*	(B18) 12 32 38	13 14 14	88-2	C3 A4 C2
MEM CLK	73	6	88-1	A6	(MTG) (KEY/RUN/DCH) (ACTG) LOAD AC* S BUFF D BUFF IR4, IR1-3	(B48) 17 23 54 93 115 122 29	6 6 6 4 6 6	90-1 88-1 " 88-3 88-4 " 88-2	D6 C6 D8 D3 C7 C8 A8
мем ок	(A9)		91	B2	RUN LOGIC	62	5	88-1	C7
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[MSKO] MSKO*	4 5	11 4	88-1	B4 A4	MSKO*	5 (A38)	3	88-1 90-1	A4
MSTP MTG0	(A20) 17	(P48 5) 89-1 88-1	D6	(RUN LOGIC) INHIBIT	24 13	1, 10 10	88-1	B7 C2
WITO			00 1	20	DCHI MTG0*	14 16	13 13	** **	C2 D6
					MTG	17	2, 15, 14	**	D6
					READ1* MB CLR*	19 19	1 4	11 11	D2 D2
MTG0* MTG1	16 17	12 7	88 -1 88 -1	D6 D6	MTG(SH)(Logic) RQENB*	16	4 5	11 11	C7 C2
MTG1*	16	10	88-1	D6	MTG1* READ2* MB CLR*	16 19 19	11 10 5	**	D6 D2 D2
					DCHO MTG(SH)(Logic	18 36	10 5	11	B2 D6
MTG3*	17	12	88-1	D6	MTG(DS) STROBE	17 18	$\begin{array}{c} 4 \\ 1, 2, \\ 4 \end{array}$	11	D6 D2
					READ1* READ2*	19 19	2 9	11	D2 D2
MULTO* MULT1*	120 120 120	10 11 13	88-4	CD 5	MBO(DS) MBO(DS) MBO(DS)	40 39 37	4 4	88-4	CD34
MULT2* MULT3*	120	14	tt	**	MBO(DS)	38	4	11	77
OVFLO	15	8	88-1	B2	A CG1 GET *	(B39) 49	10	90-1 88-2	C5
PACK	103	9	88 -3	D5	ACS1 SEL* ACS2 SEL* PACK*	49 49 83	10 12 13	17	B5 D5
PACK*	83	12	88-3	D5	ACS1 SEL* ACS2 SEL*	49 49	4 2 5	88-2 '' 88-3	C5 B5 D3
Indicates ''Not''					LOAD AC	111	J	00-0	<i>D</i> 3

SIGNAL LIST
Table 1 - Nova 1210/1220

	C	RIGIN				DES	STINA'	TION		
ı	SIGNAL	СНІР	DIN	DWG	GRID		T		DWG	GRID
Ì	[PC0]	119	10	88-4	A5	MULTO*	120	10	88-4	CD 5
I	PC1	119	9	",	A5	MULT1*	120	11	00-4	CD 5
1	PC2	119	7	,,	A5	MULT2*	120	13		CD 5
1	PC3	119	6	**	A5	MULT3*	120	14	,,	CD 5
ı	PC ENAB*	61	8	88-3	В3	PC IN*	36	1	88-2	D5
ł		i				LOAD PC*	57	5	88-3	В3
ı]]			E SET	74	2	88-2	C7
ı	PC IN*	36	3	88-2	D4	PC	119	11	88-4	A5
ı						Multiplexer	120	7,8		
I		Ī	1 1			_		9	88-4	C5
ı		i				MULT(ENAB)	120	7,8,		
I		l						9	88-4	C5
I	PI	95	11	88-2	D6	PC IN*	35	4	88-2	D5
ı			[]			ADD ONE*	90	3	11	D4
Į						CLR SKIP*	100	5	88-3	A4
ı	TOT ↓	0.5				Disable D Mult	46	2,3	88-2	В3
ı	PI*	95	12	88-2	D6	IR(SH)	114	2	88-2	A8
ı						IR(DS)	12	13	* *	A8
ı						D SET	74	11	**	C7
ı						ADD ONE*	82	13	**	D3
ł	!			l l		ION*	84	1	""	C7
ı	PI SET	96	6	88 - 2	C6	LOOP SET*	84	12	88-3	D6
ı	11001	90	٥	00-2	Co	PI FETCH	95	14	**	ъ.
ı		i i		ľ		LOAD MBO*	96	9		D6
l	PL*	(A19)	(P23	89-1	В2	KEYM· PL	98 41	2 9	88-3 88-1	A3
ı	~~	(1110)	(1 20	05-1	D2	(RUN Logic)	43	3	00-1	C6 B7
l		i i	ł			Disable D Mult	43 87	9	88-2	
ı	PRESET*	22	10	88-1	В7	MTG(MR)	17.	1	88 - 1	B4 D7
ı			- 4	**		INPUT	66	1	"	B5
ı		I	1	1		PTG(MR)	69	1	••	D5
ı				ľ		SKIP	78	1	88-3	B5
l				Į	i	(Major States)	95	$\hat{1}$	88-2	D7
	PTG0	69	9	88-1	D4	PTG DCDR	68.	2	88-1	D3
		ſ	ı	I		11	68	$1\overline{4}$	11	D_3
ĺ]	ſ		i	PTG	69	14	"	D4
			•	ł	I	PC	119	4	88-4	A5
*	Indicates ''Not''	ļ				PC	119	13	''	A5
*	Indicates ''Not''					PC	119	13	''	A

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN		·		DES	TINAT	ΓΙΟΝ		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
PTG1	69	11	88-1	D4	MB LOAD EFA·PTG1 PTG DCDR	112 34 68 68	13 4 3 13	88-1 88-2 88-1	C3 A3 D3 D3
					End Cycle F/F PC PC MB LOAD	113 119 119 112	3 5 14 10	88-4 " 88-1	D5 A5 A5 C3
PTG1*	69	12	88-1	D4	SO PTG	47 69	2 15	88-2 88-1	C3 D4
PTG2*	68	10	88-1	D4	ADDER Test TS0/TS3 PTG2 PTG2 LOOP	57 65 67 70	13 10 9 5	88-3 88-1	A6 C5 D3 D5
PTG2 PTG5	67 70	8 8	88-1 88-1	D3 D4	INPUT F/F Key/Run/DCH/	66	12	"	В5
					(LD) (LD) TS0/TS F/F Adder Test	23 42 66 78 79	10 10 2 12 4	88-1 '' 88-3	C6 C8 C5 A5
					Major States (LD) LOAD MBO* LOAD MBO*	95 98 98	10 3 4	88-2 88-3 88-3	D7 A3 A3
PTG5 ENAB*	68	6	88-1	D3	INH TRANS* PTG5 Pack Logic SKIP F/F LOAD ACB	56 70 70 79 100	1 9 12 12 12	88-1 88-3	B2 D5 C6 B5 C3
PTG=0·TS0	113	9	88-1	A 5	Adder Test MA LOAD* ADD ONE*	58 60 88	13 12 9 9	88-1 88-2 88-4	A6 D2 D3 A7
PTG= 0 · TS0*	113	8	88-1	A 5	Shifter Logic ADD ONE* Shifter Logic SHIFT ACB	90 88 90 93	4 13 10	88-4 88-2 88-4 88-3	D3 A7 C4
*Indicates ''Not''									

SIGNAL LIST

Table 1 - Nova 1210/1220

	DICINI			DESTINATION					
<u> </u>	RIGIN								
SIGNAL	CHIP	PIN	DWG	GRID	FUNCTION	CHIP		DWG	GRID
PTG= 0 · TS3*	68	4	88-1	D3	PTG=0.TS3	67	13	88-1	D3
İ	į				ADD ONE*	88	5	88-2	D3
PTG=0·TS3	67	12	88-1	D3	INPUT F/F	9	9,	00 1	C5
	1				MTG(LD)	17	10 10	88-1	D7
1					ADD ONE*	88	1, 2		D3
PTG=1.TS0*	68	11	88-1	D3	ADDER Test	80	10	88-3	A6
PIG=1 150	00	11	00-1	Do	SHIFT ACB	93	11	11	C4
PTG=1·TS3*	68	5	88-1	D3	(IO DCDR)	109	5	88-1	A5
$PTG2 \cdot \overline{LOOP}$	70	6	88-1	D4	PTG2+LOOP	73	13	88-1	D4
		ł			LOAD MBO*	98	9	88-3	B3
	_				LOOP SET*		3, 4		D6
PTG2+LOOP	73	12	88-1	D4	LOAD IR	34 79	$\frac{1}{2}$	88-2 88-3	A7 B5
DILL OF ENAD	109	6	88-1	A5	SKIP (F/F) OVFLO	15	12	88-1	B2
PULSE ENAB	109	0	00-1	AJ	IO DCDR	62	1	11	A5
PWR FAIL*	(A5)		91 -1	C2	PWR LOW	86	12	88-3	D8
1 """ """	(110)		-		AC CLR	20	12	88-1	A6
PWR LOW	102	11	88-3	D7	(SKIP Logic)	11	1	88-3	B1
PWR LOG*	102	12	* *	D7	PI SET	75	13	88-2	C7
					PWR LOW	86	13	88-3	D8
READ1*	19	3	88-1	D2	Man C (CII)	(B87) 35	10	103-1 88-1	D6
					MTG(SH) READ 1B	18	13	103-1	D6
	18	12	103-1	D6	MEAD ID	19	5, 4		D6
	10	12	100 1	Do	READ2B	19	12	103-1	D6
READ 1B	19	6	103-1	D5	11	19	10	7,7	
					(X ADDR DCDR)	72	2	103-3	A7
					**	76	2	" "	A7
					""	73	2	'' ''	A7
[**	77 79	2 3	,,	A7
					11	79 74	ა 3	,,	A7 A7
					11	78	3	,,	A7
					11	75	3	,,	A7
*Indicates ''Not''									
					L	L		<u> </u>	

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
READ 2*	19	8	88-1	D2		(B90)		103-1	D6
					READ 2B	18	11	11	D6
	18	10	103-1	D6	11	19	9	11	D6
READ 2B	19	8	103 <i>-</i> 2	D5	(Y ADDR DCDR)	19 54	13 2	103-4	D6 A7
READ 2B	19	٥	103-2	טט	(I ADDR DCDR)	62	2	103-4	A7
					**	52	2	11	A7
					11	66	2	**	A7
					**	60	3	**	A7
l					17	50	3	**	A7
	l				**	57	3	11	A7
					7.7	47	3	11	A7
READ IO*	12	3	88-1	B2	r	(B83)		103-1	A8
	10		100 1		[READ IO]	18	3	11	A8
	18	4	103-1	A 8	[MD0]	17	13	17	A
					MD1 MD2	17 15	2 13	11	A A
					MD3	15	2	11	A
				i i	MD3 MD4	13	13	**	A
					MD5	13	2	11	A
					MD6	11	13	11	Α
1					MD7	11	2	11	Α
					MD8	9	13	11	Α
					MD9	9	2	**	Α
	1				MD10	7	13	17	A
					MD11	7	2	**	A
	l				MD12	5	13	11	A
]					MD13	5 3	2	103-1	A
					MD14 MD15	3	13 2	,,	A A
[READ IO]	18	6	103-1	A8	MIDIO	18	5	11	A8
[READ IO]	10	١	103-1	Ao	[MD0]	17	10	**	A
]					MD1	17	4	**	A
]					MD2	15	10	11	A
]	ı				MD3	15	4	,,	A
	l				MD4	13	10	11	A
	- 1				MD5	13	4	11	Α
*Indicates ''Not''					MD6	11	10	11	A

SIGNAL LIST
Table 1 - Nova 1210/1220

C	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР			GRID
RESET*	22	4	88-1	В7	MD7 MD8 MD9 MD10 MD11 MD12 MD13 MD14 MD15 PRESET* IORST KEY/RUN/DCH (MR) (MR) ION* LOOP/PACK (MR)	11 9 9 7 7 5 5 3 3 10 21 23 42 84	4 10 4 10 4 10 4 10 4 13 13 9	103-1 '' '' '' '' 88-1 '' '' 88-2 88-3	A A A A A A A B7 A4 B8 C6 C8 C7
RESTART* RELOAD Disable*	(B72)		88-1	A8	KEY SEEN F/F Disable D Mult	3 87	5 10 10,	88-1 88-2	B8 B4
RESTART Enable RINH0 RINH1 RINH2 RINH3 RINH4 RINH5 RINH6 RINH7 RINH6 RINH7 RINH8 RINH9 RINH10 RINH11 *Indicates '' Not''	(A32) (A5) (A7) (A9) (A11) (A13) (A15) (A18) (A17) (A19) (A24) (A23) (A21)) 89-1 103-2 ''' ''' '''	B7 7 7 7 7 7 7 7 7 4 4 4 4			12	103-1	В8

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN				DESTINATION				
SIGNAL	CHI P	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
RINH12 RINH13 RINH14 RIN15 RQENB* RST* RUN RUN* S0 S1 S2 [S BUFFR0] [S BUFFR1] [S BUFFR2] [S BUFFR3] SELB* SELD* SELECT	(A28) (A25) (A27) 16 (A30) 23 22 91 91 115 115 115 (A82) (A80) 35	6 (P20 7 12 3 8 11 5 7 9 11 8	103-2 '' '' '' 88-1	4 4 4 C2 B6 C6	RESET* RUN* CPU CLK (CON IND) (A14) KEY SEEN F/F ADDER '' S1 ADDER S MULT '' '' '' SKIP Logic '' STRB A, B, C, D '' READ 1B INH GATE A, B '' (DRIVE IO)	(B41) 21 22		90-1 88-1 " 89-1 88-1 88-4 " " 88-2 88-4 " " " 103-1	B8 C6 A7 D2 B8 D8 C3 D8 C7 C7 C7 C7 C7 B6 B6 D4 D5 D6 D3 C8
*Indicates ''Not'					(DRIVE 10)	20	13		Co

SIGNAL LIST
Table 1 - Nova 1210/1220

	DESTINATION								
	ORIGIN SIGNAL CHIP PIN DWG GRID					T	1	1	GDID
SIGNAL	CMP	FIN	DWG	GRID	 			DWG	GRID B8
1		Í	ì	İ	(INH TRANS*) (MB LOAD)	36 36	1 13	103-1	B8
		l			(MB CLEAR)	30	1	",	B8
SERIAL CRY	54	12	88-1	D7		15	13	88-1	B2
	1				ADD ONE*	88	6	88-2	D3
SET ION*	63	10	**	B8		82	4	11	C7
SHIFT0*	125	13	88-4	A 678		(B94)	1		
					SKIP Logic	110	12	88-3	A6
				ĺ	ACD ACS	$\frac{123}{124}$	4 4	88-4	A 678
SHIFT1*	125	14	88-4	,,	ACS	(B96)	4	,,,	"
	120	* *	00 1	l	SKIP Logic	110	10	88-3	A6
	1				ACD	123	6		A 678
	1				ACS	124	6	**	11
SHIFT2*	125	11	88-4	"		(B93)			
				•	SKIP Logic	110	13	88-3	A6
	1 1			t	ACD	123	10		A 678
SHIFT3*	125	10	88-4	,,	ACS	124	10	**	''
SHITTO	140	10	00-4		SKIP Logic	110	9	88-3	A6
					ACD	123	12	88-4	A 678
					ACS	124	12	11	7,7
	l	l							
SHIFT ACB	100	3	88-3	C2	ACB(SH)	105	13	**	В4
					ACB(SH)	106	13	**	B4
		ľ			ACB(SH)	107	13	17	B4
		ł			ACB(SH)	108	13		B4
SHL*	51	6	88-2	B6	Carry F/F Logic	101	5	88-3	C6.
·	-	Ĭ	~ ·		[SHL]	101	3	11	C6
	1	- 1			SHIFTER(SEL)	125	16	88-4	A8
[SHL]	101	4	88-3	C6	CRY SET*	81	2	88-3	C6
SHR*	51	5	88 -2	В6	Carry F/F Logic	81	6	''	C6
	I	- 1	j		[SHR]	101	5	"	C6
[SHR]	101	6	88-3	C6	SHIFTER (SEL) CRY SET*	125 81	$\frac{17}{1}$	88-4 88-3	A8 C6
ركالادا	101	١	00-0	CO	CRISEL	0.1	T	00-3	0
	1						i		
	1					<u> </u>			

SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN					DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
SIGNAL SKIP SKIP* SKIP INC* +SL0 -SL0 -SL0 +SL1 -SL1 +sl2 -SL2 +SL3 -SL3 +SL4 -SL4 +SL5 -SL5 +SL6 -SL6 +SL7 -SL7 +SL8 -SL8 +SL9 -SL9 +SL10 -SL10 +SL11	CHIP 78 78 42	PIN 5 6 12	DWG 88-3 " 88-1 103-2 "" "" "" "" "" ""	B5 B5	FUNCTION ADD ONE* IR0+SKIP D SET ADD ONE* Test Skip Set PC IN* MA LOAD* PC ENAB* CLR SKIP* SNS0 " SNS1 " SNS2 " SNS3 " SNS4 " SNS5 " SNS6 " SNS6 " SNS7 " SNS7 " SNS8 " SNS9 " SNS10 " SNS11	90 (B69) 50 74 82 86 35 56	2 3 12 4 13 12 4,5	88-2 90-1 88-2 "" 88-3 88-2 88-1 88-3 "" "" "" ""	D4 B6 C7 D3 A8 D5 D3 B4 B6 66 66 66 66 66 66 66 66 66 66 66 66

SIGNAL LIST
Table 1 - Nova 1210/1220

SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN					DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
SNS11 SNS11* SNS12 SNS12* SNS13 SNS13* SNS14	46 45 40 39 40 39 38	12 8 14 8 12 6 14	103-2	3 3 3 3 3 3 3 3	SNS11* INH11 F/F SNS12* INH12 F/F SNS13* INH13 F/F SNS14*	45 24 39 23 39 23 37 21	9 10 9 10 5 4 5	103 - 2 103 - 1 103 - 2 103 - 1 103 - 2 103 - 1 103 - 2 103 - 1	C3 B3 C3 B3 B3 B3 B3 B3
SNS14* SNS15 SNS15*	37 38 37	6 12 8	11	3	INH14 F/F SNS15* INH15 F/F	37 21	9 10	103-1 103-2 103-1	A3 B2
STA·E* STOP* STOP INH*	52 (A31) 82	11 (P45) 8	88 - 2 89 - 1 88 - 1	B5 B5 B6	LOAD MBO* MULT (SEL) STOP SYNC DCHA SET* SKIP INC*	99 120 4 71 87	9 17 4,5 13 2	88-3 88-4 88-3 88-1	D8 C5 C8 D7
STOP SYNC STROBE	102 18	5 6	88-3 88-1	D7 C2	FETCH RUN Logic STRB A, B, C,	97 43 (B20)	4 1 5	88-2 88-1 103-1	B7 D5
STRB A	1	6	103-1	D4	D SNS0* SNS1* SNS2*	1 68 68 64 64	10 4 4 10	103-1	C6 C6 C6 C6
STRB B	1	6	103-1	D4	SNS3* SNS4* SNS5* SNS6* SNS7*	58 58 55 55	10 10 4 4 10	11 11 11	A6 A6 A6 A6
STRB C	1	6	103-1	D4	SNS8* SNS9* SNS10* SNS11*	48 48 45 45	10 4 4 10	11 11 11	C3 C3 C3 C3
STRB D	1	6	103-1	D4	SNS12* SNS13* SNS14* SNS15*	39 39 37 37	10 4 4 10	103-2	A3 A3 A3 A3
*Indicates ''Not''					21,020				

SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN					DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	1		DWG	GRID
[STRT*] STRT [STUTTER] STUTTER* SWP*	63 7 54 73 51	6 4 9 2 4	88-1 '' '' '' 88-2	A4 A4 D7 D7 B6	STRT (IO STRT PLS) STUTTER* CPU CLK LOAD ACB	7 (A52) 73 72 100	3 1 1,13 13	88-1 90-1 88-1 88-1 88-3	A4 D7 A7 C3
TS0	66	5	88-1	C5	PC IN IR(SH) INST DCDR Disable D Mult KEYM·PL·TS0* PC ENAB* FETCH·TS0* PTG DCDR S1 LOOP SET* (D+E SET)+TS3 ACD OUT* ALC* PC ENAB* PC ENAB* IO DCDR Logic	35 114 92 53 57 61 64 68 91 34 36 45 50 61 61 109	3 5 10 1 1 9 10 1 10 13 12 4 10 1 2,4 2	88-2 88-3 88-2 88-1 88-2 88-3 88-2 	D5 B8 B5 B3 C4 B4 D5 D3 C3 C6 D5 B3 B8 B4 B4
TS3 SET TEST* TEST SKIP Test Skip Set WAS JSR WAS JSR* WHOA* + 5 OK *Indicates ''Not''	65 (A92) 102 86 103 48 (B6) (A8)	8 7 3 5 8	88-1 90-1 88-3 '' 88-3 88-2 90-1 91-1	C5 D7 D7 D5 C5 B2	PTG DCDR ACTG(LD) Defer Again (F/F PTG=0·TS0 " CARRY F/F SKIP F/F Logic RUN LOGIC STOP INH* TEST SKIP ACS1 SEL* SHIFTER Logic CPU CLK RESET*	68 75) 76 112 76 59 41 82 102	15 9 3 3 13 13 9 2 10 12 5,9	88-2 88-1 88-3 88-1 88-3 88-2 88-4 90-1 88-1	D3 D8 D7 A6 C5 B6 B6 D7 C5 A8 A7 B8

SIGNAL LIST
Table 1 - Nova 1210/1220

QI.	ORIGIN					DESTINATION			
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
WRITE MEM	41	6	103-1	D2	X DRIVERS Y DRIVERS	72 76 73 77 79 74 78 75 54 62 52 66 60 50	3 3 3 2 2 2 2 3 3 3 2 2 2 2 2 3 3 2 2 2 2	103-3	A7 A7 A7 A7 A7 A7 A7 A7 A7 A7 A7
xrs			103-3 103-3	B2	X DRIVERS " " " X DRIVERS " "	72 76 73 77 75 78 74	11 11 11 11 11 11	103-3	B7 B7 B7 B7 B3 B3
YRS			103-4	B2	" Y DRIVERS " " "	79 54 62 52 66	11 11 11 11	103-4	B3 B7 B7 B7 B7 B3
YWS			103-4	B2	Y DRIVERS	47 57 50 60	11 11 11 11	11	В3 В3

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Intentionally

ABBREVIATIONS

CENTRAL PROCESSOR AND MEMORY

NOVA 1210/1220

		· · · · · · · · · · · · · · · · · · ·	
ABC0 thru ACB15	Accumulator Buffer Register Outputs	DATIA	Data In A (I/O instruction)
ACD	0 thru 15 Destination Accumulator	DATIB	Data In B (I/O instruction)
ACD OUT	Destination Accumulator Out	DATIC	Data In C (I/O instruction)
ACDP	Accumulator Deposit	DATOA	Data Out A (I/O in- struction)
ACD 3 SEL	Destination Accumu- lator Select enable line	DATOB	Data Out B (I/O in-
ACD 4 SEL	Destination Accumu- lator Select enable line	DATOC	struction) Data Out C (I/O in-
AC EX	Accumulator Examine		struction)
ACS	Source Accumulator	DATA0 thru DATA15	I/O Data bus signals, 16 bits wide
ACS 1 SEL	Source Accumulator Select enable line	D BUFFER	Destination (Accumulator) Buffer
ACS 2 SEL	Source Accumulator Select enable line	INTA	Interrupt Acknowledge
ACTG0, ACTG1	Accumulator Timing Generator outputs 0 & 1	INTP IN	Interrupt Priority In (to Device)
ALC	Arithmetic Logic Class (instruction)	INTP OUT	Interrupt Priority Out (from Device)
AND ENAB	AND (instruction) Enable	INTR	Interrupt (Bus Signal from Device)
CLK	Clock	IO (F+D)	IO (instruction) (Fetch or Defer state)
CLR	Clear	IO or I/O	Input/Output
CLR ION	Clear Interrupt On	ION	Interrupt On
CON DATA	Console Data	IO PLS	Input/Output Pulse
CON INST	Console Instruction	IORST	Input/Output Reset
CON RQ	Console Request	IO SKIP	Input/Output Skip
CONT	Continue switch at Console		(instruction)
CPU	Central Processor Unit	IR0 thru IR7	Instruction Register outputs 0 thru 7
CPU CLK	Central Processor Unit Clock	ISTP	Instruction Step (Console switch)
CPU INST	Central Processor Unit Instruction	ISZ	Increment and Skip if Zero(instruction)
CRY ENAB	Carry Enable	JMP	Jump (instruction)
CRY OUT	Carry Out	JSR	Jump to Subroutine
CRY SET	Carry Set		(instruction)

ABBREVIATIONS (Continued)

KEYM	Key Memory (access	STRB A	Strobe A (Memory Stack)			
	cycle)	STRB B	Strobe B (Memory Stack)			
LOAD AC	Load Accumulator	STRB C	Strobe C (Memory Stack)			
LOAD ACB	Load Accumulator Buf- fer (Shifter)	STRB D	Strobe D (Memory Stack)			
LOAD IR	Load Instruction Regis-	STRT	Start (Console switch)			
LOAD IX	ter	SWP	Swap (bytes)			
LOAD MBO	Load Memory Bus Out-	TS0 thru TS3	Time State 0 thru 3			
	puts (CPU Interface Register)	TT	Teletype			
LOAD PC	Load Program Counter	TTI	Teletype In (Teletype Keyboard/Reader Buf-			
MA1 thru MA15	Memory Address Reg-		fer)			
	ister outputs 1 thru 15	TTO	Teletype Out (Teletype			
MA LOAD	Load Memory Address Register		Teleprinter/Punch (Buffer)			
MB CLEAR	Memory Buffer Clear	XRS	X (plane) Read Source (Memory Stack)			
MBC8 thru MBC15	Memory Buffer Computer outputs 8 thru 15	xws	X (plane) Write Source			
MB LOAD	Load Memory Buffer		(Memory Stack)			
	Register	YRS	Y (plane) Read Source (Memory Stack)			
MBO0 thru MBO15	Memory Bus Outputs (CPU Interface Regis- ter) 0 thru 15	YWS	Y (plane) Write Source (Memory Stack)			
MD SEL1	Multiply Divide Select 1	32 VNR	+ 32 Volts, Not			
MD1-MD15	Memory Data 1 thru 15		Regulated			
SET ION	Set Interrupt On	+ VINH	+ (Memory) Inhibit Voltage			
SHIFT ACB	Shift Accumulator Buf- fer	+ V _{Lamp}	+ Lamp Voltage (Con- sole indicators)			
SHL	Shift Left	+ VMEM	+ Voltage Memory			
SHR	Shift Right	+ 5 OK	+ 5 Volt (power)			
SKIP INC	Skip Increment		operating properly			
SL0 thru SL15	Sense Lines (Memory Stack) 0 thru 15					
S MULT	Source Multiplexer					
SNS0 thru SNS15	Sense Amplifier Out- puts 0 thru 15					
S0 thru S2	(Adder function) Select Control Bits 0 thru 2					
STOP INH	(Processor) STOP INHIBIT					